

Foreword



Michael H. Crawford, MD
Consulting Editor

Cardiology Clinics has a long tradition of keeping its readers up-to-date on technological advances in cardiology diagnostics. Recently we have done issues on CT angiography, contrast echocardiography and MRI. This issue focuses on 3D echocardiography. It is guest edited by three of the leaders in the field, Drs. Edward Gill, Roberto Lang and Navin Nanda. Each editor is from a different academic medical center, so this issue is well balanced. The issue starts with articles on the development and technology behind 3D echo, then launches into 14 articles on specific uses. Most of the articles deal with the three major uses of 3D echocardiography, imaging the left ventricle, cardiac valves and congenital heart disease. Finally, there is an article on using 3D echocardiography to guide intracardiac therapy.

3D echocardiography is used in most large academic medical centers now, and its use is spreading as commercially available machines are being bought to replace older models. The

articles in this issue focus on the well-established uses of 3D echo, but there is much more to learn. Other uses that were not discussed because there are little data about them include the assessment of cardiac masses, aneurysms and pseudoaneurysms. Also, we have much more to learn about the utility of three-dimensional color flow imaging. I expect this to be a growing field that competes with 3D reconstruction of MR and CT images of the heart. This issue of *Cardiology Clinics* will get you up to speed in this important area.

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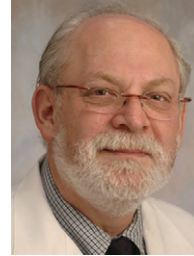
Preface



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Three-dimensional echocardiography (3DE) has transitioned from a research tool to a methodology useful in everyday clinical practice. This transition began, in earnest, in 2002 with the release of a reasonably user-friendly version of a matrix array transducer capable of real-time 3D imaging together with software that allows rapid slicing and quantification of structures. Prior to this time, 3DE had been acquired by using a two-dimensional echocardiography (2DE) transducer, wherein the movement of the transducer was followed in space, or by moving it in a prespecified pattern, acquiring multiple 2DE images with the aid of cardiac and (in some renditions) respiratory gating, and finally assembling the 2D images into a 3D image using advanced computer software and coupled with the spatial tracking information. This approach was formidable and only undertaken by those with a major interest in the research and development of the technology. Previous ultrasound imaging systems had 256 to 512 elements. The current 3D matrix transducer has approximately 3000 imaging elements, coupled with significantly enhanced computer processing power. The major breakthrough in transducer technology was the development of a microbeam former that allowed not only the acquisition of a large volume of information but also electronic steering of the transducer.

Hence the combination of the microbeam former, improved image quality, more efficient management of the images (in terms of digital storage and transfer), improved analysis packages, and reimbursement of the service combine to make 3DE a possibility for routine use in the clinical echocardiography laboratory. Most importantly, critical research has been performed that defines the current use of the technology.

The timing of this issue of the *Cardiology Clinics* is primed by the recent release of a position paper by the American Society of Echocardiography (ASE) and a message from Dr. Michael Picard, the current ASE president. The ASE position paper summarizes the data documenting the usefulness of 3D technology. Dr. Picard encourages the use of 3DE for the following reasons:

1. *Keeping up with the competition.* Currently, CT and MRI already use 3D imaging to their advantage. We as echocardiographers need to increase awareness that this approach is feasible with echocardiography.
2. *Improved assessment of the left ventricle.* There are now many publications showing the superiority of left ventricular volume, mass, and ejection fraction measurement with 3DE compared with 2DE. Volume

and mass are important markers of prognosis in both heart failure and hypertension.

3. *Improved understanding of valve function.* As depicted in the ASE position paper, 3DE allows an “en face” view of the valve for measuring the valve area in mitral stenosis and aortic stenosis. Furthermore, in mitral regurgitation—more specifically, mitral valve prolapse—3DE can precisely define which individual scallop is involved and further delineate other mechanisms of mitral regurgitation. In addition, using 3D color Doppler, the shape and exact size of the vena contracta can be assessed, obviating assumptions made regarding its shape when using 2DE/Doppler. Thus, it provides more accurate quantitative assessment of valva regurgitation severity, unlike the proximal isovelocity surface area (PISA) method, which assumes (mostly incorrectly) the flow acceleration to be hemispherical.
4. *Improved display of congenital heart lesions.* A mainstay of 3DE is its ability to display complex spatial relationships between structures in patients with more advanced forms of congenital heart disease.
5. *Preparing for the future.* It is likely that 3DE will become a common part of all echocardiographic examinations. This will be challenging, because the technology is changing rapidly—on the positive side, it is improving rapidly as well. It is important for us as cardiologists, not just as echocardiographers, to keep up with this technology.
6. *Helping drive the technology forward.* It is our job within this issue of the *Cardiology Clinics* to challenge all cardiologists and sonographers to explore this technology and ask critical questions regarding its use and development. The more people engage from the sidelines and become part of the process, the quicker

the technology will advance and be understood. Clearly improvements are needed, particularly with regard to more advanced transducers with higher frequencies and frame rates and complete Doppler capabilities.

The reader is encouraged to explore Dr. Picard’s entire document, as well as the position paper [1,2].

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Three-Dimensional Echocardiography: An Historical Perspective

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Three-dimensional echocardiography (3DE) has made a dramatic transition from predominantly a research tool to a technology useful in everyday clinical practice. Clearly this transition began in earnest in 2002 with the release of a reasonably user-friendly version of real-time 3DE (RT3DE). Before this time, 3DE had relied on using a two-dimensional echo (2DE) transducer, either tracking that transducer in space, or moving it in a prespecified pattern, acquiring multiple 2DE images with the aid of cardiac, and in some renditions, respiratory gating, and finally assembling the 2D images into a 3D image using advanced computer software and the spatial information obtained from the transducer tracking device. This type of approach was formidable and was undertaken only by those with a major interest in either the commercial or research development of the technology (ie, academic centers and industry). All of that changed with the introduction of a dense array, matrix transducer that is equipped with 3000 elements compared to the conventional 256 or 512 along with enhanced computer processing speed and memory.

Early history

3DE has its roots in the early 1980s in terms of when it actually came to market as a real commercially available product. Therefore, it is interesting to note that work with 3DE actually began in the early 1970s. All early work in 3DE

focused on methods of locating a standard 2D transducer in space, acquiring multiple 2D images, and melding the multiple 2D images into a 3D image. In fact, Dekker and colleagues [1] are credited as the original pioneers of 3DE, performing their first 3DE in approximately 1974. They used a long mechanical arm to locate the position of the transducer in space and allow alignment of multiple 2D images and ultimately generated a 3D image (Fig. 1). Unfortunately, the equipment was impractical for general clinical applicability, and the images were archaic (see Fig. 1). This was followed by the development of the spark-gap technique by Moritz and Shreve [2] in 1976 that located the 2D transducer by sending constant pulsed acoustic signals from a device holding the transducer, called a spark gap to a Cartesian locator grid (Fig. 2). Several other authors published early attempts at 3DE during this time period [3–7]. Other techniques were developed that operated under the assumption that both the patient and the housing of the ultrasound probe remained in a relatively fixed position. The ultrasound probe was held by a device that moved the probe in a specified, preprogrammed fashion within the housing of the mechanical device. Examples were linear, fan-like, and rotational acquisition methods. The rotational method became by far the most popular (Figs. 3–6). In 1977, Raab and colleagues [8] developed an electromagnetic locator that ultimately led to free-hand scanning. Although this technique was quite advanced for 1977, paradoxically, it would not see more than patchy use until the mid 1990s (Fig. 7).

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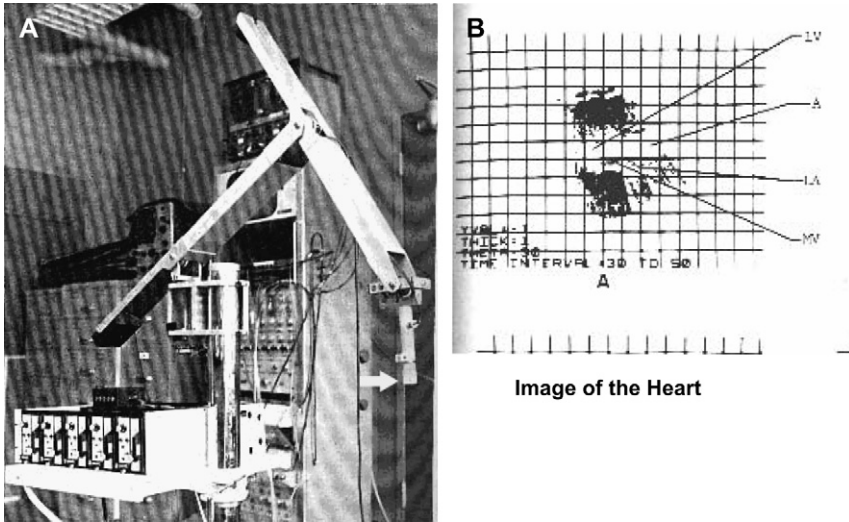


Fig. 1. (A) The mechanical arm. A large external beam device gives spatial data regarding an ultrasound probe to enable 3D reconstruction. The ultrasound probe is depicted by the arrow. (B) The image that resulted from the mechanical arm 3D reconstruction. Note that the image is barely discernible as a cardiac structure.

Rotational scanning and other transducer-prescribed methods

The development of commercially available 3DE equipment began in the early 1990s with the introduction of transesophageal 3DE. TomTec Imaging Systems (Munich, Germany) introduced a special transesophageal transducer that allowed moving a phased-array transducer element parallel within the esophagus. This movement of the transducer was controlled by a stepper motor that was in sync with the patient's ECG and respiratory cycle (Fig. 8).

The first realistic attempts at clinical 3DE began in the mid-1990s, when TomTec Incorporated

developed and began marketing a product called Echo Scan that applied transthoracic 3DE acquisition methods. Mechanical devices were used to advance a standard 2DE transducer over a region of interest. A separate computer workstation monitored the patient's ECG and respiratory signals, and, accordingly, a stepper motor advanced the position of the device and inherently the transducer. Researchers evaluated several different acquisition devices like parallel scan device, fan-like scan motion, and rotational acquisition devices (see Figs. 3–6). After a rather short period of time, mostly rotational type devices achieved the greatest popularity, with others rarely used.

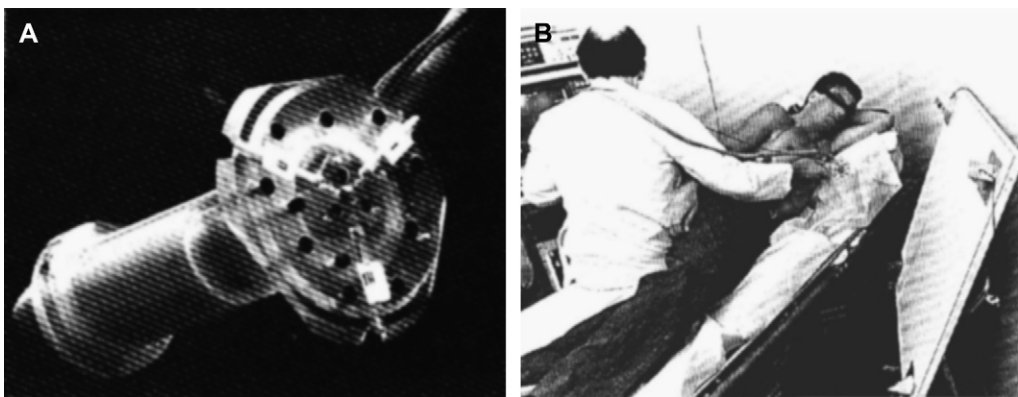


Fig. 2. (A, B) The acoustic locator or spark gap. Ultrasound probe location is tracked by a means similar to radar technology.



Fig. 3. Linear acquisition. Schematics of the sequential ultrasound images obtained by progressive linear, fan-like, and rotational motion of the transducer in a pre-specified fashion. Images then were reconstructed offline.

The rotational device did not track the transducer in space, but rather assumed that (other than rotation) the transducer axis remained in one place throughout the scan. The rotational device was large, and as a result cumbersome; it came to be known, not necessarily in an affectionate way, as the bazooka (see Fig. 6A). This rotational device, as its name implied, rotated the transducer through a 180-degree arc and acquired an image (a complete heart cycle) every 3 to 5 degrees. For such an acquisition to be successful, a sonographer would have to hold the rotational device and the transducer within it as still as possible while the device rotated. Although clinically possible, a scan then required the standard echo machine and transducer, the rotational device, and the workstation. From a practical standpoint, such a three-piece system was not mobile and

largely limited scanning to within the echo laboratory, or in some cases in the operating room; hence portable 3DE examinations became oxymoronic. In actuality, to be successful, this type of 3DE required a very skilled sonographer, a very cooperative patient, an echocardiographer physician or technician skilled with 3D reconstructions, and a little bit of luck. Ultimately, a rotational transducer was developed with the rotational mechanism contained within the transducer and the driving mechanism contained onboard the ultrasound system (see Fig. 6B). Although this apparatus was portable, as it was consolidated into the ultrasound machine, the image quality still was less than desirable except in pediatric patients, where it saw limited application. Although image quality was particularly suboptimal for smaller discrete structure analysis such as valvular structures, even at this time, ventricular volume assessment was useful.

Later, using the technology developed by Raab, free-hand scanning became commercially available from TomTec Imaging Systems and from 3D Echo Tech (Boulder, Colorado), acquired by GE Medical Systems. An electromagnetic transducer locator, an enhanced version of the device originally described by Raab, was used (see Fig. 7). As shown in the figure, a magnet enclosed in a plastic housing was placed in close proximity of the patient. The electromagnet was attached to the ultrasound machine, the transducer, and a separate computer. With freehand scanning, the electromagnet creates a highly sophisticated magnetic field that orients sequentially acquired 2DE images and their imaging planes by tracking the transducer through space as it is

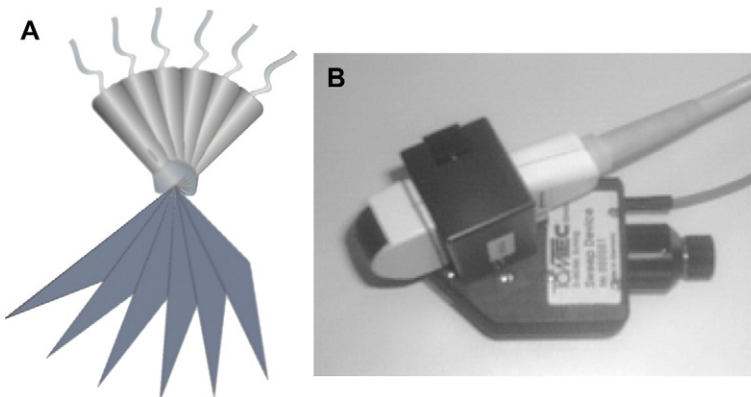


Fig. 4. (A, B) The actual hardware that was used for fanlike acquisition.

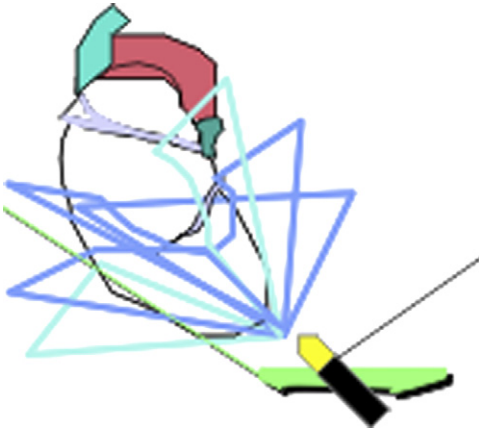


Fig. 5. Transesophageal echo (TEE) probe using rotational acquisition. The TEE probe was positioned in the esophagus in a position to visualize the heart. Then, the TEE probe was pulled back in a prescribed fashion using a stepper motor with ECG and respiratory cycle gating.

moved so by the sonographer. Therefore, at the end of the scan, the collection of images (typically 15 to 60 cardiac cycles, with 10 to 15 frames/cardiac cycle) can be oriented appropriately into a 3D data cube and ultimately rendered into a 3D image by placing each individual image in its appropriate plane relative to the others. This particular technology gained some popularity in the late 1990s and is still today used by some researchers [9]. It arguably was the most likely technology to make it to the clinical arena before the advent of RT3D imaging.

The reason why RT3D imaging took essentially three decades to be developed from the

earliest forms of 3D is related simply to fact that adequate computing power did not exist to support the infrastructure needed for RT3D. In addition, transducer technology was not advanced enough to acquire a volume of data.

Integrated transesophageal echo methodology with rotational transducer

Initially 3D TEE was performed using an external computer and a TEE probe advanced in a parallel mode using a stepper motor (see Fig. 8). Then in a cooperative effort between Hewlett-Packard and TomTec in 1994, a TEE method of 3D acquisition with software onboard the ultrasound machine became commercially available. The multiplane TEE probe, invented by Hewlett-Packard in the early 1990s and sold commercially starting in 1992, provided a ready-made rotational device to couple with technology already used by TomTec in its transthoracic rotational device. That is the multiplane TEE probe had an inherent design for the ultrasound transducer at the tip of the probe to rotate within the TEE probe itself between 0 and 180 degrees (Fig. 9). Hence, all that had to be added was software and hardware onboard the ultrasound system itself that automatically drove the TEE probe through its 0- to 180-degree rotation, typically (although adjustable up or down by the user) through 3-degree increments, and acquired a complete 2D heart cycle. In addition, respiratory and cardiac cycle gating was added to assure uniformity to the 2D images. The result was 61 2D cardiac cycles that then were transferred to an offline PC and reconstructed into a cube of

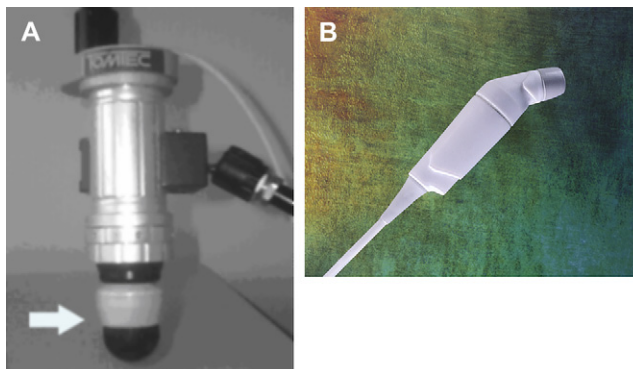


Fig. 6. (A) An early mechanical rotator that housed an external stepper motor that controlled transthoracic echocardiography (TTE) probe rotation. (B) A transducer with rotational capacity within the head of the transducer for transthoracic imaging.

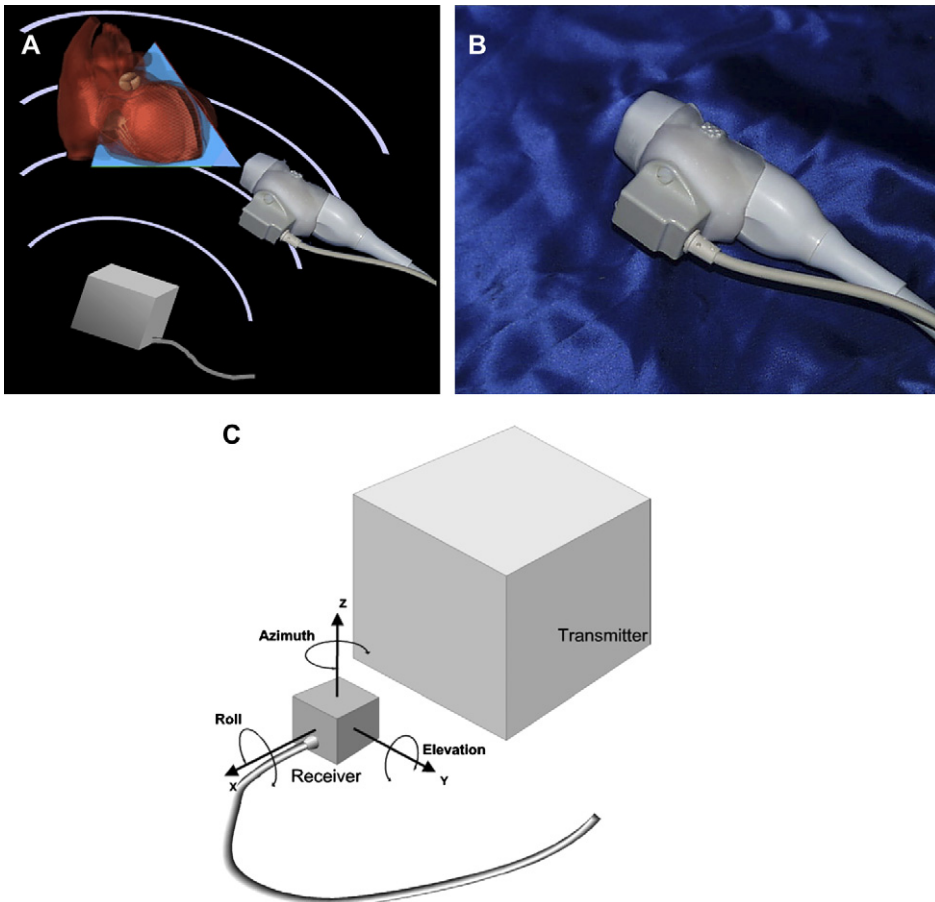


Fig. 7. (A, B) Freehand scanning. A modified ultrasound probe is tracked in 3D space using an electromagnetic field device; images then may be reconstructed off-line to create 3D data sets (C). Schematic of the receiver and transmitting device and the Cartesian coordinate system for tracking the location of the transducer. (Courtesy of TomTec Imaging Systems, Munich, Germany; with permission.)

data and ultimately cropped into a 3D image. This type of 3DE was limited by the fact that it had to be reconstructed after the examination was completed, because the reconstruction process was not on the ultrasound system. It did, however, offer the tremendous advantage of working with high-quality 2D images, because they were obtained by means of TEE. During this time period (1994 to 2000), a solution for most multiplane TEE probes was available from TomTec using an external acquisition computer, but only Hewlett Packard integrated the acquisition software into the ultrasound system itself. In 1992, Nanda performed one of the first 3D reconstructions using a multiplane TEE for acquisition [10]. It is notable that Chen and colleagues [11], at the Thorax center in Rotterdam, Netherlands, had developed

their own apparatus for TEE acquisition, again using TomTec software for offline reconstruction. Finally it is also worth noting that in 2004 Siemens Ultrasound (Mountain View, California), in cooperation with TomTec, began offering a similar system with reconstruction (in addition to acquisition) possible onboard the ultrasound system, a clear advantage. However, it is clear that the advent of real-time 3D echo imaging has made any type of 3D echo that utilizes a reconstructive process obsolete.

Real-time 3D methods

RT3D first was developed by von Ramm at Duke University during the 1990s [10–13]. With RT3D, an entire volume of heart was obtained

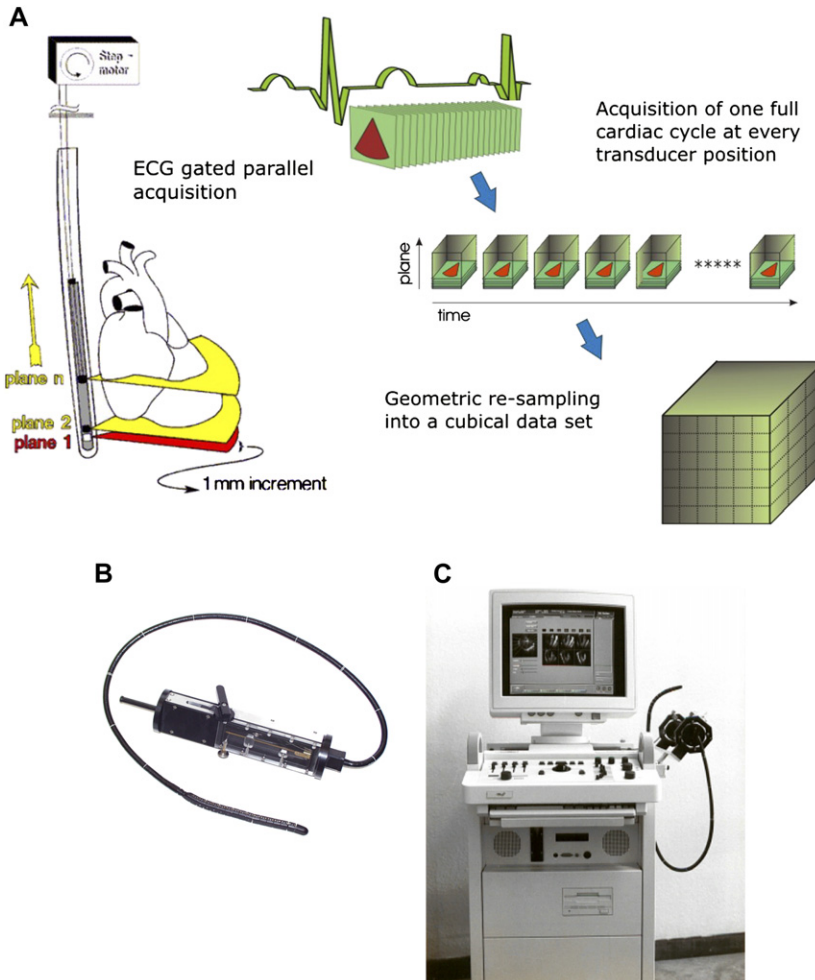


Fig. 8. The parallel acquisition of a 3D image by transesophageal echo (TEE) (A). The TEE probe in schematic and how it was advanced in the esophagus using a stepper motor (B). The actual TEE probe attached to the stepper motor, a device known as the lobster tail (C). The original TomTec Echo CT showing the computer that was used to drive the acquisition and the lobster tail in a carrier with the computer. (Courtesy of TomTec Imaging Systems, Munich, Germany; with permission.)

using one cardiac cycle. This was of course a major transition from the thin slice sector imaging that 2D provided. And although it was a very positive development with the volumetric acquisition, the negative was that the images displayed were in fact 2D images. The 2D images were in fact derived from the 3D data but were displayed as 2D orthogonal planes. This was the major advent of the C scan (Fig. 10). An attempt was made to commercialize this product through the company Volumetrics (Chapel Hill, North Carolina). Although Volumetrics had an imaging system in production and commercially available for a few

years (from 1997 to 2000), the system was large and not particularly versatile for also performing 2D imaging. Additionally, to derive true 3D images, an off-line workstation had to be used (TomTec, Echo-Scan). There were no truly RT3D images. Having said that, Volumetrics did show RT3D rendering at the 2000 American Heart Association meetings, but soon after that, the company folded never to be heard from again.

By the time that Volumetrics had shown its RT3D rendering, a similar, yet much more advanced product was already well into the development stage at Hewlett-Packard. Hewlett-Packard

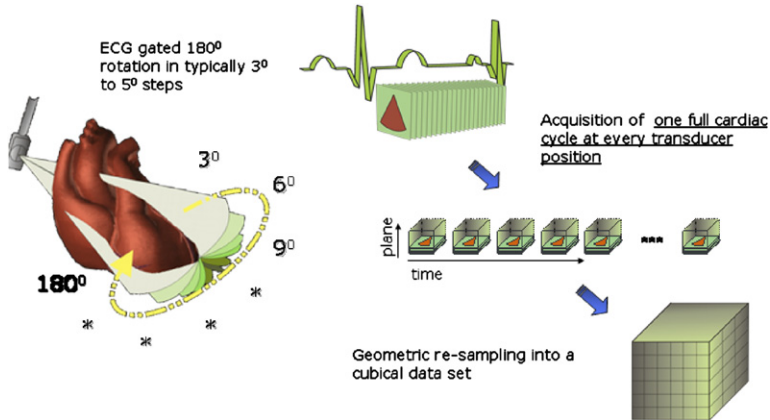


Fig. 9. Schematic of how 3D transesophageal echo (TEE) was acquired. The TEE probe is shown with its range of rotation from 180 degrees. Typically, a 2D image was acquired every 3 degrees. The relationship between the heart and the TEE rotation. (Courtesy of TomTec Imaging Systems, Munich, Germany; with permission.)

began developing RT3DE in roughly 1996. The company had already been a force in the development of 3D TEE using the 2D reconstruction approach and had released that product for general consumption in 1995. By late 1998, Hewlett-Packard had a working prototype for transthoracic RT3D (RT3DE) and began showing it to luminary customers by 1999. A major

development in the history of RT3D came in 1999 when Hewlett-Packard spun off its medical division and some other noncomputer divisions as Agilent Technologies (Andover, Massachusetts). One year later in 2000, this led to the purchase of the medical division of Agilent Technologies, including its medical ultrasound division, the most pertinent division for this discussion, by

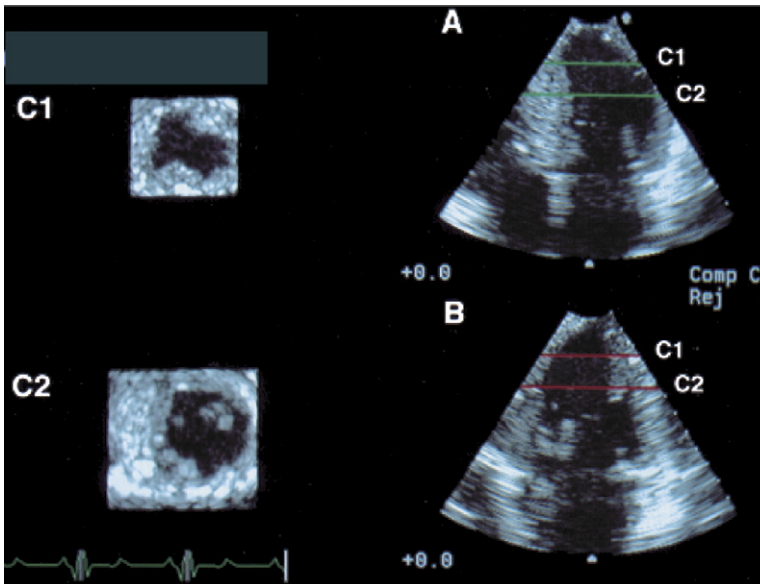


Fig. 10. Real-time 3D echocardiograph C-scan images, Volumetrics, Inc. The images shown are apical view of the heart on right, four chamber on top, and two chamber on the bottom. On the left are short axis or C scans of the LV derived from perpendicular cuts through the apical views on the right. (Courtesy of David Adams, RDCS, Durham, NC.)

Philips Medical Systems. As Philips Medical Systems (Bothell, Washington) had purchased another ultrasound company, Advanced Technology Laboratories (ATL), (Bothell, Washington), in 1998, the plan became for ATL and Agilent to merge their ultrasound knowledge to further develop this 3D technology. Hence, in November 2002, at the time of the American Heart Association meetings, Philips released the first generation of RT3DE. Two years later, at the 2004 American Heart Association meetings, General Electric Health Care (Chalfont St. Giles, United Kingdom) would follow-suit with its introduction of RT3D. At the 2007 American College of Cardiology Annual Scientific Sessions, New Orleans, Louisiana, Toshiba revealed its version of RT3D. Hence, currently, three of the four major ultrasound companies now have RT3D with the fourth, Siemens expected to soon have a version.

The major breakthrough that allowed quality real-time imaging was the development of a microbeam former. This was necessary, because the Matrix transthoracic imaging probe developed by von Ramm and commercialized by Volumetrics was a sparse array transducer (not all of the transducer head was used and connected to individual elements) (Fig. 11). That is because of earlier lack of miniaturization and the fact that only 128 channels can be connected to this array. This limits the beam-forming characteristics and hence image quality. When the entire crystal of the transducer head is sampled or covered with elements, the transducer is a dense array (Fig. 12). The microbeam former is required for this arrangement to provide a communication of all of the approximately 3000 elements to the ultrasound system. Although still only 128 channels are used on the ultrasound system, the 3000 elements are divided into subgroups, and each of the subgroups is attached to one of the 128 channels. This arrangement makes the beam steering very powerful, and this is how the image quality is maximized to result in a high-resolution, RT3D rendered image. More detail regarding the mechanism of operation of this transducer can be found in the article by Salgo elsewhere in this issue.

Since the initial release of RT3DE by Philips Medical Systems in 2002, much research has been performed on this system, and to a lesser degree on other systems. This research is summarized in the remainder of this edition. In November 2006, the second generation of RT3D imaging was

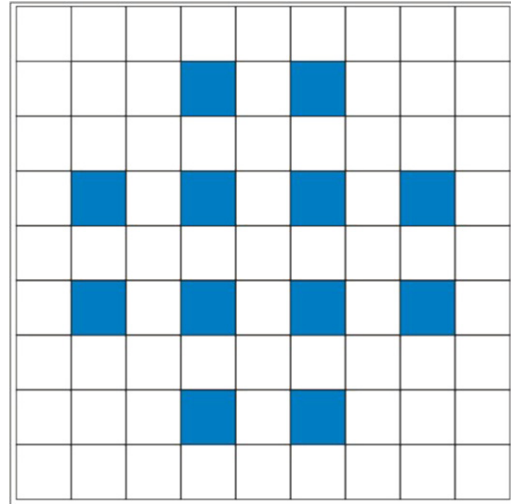


Fig. 11. Sparse array transducer. The diagram depicts the difference between a sparse array shown here and a dense array. Not all of the transducer head is connected to an element. This limits image quality. See discussion in text.

released by Philips Medical Systems, again at the American Heart Association annual meeting. It is anticipated that GE soon will release a significant upgrade to its first generation of RT3D imaging. With these developments, RT3DE has become more commonplace throughout the United States and the world. In fact, technology in 3D has proliferated more throughout Europe and Asia than the United States. Proliferation of the technology continues as improved methods of image management and analysis are developed. In the United States, billing and reimbursement for RT3DE was instituted in 2005 using a general 3D radiology billing code. In January 2006, two new 3D ultrasound billing codes were introduced: RT3DE acquisition and analysis and off-line analysis. With the combination improved image quality, rapid image management and analysis, and reimbursement, it is likely the RT3D imaging will become a routine in most clinical echo laboratories in the near future. At this point, it is clear that the advent of RT3DE has transitioned 3DE from a relatively impractical research tool to a very user-friendly clinically applicable diagnostic test. Finally, all of the vendors for 3DE have developed practical software for quantification. This is important from the standpoint of moving 3DE from a qualitative pretty picture technology

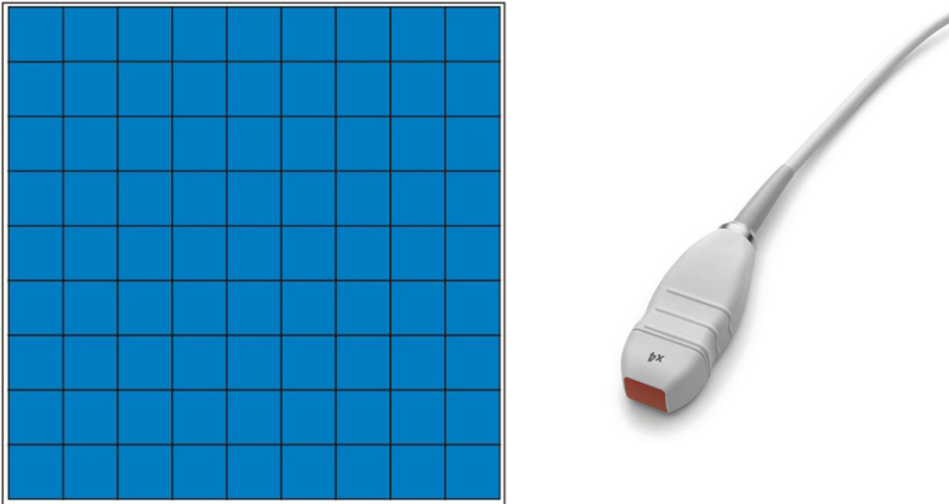


Fig. 12. Dense array transducer. Schematic shows that compared with Fig. 10, in this rendition, all of the squares on the transducer head are connected to one of the roughly 3000 elements. It is the microbeam former that allowed the utilization of the very large (3000) number of elements, the definition of dense array transducer.

to one of providing significant quantification, particularly of left ventricular function.

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Three-Dimensional Echocardiographic Evaluation of the Heart Chambers: Size, Function, and Mass

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Over the past 3 decades, echocardiography has become a major diagnostic tool in the arsenal of clinical cardiology for real-time imaging of cardiac function. More and more, cardiologists' decisions are based on images created from ultrasound wave reflections. From the time ultrasound imaging technology provided the first insight into the human heart, our diagnostic capabilities have increased exponentially as a result of our growing knowledge and developing technology. One of the most significant developments of the past decades was the introduction of three-dimensional (3D) imaging and its evolution from slow and labor-intensive off-line reconstruction to real-time volumetric imaging. While continuing its meteoric rise instigated by constant technological refinements and continuing increase in computing power, this tool is guaranteed to be integrated into routine clinical practice in the near future. The major advantage of this technique is the improvement in the accuracy of the echocardiographic evaluation of cardiac chamber volumes, which is achieved by eliminating the need for geometric modeling and the errors caused by foreshortened 2D views. In this article, we review the literature that has provided the scientific basis for the clinical use of 3D ultrasound imaging of the heart in the assessment of cardiac chamber size, function, and mass, and discuss its potential future applications.

Historical perspective

Since the first successful attempts to interrogate organs and systems “hidden” inside the human body by reconstructing reflections along the ultrasound beam half a century ago, ultrasonography has evolved into a widely used imaging modality. With the important advantages of no ionizing radiation and unique real-time imaging capabilities, echocardiography has become the leading tool for the noninvasive assessment of cardiac anatomy and function. Over the years, the technological evolution has passed multiple milestones, including the transition from the one-dimensional M-mode imaging that provided limited “ice-pick views” to the dynamic 2D B-mode images of the beating heart created virtually in real time at increasingly growing frame rates. Another important milestone was the development of Doppler imaging, which depicts blood flow patterns in the heart chambers and vessels and continues to be a leading diagnostic tool for valvular and vascular pathologies. Whereas echocardiographic scanners have become an indispensable part of routine clinical cardiology practice anywhere from advanced medical centers in large urban areas to remote rural clinics, other more technologically complex and more costly, radiation-free imaging modalities, such as magnetic resonance, are still struggling today with multiple challenges on their ways to attain similar capabilities.

As huge a leap as live 2D imaging was from the M-mode, its limitations, when interrogating a 3D organ such as the heart, have become quickly recognized. Geometric modeling of ventricular volumes from one or two cross-sectional planes proved inaccurate in the presence of aneurysms or asymmetric ventricles [1–7]. Moreover, even in

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symmetric ventricles, the use of foreshortened views to improve endocardial definition turned out to be a major source of error in measuring ventricular volumes [4,8–12]. The potential of 3D imaging to overcome these limitations had become obvious in the early 1980s, when initial results of off-line 3D reconstruction from serial ECG-gated acquisitions of multiple 2D planes were reported [13–15]. This multiplane acquisition strategy was implemented in three different approaches based on parallel linear motion [16,17], rotation [18–20], and free-hand sectioning with electromagnetic or acoustic (spark-gap) locating devices capable of registering transducer position and spatial orientation [21–24]. While parallel linear motion was found less efficient because of the difficulties with maintaining adequate acoustic windows throughout the scan, rotation of the imaging plane from a fixed transducer position was implemented and widely used with transesophageal imaging. The free-hand scanning turned out to be a useful option for transthoracic imaging because it used commercially available transducers and allowed integrating information obtained from multiple acoustic windows from which the structures of interest could be optimally visualized. The main disadvantage of this latter approach is the portability difficulties associated with locator devices. Importantly, all multiplane acquisitions required ECG gating and relied on the assumption that all planes would be

acquired at the same phase of the respiratory cycle to ensure identical shape and position of the heart within the chest for each consecutive acquisition.

Over the past decade, a different approach has been pursued to eliminate the need for tedious multiplane acquisition and time-consuming 3D reconstruction altogether. This approach is based on real-time volumetric imaging, which uses transducers containing arrays of piezoelectric elements capable of scanning pyramidal volumes (Fig. 1), rather than the conventional 2D phased-array transducers that scan a fan-shaped sector in a single plane. Initial reports on the use of sparse array transducers date back to the early 1990s [25,26]. Processing the information generated by these transducers required computational power that was orders of magnitude beyond what was available at the time. To overcome this limitation, a group of researchers and engineers at Duke University built a dedicated system based on parallel processing that allowed, for the first time, real-time 3D ultrasound imaging of the heart. A small number of such systems were used in several academic centers to demonstrate the added benefits of real-time 3D imaging in multiple clinical scenarios [27–32]. Importantly, real-time volumetric imaging allowed fast acquisition of pyramidal datasets during a single breath-hold without the need for off-line reconstruction, thus eliminating motion artifacts known to have adversely affected

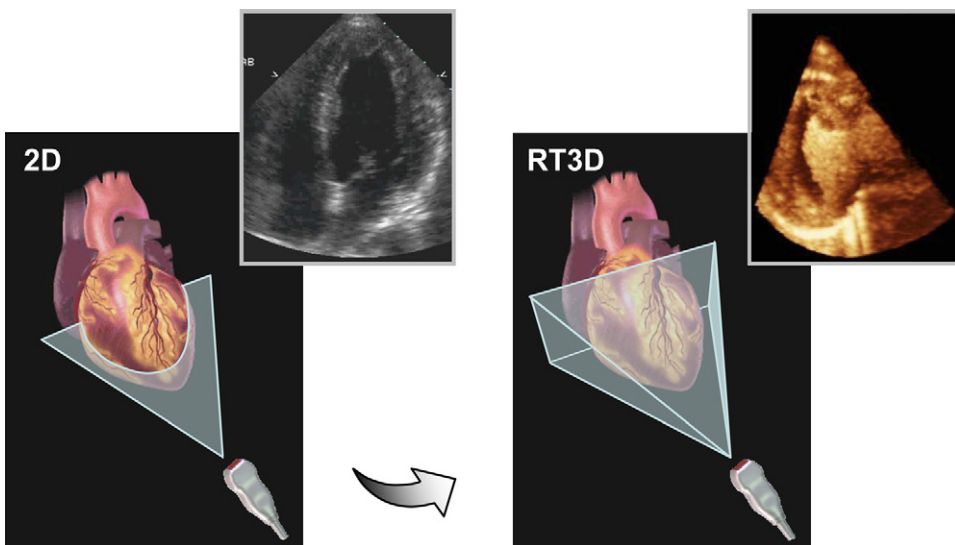


Fig. 1. The transition from 2D to 3D imaging. Whereas 2D imaging is based on scanning a single cross-sectional plane of the heart at a time (*left*), 3D imaging scans a pyramidal volume (*right*).

the multiplane acquisition and reconstruction methodology.

These earlier studies provided the scientific basis for further development of smaller matrix phased-array transducers with larger numbers of crystals and faster scanners based on modern digital processing and improved image formation algorithms to allow higher spatial and temporal resolution real-time volumetric imaging. Such systems have recently become commercially available and are currently offered by several major manufacturers. Their increasing availability gave rise to growing research efforts geared toward embracing this new modality. The large numbers of recent publications in this area reflect the rapidly growing body of knowledge necessary for accepting and incorporating this methodology into the arsenal of clinical cardiac imaging.

Clinical applications

Since the early 1990s, the usefulness of 3D echocardiography has been demonstrated in several areas. In this article, we focus on only a few major applications, including direct evaluation of cardiac chamber volumes without the need for geometric modeling and without the detrimental effects of foreshortened views [12,27–29,31,33–43], and direct 3D assessment of regional left ventricular wall motion aimed at objective detection of ischemic heart disease at rest [40,44–47] and during stress testing [48,49], as well as quantification of systolic asynchrony to guide ventricular resynchronization therapy [50–54].

Assessment of heart chamber volumes and function

One of the main reasons for requesting an echocardiogram in routine clinical practice is the assessment of global and regional left ventricular (LV) function. To date, this assessment is predominantly performed using visual interpretation or “eye-balling” of dynamic ultrasound images of the beating heart, which requires adequate training and experience to accurately estimate LV ejection fraction (EF) and evaluate wall motion. However, the limitations of this subjective interpretation have been long recognized, and consequently the use of quantitative techniques has been recommended. Thus, multiple methods to measure LV size and function have been developed, validated, and refined for both

M-mode and 2D B-mode images, and subsequently for reconstructed 3D images and more recently for volumetric real-time 3D datasets. The relative inaccuracy of the one- and 2D echocardiographic approaches has been attributed to the need for geometric modeling of the ventricle. The “missing dimensions” have also been consistently referred to as the main source of the relatively wide intermeasurement variability of the echocardiographic estimates of ventricular size and function. In addition, the frequently encountered limitations in endocardial visualization, particularly in the apical-lateral segments of the left ventricle, are commonly compensated for by tilting the transducer. This maneuver generally improves endocardial visualization, but at the same time generates oblique or “foreshortened” views of the ventricle, resulting in even less accurate and reproducible measurements. In this regard, the biggest advantage of 3D echocardiography is the lack of dependence on geometric modeling and image plane positioning, which theoretically should result in more accurate chamber quantification.

Indeed, almost all studies that have directly compared the accuracy of 3D measurements of LV volumes and EF have demonstrated the superiority of the 3D approach over the 2D methodology, which was shown to consistently underestimate LV volumes. This superiority was demonstrated in both accuracy and reproducibility when compared against independent reference techniques, such as radionuclide ventriculography or MRI [11,12,22,31,37,38,48,55–59]. These improvements have been shown to occur irrespective of the 3D acquisition strategy employed. Whereas in earlier 3D studies, quantification of LV size and function relied on tedious, manual, or at best semi-automated tracing of endocardial boundaries in multiple planes, today it is based on near fully automated frame-by-frame detection of the 3D endocardial surface from real-time 3D datasets (Fig. 2). Recently a similar approach was implemented in commercial imaging systems, and is rapidly gaining widespread popularity because of its accuracy and ease of use [12], and is poised to become part of the mainstream assessment of LV function.

Similar results confirming improved accuracy and reproducibility of the 3D approach were reported by investigators who compared 2D and 3D echocardiographic measurements of left and right atrial volumes against an independent gold standard [22,42,60,61]. These findings may have

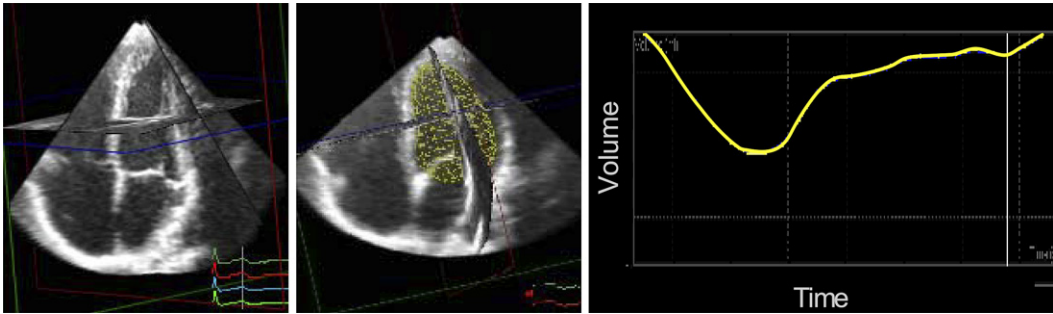


Fig. 2. Dynamic analysis of real-time 3D data. Biplane display (*left*) can be used to detect LV endocardial surface at each time point (*middle*), which allows the calculation of LV volume over time throughout the cardiac cycle (*right*).

important clinical implications on the diagnosis and management of patients with atrial fibrillation, diastolic dysfunction, and acute myocardial infarction.

Because of its complex geometrical crescent shape, the estimation of right ventricular volumes based on geometric modeling from 2D images has been extremely challenging. Thus, not surprisingly, the intrinsic ability of 3D imaging to directly measure right ventricular volumes without the need for geometrical modeling has resulted in significant improvements in accuracy and reproducibility compared with previously employed 2D techniques [27,34,62–64].

Assessment of left ventricular mass

Another clinically important variable that is frequently assessed by echocardiography is LV mass. Measurement of LV mass relies not only on endocardial but also epicardial visualization, which is known to be even more challenging because of the difficulties in identifying the epicardial border. This difficulty is in addition to the limitations previously discussed for the measurements of LV volumes such as inaccurate modeling and foreshortening. Again, the use of 3D images appears to have overcome these limitations, as several studies have reported significant improvements in the accuracy and reproducibility of 3D estimates of LV mass compared with their traditional M-mode and 2D counterparts (Fig. 3) [65–71].

Assessment of regional ventricular function

Diagnosis of regional wall motion abnormalities in echocardiographic studies is routinely performed by visually integrating regional

endocardial motion and wall thickness. The reproducibility of this interpretation is limited because of its subjective nature, which is also extremely dependent on the experience of the reader. This is of particular concern in patients with suboptimal image quality that impedes endocardial visualization. Not only endocardial segments that are poorly visualized may be incorrectly interpreted as having abnormal wall motion, but also discrete areas of hypokinesia may be missed because they are simply not visualized in the standard imaging planes. It is not uncommon for an echocardiographer performing the test to slightly change transducer orientation to “better see” a specific myocardial segment. Such maneuvers can make a myocardial segment look like an area of hypokinesia or alternatively make an apparent wall motion abnormality disappear, and thus affect the diagnostic accuracy of the test. In this regard, volumetric imaging is different because the 3D dataset contains the complete dynamic information on LV chamber contraction and filling.

Importantly, such datasets are acquired virtually instantaneously, and any 2D view can be obtained from them simply by cropping out or “peeling off” the rest of the information. In addition, the function of any ventricular wall can be objectively assessed by measuring a variety of wall motion parameters (Fig. 4) [40]. For these reasons, 3D datasets are extremely appealing for the evaluation of regional LV function. Real-time 3D imaging has been recently used during dobutamine stress testing and found to be feasible and useful for the detection of stress-induced wall motion abnormalities (Fig. 5) [72]. Several other studies have explored the potential of quantitative evaluation of regional LV function based on segmental analysis of the dynamic 3D endocardial

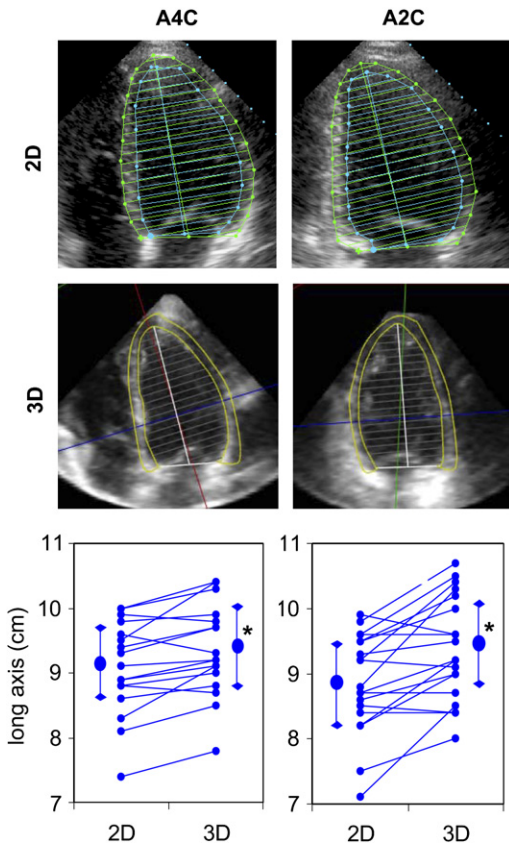


Fig. 3. Effects of volumetric imaging on the accuracy of LV mass measurements. End-diastolic apical four- and two-chamber views of the left ventricle obtained in a patient using conventional 2D imaging (*top*) and anatomically correct apical four- and two-chamber cut-planes selected from a real-time 3D dataset obtained in the same subject (*middle*). Manually traced endocardial and epicardial boundaries used to calculate LV mass are shown on the images. Left ventricular long axis dimension measured on such images in 19 patients (*bottom*). Note the increase in the length of the left ventricle in both apical views, as assessed by the 3D technique in most patients (large circles and error bars represent mean \pm SD, $*P < .05$). (Reproduced from Mor-Avi V, Sugeng L, Weinert L, et al. Fast measurement of left ventricular mass with real-time 3D echocardiography; comparison with magnetic resonance imaging. *Circulation* 2004;110:1814–8; with permission.)

surface [40,44–47]. The use of this methodology in clinical practice requires further studies to be performed in larger groups of patients.

A clinically useful by-product of the 3D quantification of regional LV wall motion is the ability to quantify the temporal aspects of regional endocardial systolic contraction, which

have been used for objective serial diagnosis of LV systolic asynchrony as a guide for resynchronization therapy [52,53], despite the relatively low temporal resolution of real-time 3D imaging. The standard deviation of the regional ejection times (interval between the R wave and peak systolic endocardial motion) has been used as an index of myocardial synchrony. This approach has been used to assess the short- and long-term benefits of biventricular pacing (Fig. 6). A recent study has shown a direct relationship between overall LV performance and synchronicity [54]. In this study, this approach has also been shown to be useful in identifying patients with severe heart failure and asynchronous LV contraction who could theoretically benefit from resynchronization therapy but would not be considered candidates based on their QRS duration [54]. Also, real-time 3D intracardiac imaging has been successfully used to guide the positioning of pacing catheters during interventional electrophysiology [51].

Contrast-enhanced 3D echocardiography

The ability of conventional contrast-enhanced echocardiographic imaging to provide accurate information on the extent and severity of either wall motion or perfusion abnormalities is also limited by its 2D nature. Despite the obvious appeal of the 3D imaging in this context, its use in humans has not been explored until recently. This is because this approach relied on off-line reconstruction from multiple planes, significantly complicating volumetric assessment of LV function. The feasibility of applying volumetric analysis to contrast-enhanced real-time 3D datasets obtained in patients with suboptimal image quality was recently tested. This approach allows quantification of global [73] as well as regional [74] LV function, when used with selective dual triggering at end-systole and end-diastole to reduce the destructive effects of ultrasound on contrast microbubbles.

Future directions

Future advances in transducer and computer technology will allow wider angle acquisition and color flow imaging to be completed in a single cardiac cycle, which will shorten data acquisition and eliminate stitching artifacts. The transducers will have a smaller footprint and weight with higher spatial and temporal resolution. In

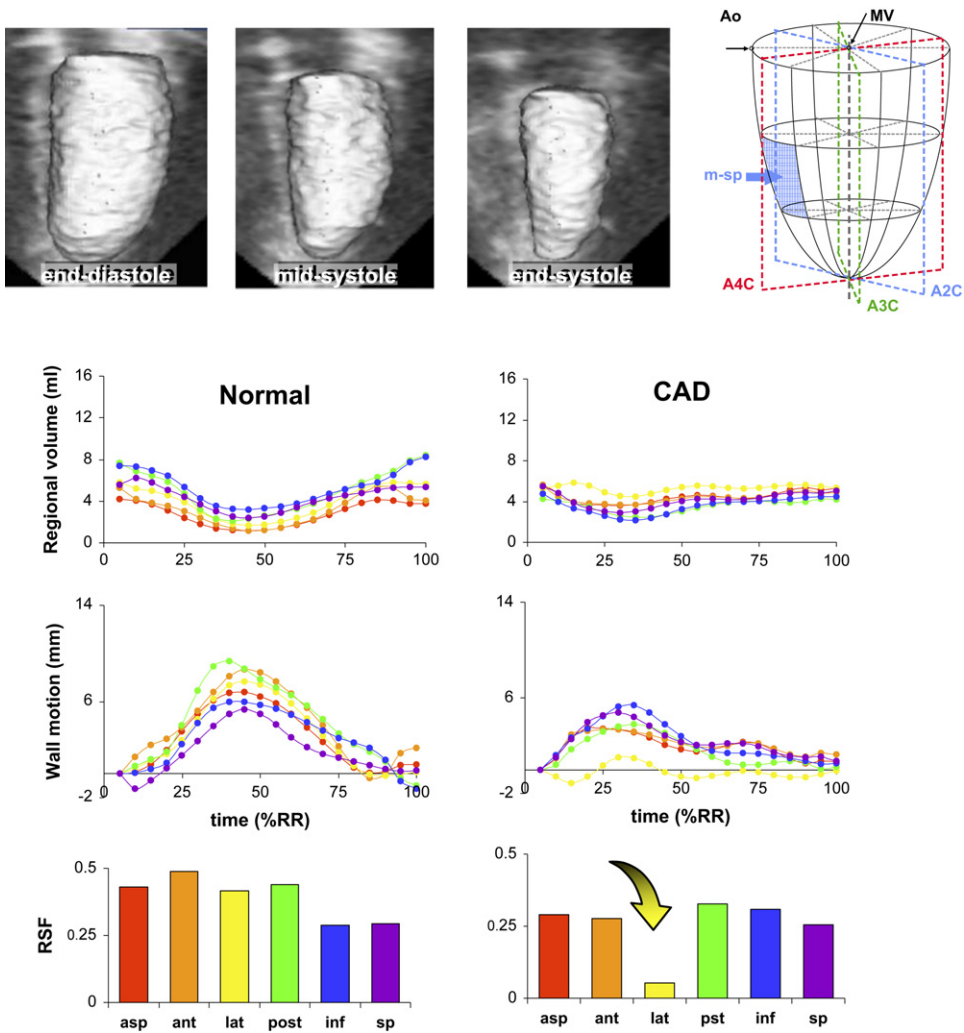


Fig. 4. Volumetric analysis of regional LV function. Example of LV endocardial surface detected from a 3D dataset at three different phases of the cardiac cycle, superimposed on cross-sectional long axis plane (*top left*). Schematic representation of the 3D segmentation model. A2C, A3C, and A4C, apical 2-, 3-, and 4-chamber planes; MV, central point of the mitral valve; Ao, central point of the aortic annulus (*top right*). Shaded area is an example of an LV endocardial surface segment representing the mid-septal (m-sp) wall. Below are examples of regional volume and wall motion time curves and regional shortening fraction (RSF) in six apical segments, obtained in a normal subject (*left*) and a patient with coronary artery disease (CAD, *right*) and hypokinesia in the lateral wall (*arrow*). (Reproduced from Corsi C, Lang RM, Veronesi F, et al. Volumetric quantification of global and regional left ventricular function from real-time 3D echocardiographic images. *Circulation* 2005;112:1161–70; with permission.)

addition, transducers capable of 2D imaging only will be gradually phased out and replaced by new probes that will be versatile in their capability of imaging in different modes, including 2D, 3D, color, and tissue Doppler. With these multi-tasking transducers, it may be possible to significantly reduce the number of steps required to complete an echocardiographic examination, and

thus reduce the time of the test. For example, the standard 2D views could theoretically be obtained from a single volumetric dataset and used for diagnostic purposes assuming that both spatial and temporal resolution are sufficiently high. Significant improvements from the current state of the art are needed in the temporal resolution as well as in the spatial resolution in the far field. We

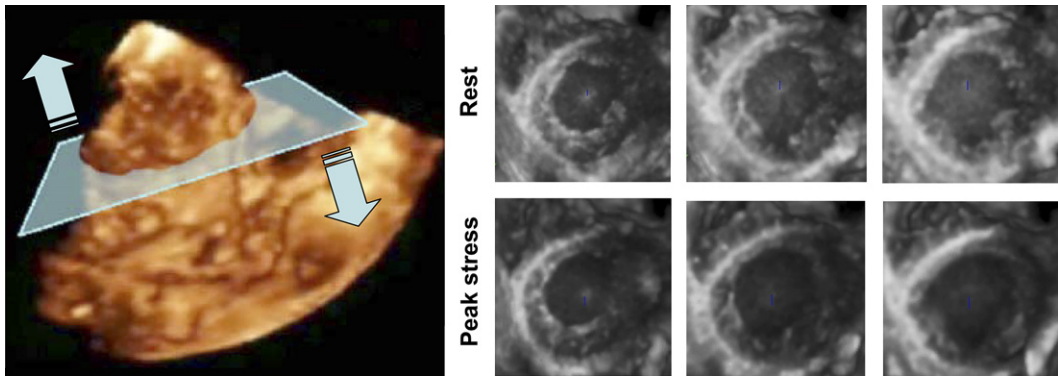


Fig. 5. Off-line viewing of real-time 3D data obtained during dobutamine stress test. These datasets can be used to extract multiple short-axis views at different levels of the left ventricle (*left*). Example of such views extracted from datasets obtained at rest and during peak dobutamine stress (*right*).

also anticipate that the quantification of all cardiac chambers, including flow dynamics, will be performed on the imaging system in an increasingly automated fashion, thus gradually eliminating the need for off-line analysis.

Summary

In the next years, we anticipate that real-time 3D imaging will continue to be integrated into the routine echocardiographic examination. Presently,

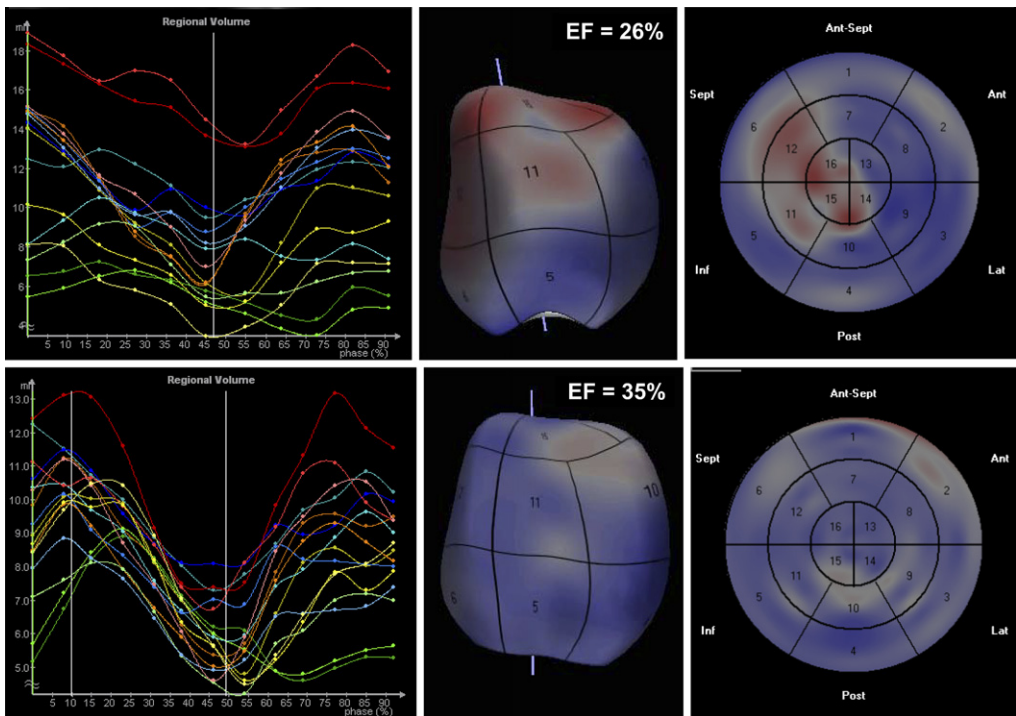


Fig. 6. Assessment of the improvement in synchrony of LV contraction with pacing. Regional volume time curves (*left*) obtained in a patient with LV dyssynchrony without (*top*) and with (*bottom*) biventricular pacing. Endocardial surfaces reconstructed from each dataset are shown with segmentation and color-coding according to regional time to end ejection (*middle*) along with the bull's eye representation of the same data (*right*). Note the changes in colors with pacing reflecting the effects of resynchronization therapy in this parametric display.

there is sufficient evidence to prove that 3D imaging is superior to the traditional 2D techniques and should be routinely used for the quantification of LV volume, EF, and mass. Future clinical applications of this technology are likely to include stress testing with real-time volumetric or simultaneous multiplane imaging from a single transducer position. Volumetric assessment of ventricular asynchrony will be used as an additional tool to guide resynchronization therapy. Also, miniaturization of the matrix-array transducer technology will enable the acquisition of real-time 3D transesophageal images.

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Intraventricular Dyssynchrony Assessment by Real-Time Three-Dimensional Echocardiography

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Heart failure is extremely prevalent in the United States and worldwide, particularly in developed countries. In the United States, 4.7 million people or 2% of the population are affected by heart failure, and 550,000 new cases are diagnosed every year. Further, heart failure accounts for more than 45,000 United States deaths annually [1–3]. Heart failure is the single most frequent reason for hospitalization in the elderly [4,5]. Although there is considerable evidence that heart failure prognosis is improving, recent data from Sweden demonstrated that patients admitted to the hospital with the chief diagnosis of heart failure have a 25% 1-year mortality, an outcome worse than most cancers [6]. Moreover, mortality at 3 years remains greater than 25%, and 5-year mortality still approaches 50%. Based on heart failure patients' annual expenditures of \$10,832, the annual expenditure for heart failure in the United States is as much as \$48 billion [3]. Hence, it is clear that heart failure is a very significant problem, from morbidity, mortality, and cost standpoints. As technology and pharmaceuticals provide more advanced treatments for heart failure, the cost obviously increases.

At least 40% of patients who have congestive heart failure have conduction system disease evidenced by a wide QRS on 12-lead ECG but only 30% have a QRS wider than 120 milliseconds [7–9]. Biventricular pacing has now become

well established as an important therapy in patients suffering heart failure who remain symptomatic despite optimal medical therapy and who have evidence of dyssynchrony documented by a wide QRS duration. Indeed, biventricular pacing has been shown to increase functional capacity, improve quality of life, and even confer a mortality benefit, the latter based on the Cardiac Resynchronization in Heart Failure (CARE-HF) trial results [10]. Currently, only patients who have a QRS duration of 120 milliseconds or more are recommended for biventricular pacing. Paradoxically, mechanical asynchrony defined by echocardiographic parameters is present in up to 43% of heart failure patients who have a narrow QRS duration (<120 milliseconds) [11].

Correctly choosing the patients who will respond favorably to biventricular pacing has emerged as one of the important challenges for cardiologists and other physicians taking care of heart failure patients. This choice is difficult because the current selection criteria for dyssynchrony—a QRS of 120 milliseconds or greater—results in approximately 30% nonresponders. Paradoxically, 20% to 50% of patients who have a QRS less than 120 milliseconds have dyssynchrony documented by advanced echocardiography techniques. At least 45% of patients who have a narrow QRS and dyssynchrony apparently respond to therapy [11–13].

In fact, when dyssynchrony is well documented by all of the echocardiographic methods, the response to therapy tends to be favorable regardless

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of the QRS duration [14–19]. Therefore, it seems essential to develop more advanced techniques for defining dyssynchrony and to test those techniques for prediction of response to biventricular pacing. If such techniques truly define additional patients who respond to biventricular pacing, then the techniques need to be adopted by third-party payers, particularly CMS (Medicare) in the United States. More specifically, it is critical that such techniques more accurately identify those patients who would respond to biventricular pacing such that when compared with QRS duration, additional patients would be eligible for pacing and patients who currently do not respond to pacing would not be chosen such that the paradigm for this relatively expensive treatment is changed. It is clear, however, that despite substantial breakthroughs in the field, development of such an optimal test for biventricular pacing is a daunting task. In that regard, 3D echocardiography (3D echo) offers robust tomographic imaging of the left ventricle that may be capitalized on to provide a more accurate and reproducible index of left ventricular (LV) dyssynchrony than current techniques. In addition, 3D echo is unique in that it allows dyssynchrony comparison of all myocardial segments (including the apex) rather than those contained within a 2D scan plane.

Current techniques of dyssynchrony evaluation

Current techniques of echocardiography use regional velocity, strain, and strain rate using tissue Doppler, gray-scale tracking, or both. Currently, the time to maximum velocity of each of the 12 nonapical LV segments is typically analyzed. The SD of these 12 time increments has become arguably the most popular echocardiographic measure of dyssynchrony and also has the most robust compilation of verification data. In some circles, this approach is referred to as the Yu index because it was developed and largely validated by C. M. Yu [18]. Other methods include the opposing wall index, an index that uses the same data of time to peak systolic velocity, but instead of determining the SD, it compares the time to peak velocity between the anteroseptal and posterior, the anterior and inferior, and the septal and lateral walls. A difference of 65 milliseconds is considered consistent with dyssynchrony [15]. Regional strain and strain rate have also been used to evaluate dyssynchrony, but in most investigators hands, these rates have been inferior to tissue Doppler, mainly

because the waveforms are relatively “noisy.” The one clear exception has been strain determined by gray-scale speckle imaging, a technique that seems to correlate well with tissue Doppler–derived measures of dyssynchrony [20].

3D echo approach to dyssynchrony

3D echo offers a novel approach for identification of intraventricular dyssynchrony. Using semi-automated LV endocardial edge detection, or by partially automated tracing of multiple ventricular views, 3D echo allows functional assessment of all 16 individual segments of the left ventricle. By integrating the function of all the segments, a simple, reproducible method for quantifying global LV dyssynchrony was developed by Monaghan and colleagues [21].

The real-time 3D echo approach uses a dense-array 3D transducer such as the X4 matrix transducer used on the Philips ie33 (Philips Medical Systems, Bothel, Washington and Andover, Massachusetts). This transducer has roughly 3000 active elements that are continuously sending and receiving data, resulting in real-time 3D volume rendering. General Electric also manufactures a matrix transducer that reportedly is somewhat similar in design. This approach typically cannot capture the entire LV volume but captures a series of relatively narrow sector-width subvolumes (typically $30^\circ \times 50^\circ$). Between 4 and 7 of these subvolumes are “stitched” together to provide a full-volume dataset. The result is a pyramidal data set, technically a “frustum,” because the far-field capture is curved ($105^\circ \times 105^\circ$). These data can then be cropped to create orthogonal views equivalent to the apical four- and two-chamber views. From there, manual tracing or semiautomated endocardial border techniques are applied using software developed by TomTec (Munich, Germany) or Philips Medical Systems (Fig. 1). After application of the tracing or edge detection algorithm, an LV cast is created that shows the individual 16 segments of the left ventricle (Fig. 2). From this 16-segment cast of the LV cavity, individual pyramidal subvolumes are created using mathematic modeling, with a nonfixed centerline of the ventricle used as the starting point for the volumes. The pyramidal volumes then protrude outward from the centerline to the edge of the ventricle. By using these pyramidal subvolumes of the entire left ventricle, it is possible to display time–volume data that correspond to each of the 16 standard myocardial

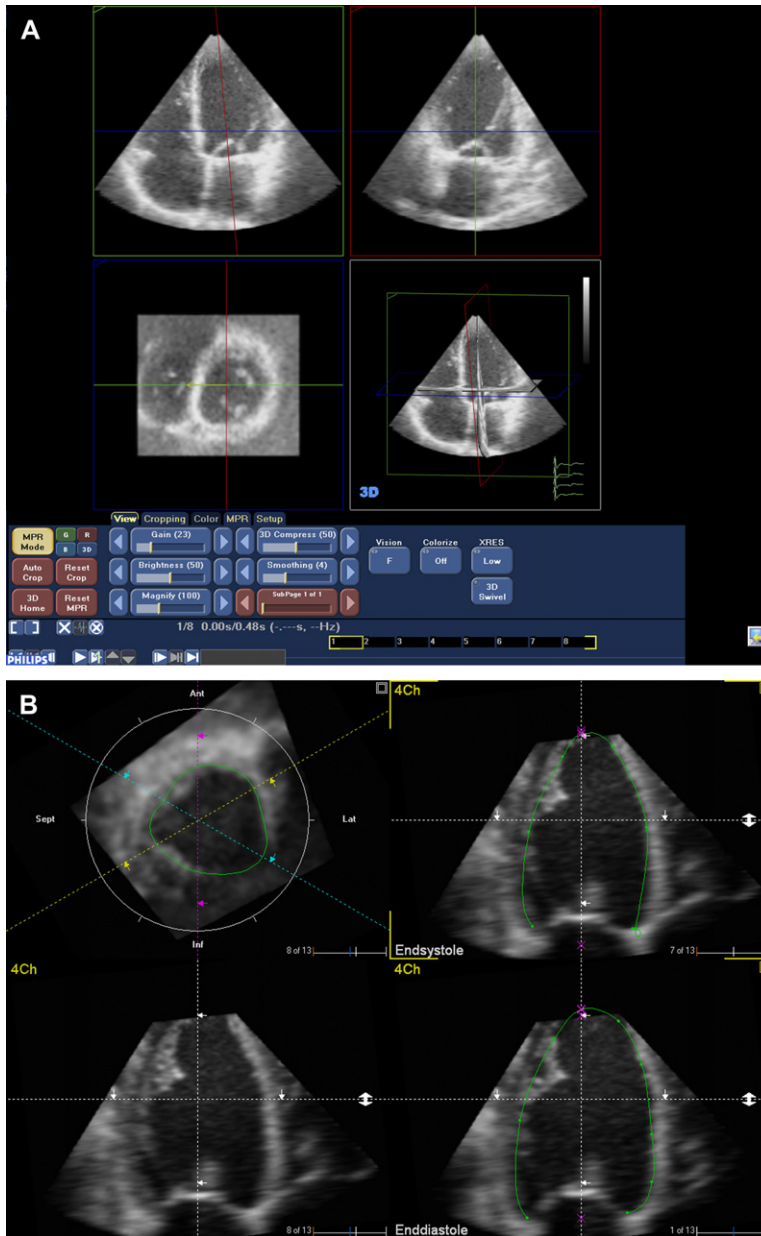


Fig. 1. A 3D data set is displayed after cropping. Cropping results in the display of three orthogonal planes of data. (A) Top left is the four-chamber view, top right is the two-chamber view, and bottom left is the short-axis view. The entire volume of the heart is shown in the bottom right view, with the partial cut-out showing the summarizing of the orthogonal views displayed in the other views. This data set is an example of cropping using Philips Q Lab. (B) A similar example using TomTec software for cropping. The orientation is different, with the short-axis view in the upper left and orthogonal apical views shown in the remaining views.

segments, as defined by the American Society of Echocardiography [22]. When all 16 segments reach minimum systolic volume at nearly the same time, synchrony is present. Conversely,

when the points of minimum systolic volume show great variation (defined in the next section) between segments, there is intraventricular dyssynchrony (Fig. 3).

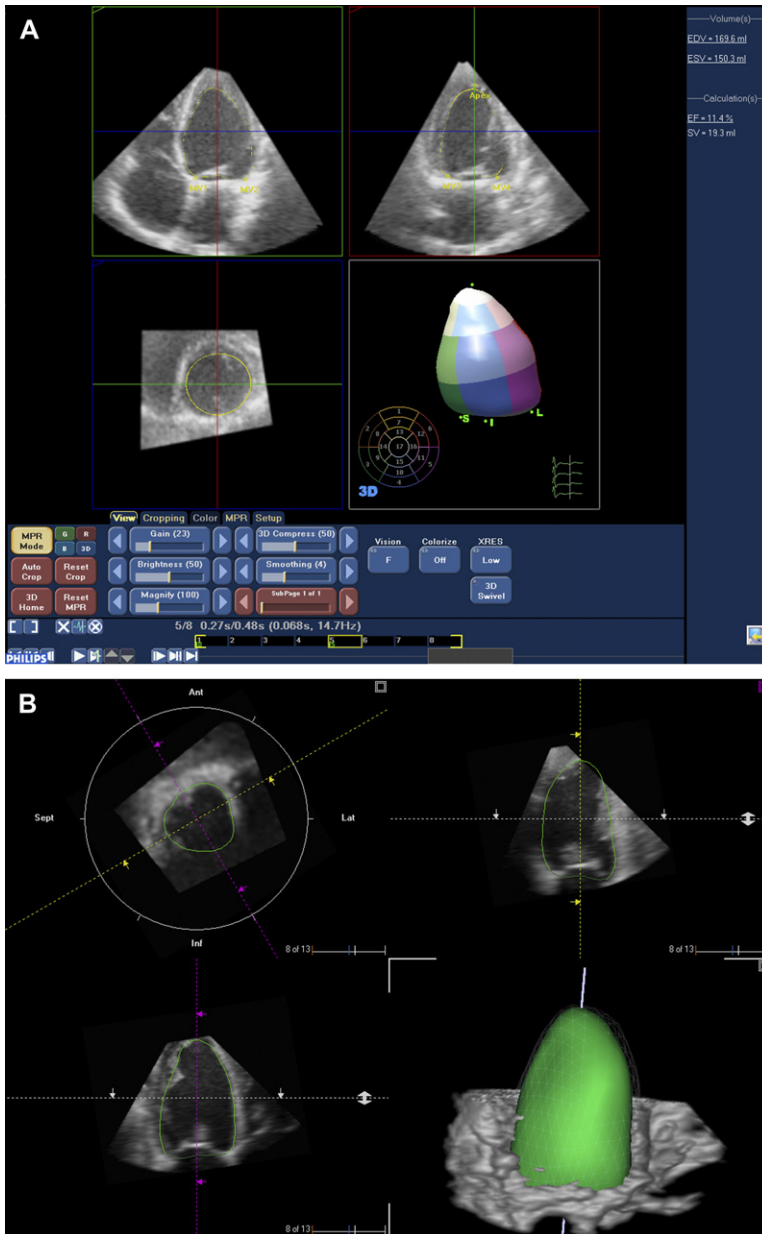


Fig. 2. A “cast” of the ventricle is displayed with the individual segments by Philips Q Lab (A) and without the individual segments with using TomTec software (B).

Development of an index to quantify left ventricular dyssynchrony with real-time 3D echocardiography

A dyssynchrony index has been devised by measuring the time from the onset of the cardiac cycle (defined as the start of the R wave) to the

minimum systolic volume for each segment, and then calculating the SD. The systolic dyssynchrony index (SDI) is the SD expressed as a percentage of the duration of the entire cardiac cycle. Higher SDI levels represent higher levels of dyssynchrony, and vice versa. SDI can be expressed as a percentage of the cardiac cycle rather

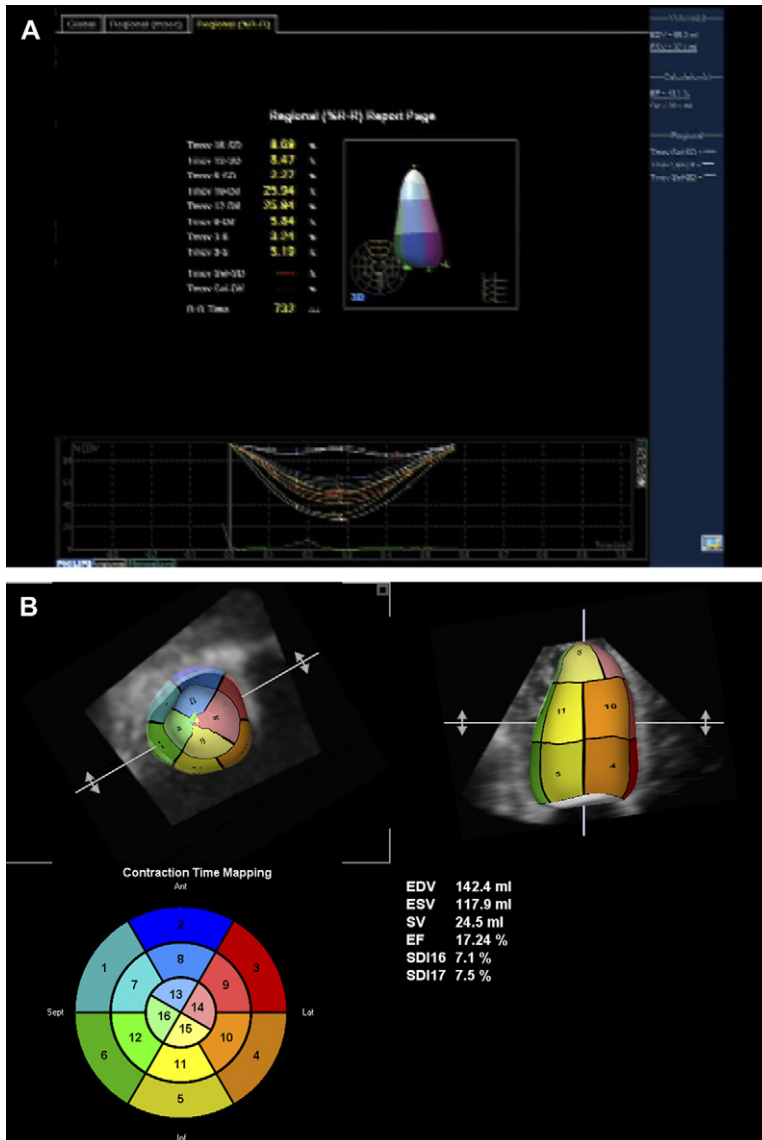


Fig. 3. (A) Normal synchrony, with time volume curves converging on a near-single time point. (B–D) Dyssynchrony, with the minimum volumes occurring at very different time frames for most segments. A and C are examples of analyzing the ventricle for dyssynchrony with Philips Q Lab and B and D are with TomTec software. Note that B shows the ability to calculate dyssynchrony by the 16- or 17-segment model.

than in milliseconds to allow comparisons between patients who have different heart rates.

Establishing a normal value for the systolic dyssynchrony index

A normal value for SDI was established based on the average for normal volunteers plus 3 SDs.

Because healthy volunteers had an SDI of 3.5+/-, the normal was established as 8.3%. Note that the average for patients with normal left ventricular ejection fraction was 4.5±2.4%. Hence an alternate “normal” for patients might be considered to be 11.7 [21]. However, since it is now postulated that even patients with normal left ventricular systolic function may have dyssynchrony [23], the

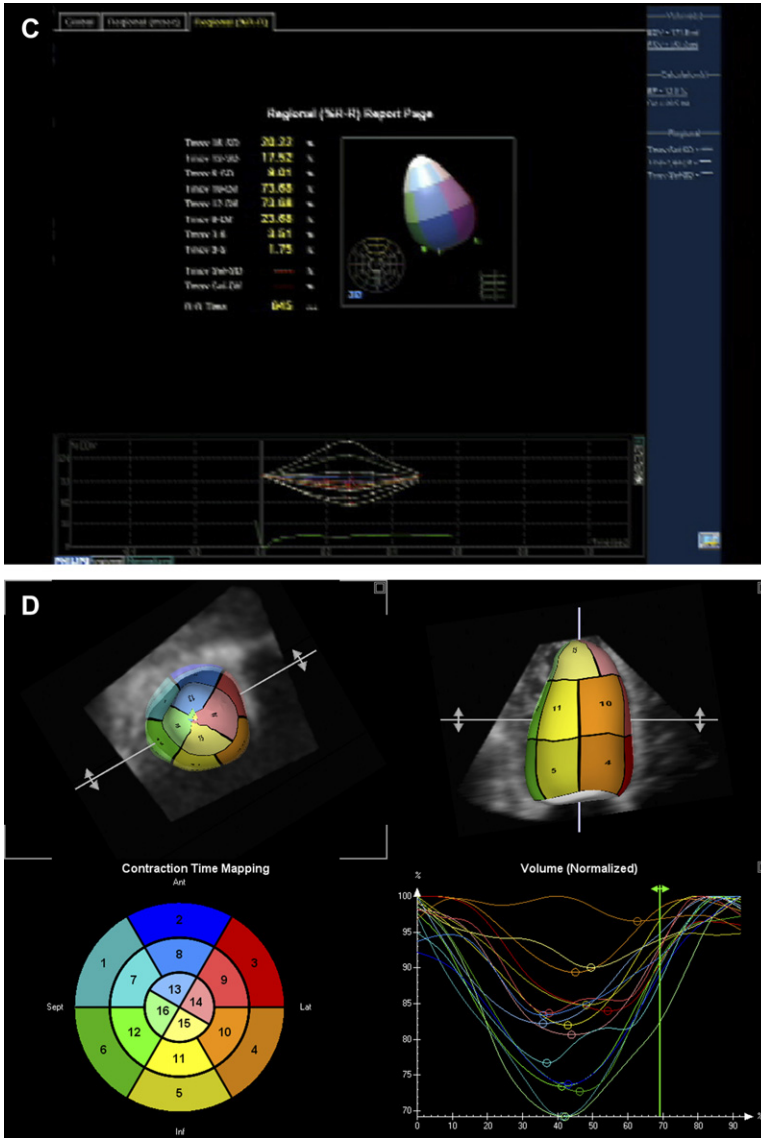


Fig. 3 (continued)

former normal value is likely more clinically applicable.

Response of the systolic dyssynchrony index to cardiac resynchronization therapy

The experience with SDI in response to biventricular pacing (cardiac resynchronization therapy [CRT]) is limited; however, in a small sample of patients (N = 26), Monaghan and colleagues reported significant improvement in SDI with

CRT [21]. Yu and colleagues [18] saw improvement in the SDI when pacing was turned on versus turned off. Gill and colleagues (unpublished data, 2007) also found a significant improvement in a small group of patients. Clearly, a larger experience with CRT and SDI is needed to draw more concise conclusions. Of interest, Monaghan and colleagues [24] recently presented in abstract form a study of 81 patients before and after CRT by real-time 3D echo, with similar results as reported in their initial study [21].

Systolic dyssynchrony index compared with other indices of dyssynchrony

Monaghan and colleagues [24] compared the SDI to the SD of time to peak systolic velocity by tissue Doppler developed by Yu; there was little correlation, with an *r* value of 0.26 (nonsignificant *P* value). In data compiled in the authors' laboratory (Gill and colleagues, unpublished data, 2007), an essentially identical *r* value was found, but with tighter SD (significant *P* value). This result is in marked contrast to recent data by Takeuchi and colleagues [25]. As noted earlier, Yu and colleagues [18,20] evaluated SDI when CRT was turned off and compared it to when patients had CRT turned on. They found the 16-segment SD to be 70 ± 19 (CRT off) versus 46 ± 14 (CRT on). Notable is that although these investigators used the SDI not corrected for R-R interval, their SDI values correlated much better than the authors' values with the 12-segment SD (*r* = 0.739).

Correlation with maximum opposing wall difference was also minor. In fact, SDI correlated best with variables of ventricular systolic function,

Table 1
Correlations of SDI with other echocardiography parameters and QRS

Parameters	<i>r</i>	<i>P</i>
LVEF	0.794	<.0001
FS	0.635	<.0001
WMSI	0.547	<.0001
MPI	0.520	<.0001
SPWMD	0.406	<.0001
EDV	0.580	<.0001
QRS	0.264	.0005
SD-Ti	0.330	.0205
SD-Ts	0.264	.0640
SD-Te	0.169	.2466
SD-Ta	0.334	.203
SD- T€	0.470	.0021

Abbreviations: EDV, end diastolic volume; FS, fractional shortening; LVEF, left ventricular ejection fraction; MPI, Myocardial Performance Index; SPWMD, difference between maximal excursion of the septal and posterior wall by M mode; SD-T€, SD of time to minimum strain; SD-Ta, SD of time to late diastolic peak velocity; SD-Te, SD of time to early diastolic peak velocity; SD-Ti, SD of time to isometric contraction; SD-Ts, SD of time to maximum systolic velocity; WMSI, wall motion score index.

Data from Kapetanakis S, Kearney MT, Siva A. Real-time 3D echocardiography: a novel technique to quantify global left ventricular mechanical dyssynchrony. *Circulation* 2005;112:992–1000.

Table 2
Correlations of SDI with other echocardiography parameters and QRS

Parameters	<i>r</i>	<i>P</i>
LVEF	0.71	<.001
SPWMD	0.377	.0013
QRS	0.46	<.001
SD-Ts	0.26	.022
SD-Te	0.185	.11
SD- T€	0.07	.54

Abbreviations: LVEF, left ventricular ejection fraction; SPWMD, difference between maximal excursion of the septal and posterior wall by M mode; SD-T€, SD of time to minimum strain; SD-Te, SD of time to early diastolic peak velocity; WMSI, wall motion score index.

specifically the ejection fraction, fractional shortening, and wall motion score index. These data are summarized in Tables 1 and 2.

Summary

Real-time 3D echo is a feasible, relatively easy, and reproducible method to evaluate LV systolic function and intraventricular dyssynchrony. Correlation with tissue Doppler indices has been modest in the authors' experience, but other investigators have found more robust correlation [25]. Dyssynchrony by 3D echo inversely correlates with ejection fraction in a tight manner. Additional studies are needed to further correlate the 3D index of intraventricular dys-snchrony with responders to biventricular pacing. Particularly, more patients need to be followed with 3D echo before and after biventricular pacing is instituted. In addition, follow-up of biventricular pacing beyond 6 months will establish the longevity of benefit from biventricular pacing and the longevity of the 3D index over time. At this point, there are two significantly different algorithms for calculating the dyssynchrony index by 3D echo. Both are now largely automated but result in somewhat different results. Again, more studies are necessary to further establish the reliability of the two indices.

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Real-Time Three-Dimensional Echocardiography in Stress Testing: Bi- and Triplane Imaging for Enhanced Image Acquisition

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Stress echocardiography has become a widely used technique in the hands of the clinical cardiologist for diagnosis and risk stratification of patients who have suspected or known coronary artery disease.

There are still numerous methodological limitations, however, so that it remains difficult to acquire high-quality data and to reproducibly analyze the images. These limitations result in reduced test accuracy and a lack of ability to detect regional myocardial ischemia. Main limitations for conventional 2D stress echocardiography are problems during acquisition on one hand and of data analysis on the other hand. Data acquisition may be impaired by

- Probe positioning errors resulting in inadequate image planes
- A reduced image quality during transthoracic scanning with poor visualization of left ventricular (LV) walls
- The time-consuming serial acquisition of different image planes—the set of different 2D cut planes (parasternal short and long axis, apical four and two-chamber view as well as apical long axis) has to be acquired in a narrow time window during peak stress while wall motion abnormalities exist

Regarding data analysis, subjectivity of image interpretation remains the major problem, which

leads to poor interobserver agreement and causes a relevant examiner dependency [1].

Over the last two decades, several attempts have been undertaken to make stress echo easier and less problematic. The use of pharmacological approaches (dobutamine plus atropine) instead of physical stress/exercise may improve image quality and increase the available time for peak level image acquisition. Harmonic imaging with and without contrast enhancement of LV cavity has been demonstrated to improve the endocardial visibility. Thus it will influence the image quality and test accuracy. Other advanced modalities such as tissue Doppler imaging, strain analysis, and color-coded wall motion tracking may facilitate or even replace subjective interpretation in the future. They provide more objective and quantifiable information on wall motion abnormalities. Although promising, because of their complexity, most of these techniques have not made their way into clinical routine. Besides these more technical approaches a human factor may improve test accuracy. Training and higher experience of the examiner lowers interobserver variability and increases test sensitivity, as does a common definition of what wall motion pattern is pathological.

Each of these different approaches was reported to increase stress echo test accuracy. Yet, already the variety of attempts demonstrates that today's 2D stress echocardiography obviously is not perfect.

The development of matrix array transducers and their commercial availability again create new technical possibilities: the simultaneous acquisition of two or three image planes (bi- or triplanar imaging) or even the acquisition of

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a complete pyramidal volume data set dramatically decreases the number of serially acquired heart beats. Several of the previously mentioned limitations of conventional 2D stress echo can be solved using this technique. One clear advantage of the bi- and triplane imaging modalities is that intravenous contrast still can be used easily with the conventional 2D harmonic contrast settings. On the other hand, complete pyramidal volume data sets make the use of contrast more complex as the settings in the 3D rendering mode are being worked out.

Method

Matrix array transducers allow different approaches to perform a stress echocardiography. Two (biplanar, orthogonal or in any desired angle) or three triplanar, mostly in 60-degree increments) image planes can be acquired simultaneously (Fig. 1; videos 1 and 2). Bi- and triplanar techniques may serve as a first step toward complete 3D stress echocardiography.

(Access Biplanar stress and echocardiography and Triplanar stress echocardiography in the online version of this article at: <http://www.cardiology.theclinics.com>.)

The acquisition of wide-angle 3D data sets (so-called full-volume 3D) is based on the serial recording of four narrow subvolumes in consecutive heart beats. Immediately after acquisition, the subsegments are combined to a pyramidal 3D data set with an overall angle of about 80 by 80 degrees, which can comprise a complete LV cavity. Although theoretically more desirable because of complete LV coverage with a full volume, this type of acquisition is not feasible using exercise for stress because of the variable

heart rate immediately following stress. Hence, this limitation makes the bi- and triplane imaging modes more desirable. In addition, in the particularly dilated hearts, even using the now-available wider 105 by 105 acquisition pyramid, sometimes not all of the heart can be acquired. Although this too is a problem for 2D echo, it is less so.

Like conventional 2D techniques, 3D echo during the stress echo workflow then is performed at rest, at low and peak stress, and during recovery. Both physical stress (either bicycle or treadmill exercise) and pharmacological stress (mainly dobutamine plus atropine) have been used in combination with 3D techniques. Left heart contrast agents can be applied for better endocardial delineation.

Once the 3D data set is acquired, image planes can be created in every desired orientation. Besides the extraction of conventional two-, three- and four-chamber-views, multiple parallel short axis slices can be used for systematic analysis of regional wall motion analysis. These slices can be extracted manually (Fig. 2) or semiautomatically, as it is meanwhile possible in several commercially available 3D echo machines (Fig. 3; video 3). The last step of stress echo analysis is a side-by-side analysis of the extracted image planes at different stress/exercise levels still is based on subjective interpretation of wall motion abnormalities.

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Clinical studies on 3D stress echo

Early studies using first-generation 3D equipment in the late 1990s already demonstrated that

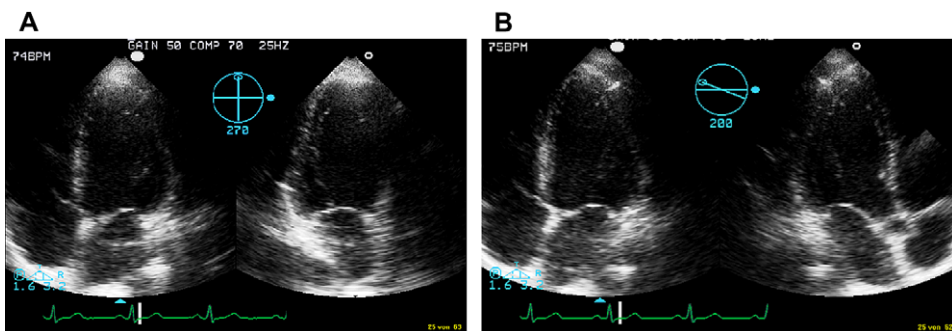


Fig. 1. Biplanar stress echocardiography. Stop frame images demonstrate the image orientation from an apical echo window. Four-chamber view is always shown at the left side, on the right side in (A): two-chamber view, in (B): apical long axis.

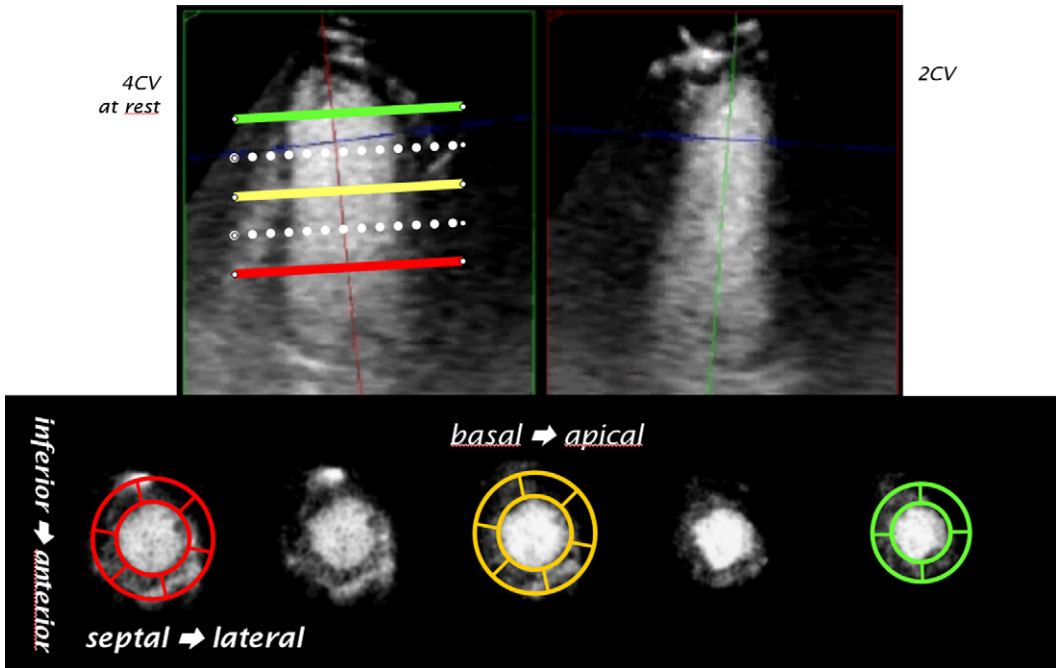


Fig. 2. Cut plane images from a contrast-enhanced 3D data set. Two representative long axis planes (upper panels: four-chamber view, 4CV and two-chamber view, 2CV) and a set of parallel short axis planes from the base (*left*) to the apex (*right lower panel*).

3D volumetric imaging can be used to analyze regional left ventricular wall motion [2]. Other studies even claimed a high sensitivity and superiority over conventional 2D stress echocardiography [3,4]. Overall poor image quality and other technical limitations of the purely 3D dedicated echo system, however, prevented this first approach from widespread clinical use.

Since the advent of the next generation of matrix array transducers, several groups used bi- and triplanar techniques as a first step toward complete 3D stress echo and performed comparative studies versus conventional 2D echo and nuclear imaging [5,6]. The main difference between both stress echo techniques was a significantly shorter scanning time to acquire a triplanar data set covering the complete LV (one loop from an apical window) compared with the serial scanning of three different 2D image planes. Importantly, the shorter scanning time did not reduce test accuracy.

Meanwhile, several recent studies on the use of full-volume 3D stress echocardiography [7–10] also found a good correlation between conventional 2- and 3D stress echo with a nearly identical sensitivity, specificity, and accuracy. The major

difference between 2- and 3D echo techniques was a dramatically shorter scanning time to acquire a 3D data set covering the complete LV compared with the serial scanning of three or more different 2D image planes.

As a consequence of these first studies, a possible question of clinical cardiologists will be: If sensitivity and specificity are equivalent, why should one use a matrix array transducer at all and not continue to use a 2D stress echo? There are, however, more advantages of 3D imaging during stress echo workflow than only a shorter scanning time.

First, there is no need to change the transducer position during apical scanning once the echo window is found. This makes acquisition easier and faster for both beginners and expert echocardiographers. Furthermore, image plane positioning errors leading to false-positive or negative 2D stress echo examinations might be avoided.

Second, the narrow time window at peak stress—especially in physical exercise echo—can be used much more effectively when acquiring a complete 3D data set. Another recent publication on biplanar stress echo [5] has demonstrated that this results in a higher heart rate during exercise stress acquisition, a prerequisite for ischemia

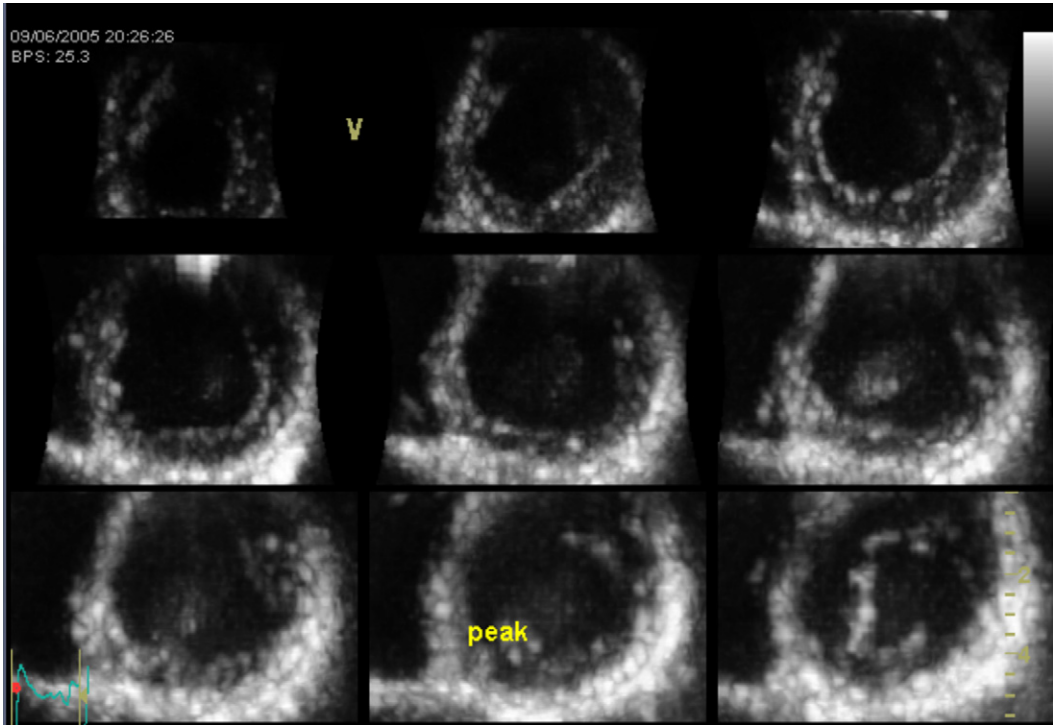


Fig. 3. Modern real-time 3D equipment allows the rapid semiautomatic generation of a set of parallel short axis slices of the LV (nine-slices technique), which makes the interpretation of wall motion abnormalities faster and easier. Stop frame image of nine simultaneously acquired and equidistant short axis slices during peak dobutamine stress. Most apical slice in the upper left corner, most basal slice in the lower right corner.

detection. A shorter time needed for scanning at peak stress and a more complete monitoring (more segments can be observed on-line during stress testing) also reduces the potential risk of prolonged myocardial ischemia for the individual patient. Moreover, reduction of stress echo duration on the long run also may reduce costs and increase throughput in the stress echo laboratory.

Finally, besides the advantages during image acquisition, there seem to be advantages analyzing regional LV wall motion abnormalities in short axis slices instead of long axis planes (see example in videos 4 and 5).

(Access Analyzing Regional LV Wall Motion Abnormalities in Short Axis Slices and 2D Stress Echo in the online version of this article at: <http://www.cardiology.theclinics.com>.)

Limitations

Despite all enthusiasm about a new and revolutionary imaging modality, there are also some limitations of 3D stress echo. Image quality

using matrix array transducers still is worse than with high-end 2D equipment. This is because of a decreased line density and because of the mechanical limitation of a relatively large probe that interferes with narrow intercostal spaces. Some authors therefore claim that left heart contrast enhancement is mandatory for adequate endocardial delineation when acquiring full-volume 3D data [9], although most of the recent studies used no contrast. As previously mentioned, the settings used for contrast in 3D acquisitions are being worked out, and as a result, image enhancement is typically not as robust with full-volume 3D imaging as it is with conventional 2D imaging. Temporal resolution is limited to about 40 to 50 ms, which especially during peak stress influences tests sensitivity and remains unsatisfactory. Meanwhile, potential solutions for this problem are on their way. In addition, the limited sector width sometimes is not wide enough to encompass the complete left ventricle in the ultrasound sector. This is especially true in patients where follow-up of LV function is crucial, those who

have an apical aneurysm or dilated ventricles. Even off-axis scanning sometimes cannot circumvent this problem.

Summary

3D stress echo has been demonstrated to be feasible, resulting in a test accuracy comparable to conventional 2D techniques. Besides the advantages during image acquisition, there are potential advantages to analyzing regional LV wall motion abnormalities in short axis slices instead of long axis planes. 3D stress echo is an important step forward on the way to solving the old dilemma in stress echo: reducing the scanning time and covering the complete left ventricle without losing image quality. At the end of the day, real-time 3D stress echo without any doubt will be the fastest and probably sometime the best way to perform a stress echo. Because bi- and triplane imaging offer 2D quality imaging while simultaneously saving acquisition time, this is arguably the preferred method of using the matrix transducer during stress echo over full-volume acquisition.

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Three-Dimensional Stress Testing: Volumetric Acquisitions

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2D stress echocardiography is a versatile and established technique for diagnosing coronary artery disease [1–3]. Exercise stress echocardiography (ESE) provides not only functional information about the severity of coronary artery stenosis, but also additional physiologic information on exercise capacity and blood pressure response during exercise [4]. Dobutamine stress echocardiography (DSE) should be used in patients who are unable to exercise adequately because of advanced age, orthopedic disease, and/or peripheral vascular disease [2]. Although exercise provides the most physiologic type of stress, DSE has the major advantage of a more controlled setting. It is more ideal for acquisition of multiple images and is particularly optimal for acquisition of full-volume 3D data sets. Both types of stress testing are useful for the detecting myocardial viability and are reliable predictors of future cardiac events [1–5]. Although second harmonic imaging and intravenous ultrasound contrast agents have improved image quality and reduced the number of uninterpretable myocardial segments, 2D stress echocardiography continues to be limited. Conventional wall motion assessment from the four standard imaging planes (parasternal long and short-axis and apical four- and two-chamber views) at times fails to display all left ventricular (LV) segments, with the potential risk of missing stress-induced wall motion abnormalities that could have been delineated

using nontraditional off-axis views. Inadequate visualization of the true LV apex and malalignment of the standard imaging planes frequently result in erroneous interpretations.

Over the last decade, the rapid development of technological and engineering refinements have made the routine clinical application of real-time 3D (RT3D) echocardiography possible [6,7]. Acquisition of full-volume 3D datasets from a single acoustic window allows visualization of multiple imaging planes after cropping the dataset. These characteristics are valuable for stress echocardiography, because:

Single volumetric acquisitions reduce the recording time and delay from peak stress, thus enhancing the detection rate of transient ischemia.

Full-volume datasets incorporate the entire left ventricle.

Alignment and cropping datasets enable visualization of the true apex, which frequently becomes hypokinetic with ischemia originating in the left anterior descending coronary artery.

Alignment of equivalent views acquired at baseline and peak stress, and off-axis visualization of regional wall motion by cropping full-volume datasets could provide enhanced interpretation of wall motion abnormalities.

Accurate interpretation of stress echocardiography highly depends on image quality. One of the current limitations of RT3D echocardiography is the relatively poor image quality and low frame rate obtained compared with 2D imaging. These limitations could result in poor visualization of

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subtle wall motion abnormalities. These issues should be taken into account when performing RT3D stress echocardiography.

Imaging modes

RT3D echocardiography currently allows two types of imaging modes useful for stress echocardiography. These are full-volume mode and multi-plane (biplane or triplane) imaging mode.

Full-volume mode

Full-volume datasets usually are acquired during four or seven consecutive cardiac cycles from the apical transducer position. Because of

variability in heart rate that occurs immediately following exercise, this mode is not suitable for exercise echocardiography (ie, treadmill echocardiography); therefore full-volume acquisitions are most suitable for DSE. The acquired RT3D echocardiography data are cropped using the software integrated in the 3D operating software (QLAB; Philips Medical Systems, Andover, Massachusetts) (Fig. 1). After alignment of the LV long axis, each pyramidal data set is cropped from apex to base to create multiple short-axis images. Long-axis assessment with multiple apical views is also possible. A side-by-side comparison of wall motion then is performed at the similar cut plane of the baseline and peak stress loops.

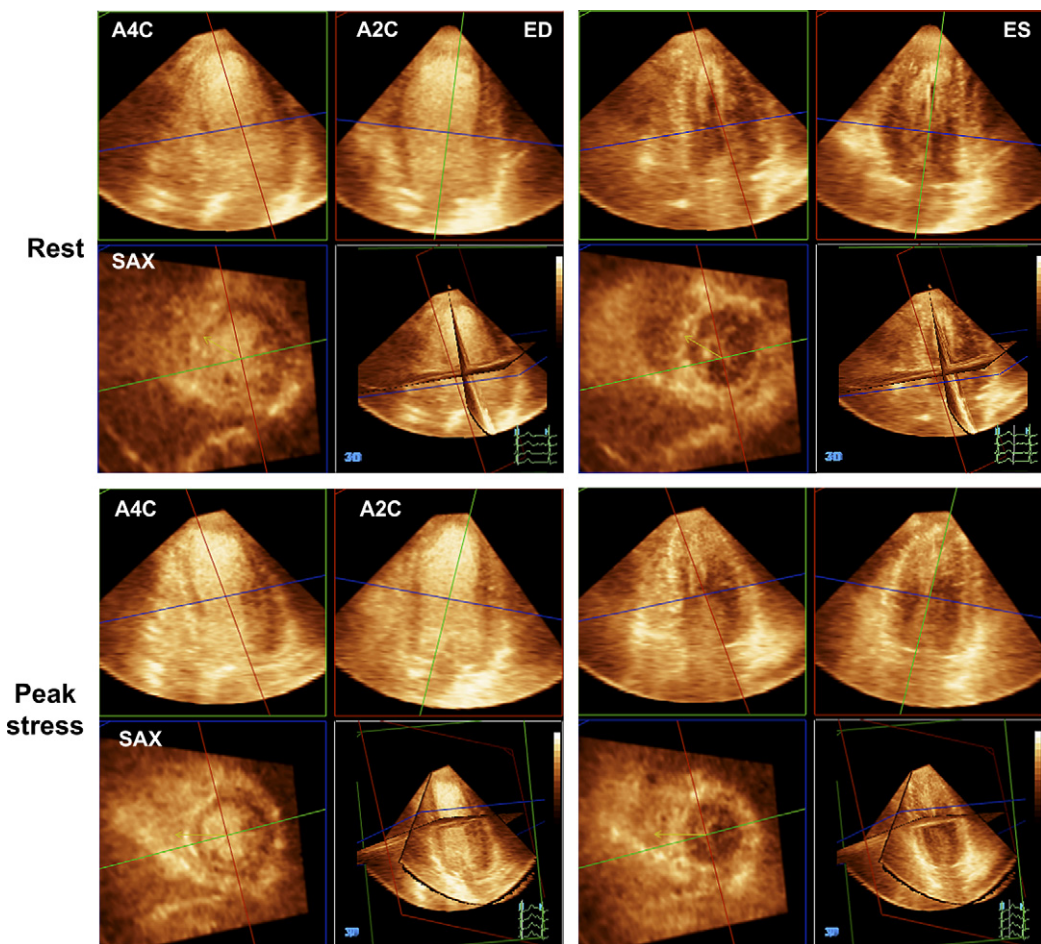


Fig. 1. Cropped image from full-volume datasets obtained during dobutamine stress echocardiography. Upper panels show baseline images, while the lower panels depict images obtained during peak dobutamine infusion. Simultaneous multiple cut plane images (apical four-chamber, two-chamber, and short-axis views) can be cropped from the full-volume datasets (left, end-diastole; right, end-systole).

In addition to manual editing, multiple short-axis 2D views can be created from full-volume datasets (iSlice in Philips Medical Systems, 9 slice in GE Healthcare, Milwaukee, Wisconsin, Fig. 2). With full-volume assessment, the individual wall segments (either 16 or 17 segments) can be divided more precisely and scored at both stress and rest. Finally, even LV dyssynchrony can be evaluated at rest and stress using QLAB or software available from TomTec (Unterschleisheim, Germany).

Biplane or triplane mode

The matrix-array transducer is also capable of imaging in biplane (Philips) or triplane (GE) modes, thus allowing simultaneous display of two or three imaging planes (Fig. 3). The real-time simultaneous acquisition of two or three planes from one acoustic window rather than LV full-volume mode reduces the acquisition time without a significant loss of image quality. This mode is particularly useful for exercise echocardiography.

3D exercise echocardiography

Few studies have reported on the clinical usefulness of RT3D echocardiography during exercise treadmill testing [8,9]. Irrespective of whether a first- or second-generation three-dimension echo machine was used, multiplane exercise echocardiography results in shorter acquisition times with post-treadmill images recorded at higher heart rates without a significant reduction

in image quality. Although reduction of the time required to the completion of image acquisition at peak exercise could improve the sensitivity of exercise stress echocardiography, this hypothesis remains to be proven.

3D dobutamine stress echocardiography

The clinical usefulness of RT3D echocardiography during DSE first was reported using first-generation RT3D echocardiography [10]. Good correlation of segmental wall motion assessment between RT3D and conventional 2D techniques was noted at baseline and at peak stress. The diagnostic accuracy for detecting significant coronary stenosis was slightly higher in RT3D echocardiography (88%) compared with 2D echocardiography (80%). Although encouraging initial results were reported, relatively poor image quality because of the use of sparse-array transducers coupled with tedious off-line processing did not allow RT3D echocardiography to be embraced as the new reference imaging modality for stress echocardiography. Recently, the advent of second-generation RT3D echocardiography and commercially available 3D analysis software has facilitated the application of this technique during DSE in routine clinical setting. Several studies have addressed comparable diagnostic accuracy between RT3D and 2D echocardiography for detecting myocardial ischemia and coronary artery stenosis (Table 1) [11–15]. The use of intravenous ultrasound contrast agents has been shown to further improve endocardial border

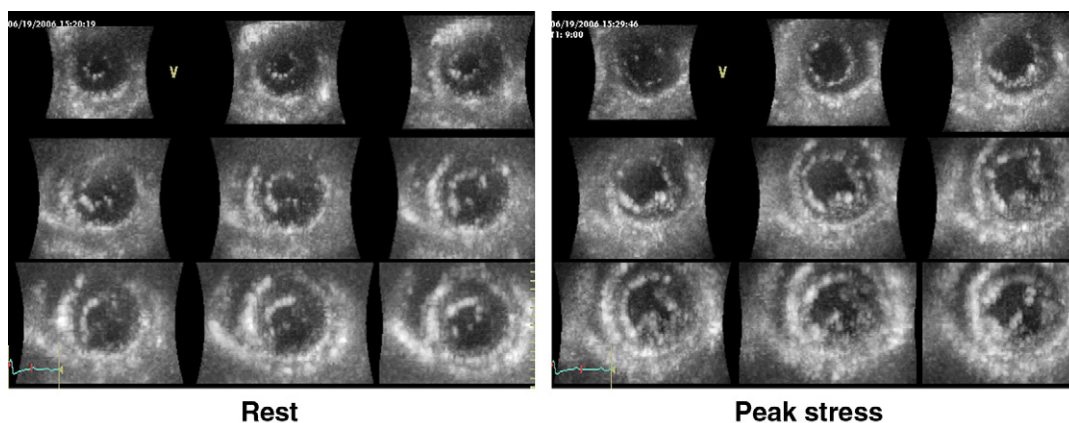


Fig. 2. Multiple 2D short-axis views (nine-slice) from full-volume datasets during dobutamine stress echocardiography. By cropping full-volume datasets, multiple 2D short-axis views from apex to the basal part of the heart can be obtained. These short-axis views obtained at end-systolic frame clearly show cavity dilatation at peak stress (*right panel*), suggesting the presence of multivessel disease. Coronary angiography confirmed the presence of triple vessel disease.

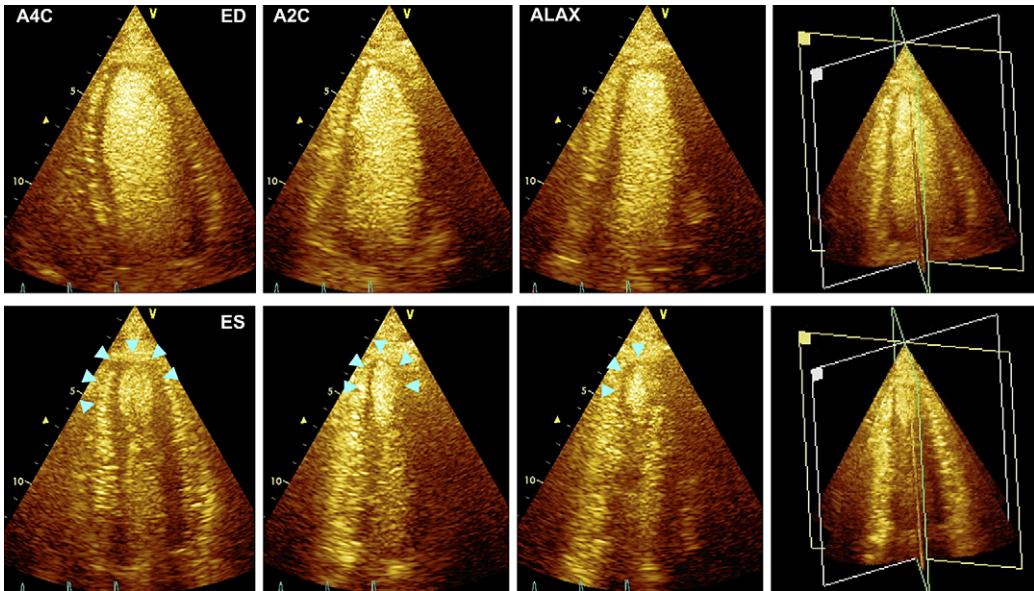


Fig. 3. Stress-induced apical wall motion abnormalities with triplane dobutamine stress echocardiography. Real-time triplane echocardiography from the apical window allows simultaneous visualization of apical four-, two- and long-axis views. The relative angles between the three images can be adjusted. Upper panels show end-diastolic triplane images obtained at peak stress. Lower panels show end-systolic images. Apical wall motion abnormalities are shown clearly, and their extent can be evaluated.

delineation and decrease the number of uninterpretable segments during 3D DSE [12,14]. Despite these excellent results, several limitations of RT3D DSE should be mentioned [13,14,16]. These include:

Low frame rates

The large matrix array transducer footprint results at times in poor image quality, particularly in patients who have narrow intercostal spaces.

Contrast stitch artifacts

Low frame rates and stitch artifacts originating from the wedge-shaped subvolume acquisitions may result in false-positive interpretations because of the erroneous diagnosis of inhomogeneous contraction and relaxation patterns.

Image quality of the matrix transducer is still not as good as that generated by conventional 2D transducer, even with the use of contrast agents. Despite the potential advantage of acquisition of a full-volume data set in terms of complete coverage of the left ventricle, the sensitivity, specificity, and accuracy remain less than ideal and not particularly better than conventional 2D methods [11–15].

The feasibility of real-time triplane DSE has been addressed in a recent study [17]. This study also reported that real-time triplane DSE appeared to be equally sensitive and specific as 2D DSE for assessing coronary artery disease. Although the triplane methodology has not been compared directly with full-volume acquisition, the sensitivity in this study was higher than reported in similar studies using the full-volume acquisition [10–15]. Clearly there are major discrepancies between these studies. Some use coronary angiography as their reference standard [10,15]; one used single photon emission computed tomography (SPECT) [11], and one used 2D DSE [13]. Whether ultrasound contrast agents could improve diagnostic accuracy of multiplane DSE further remains to be determined.

Future direction

In the future, technological transducer developments should improve the diagnostic yield of 3D stress echocardiography further. A single-beat acquisition of the full-volume datasets could avoid stitch artifacts and reduce acquisition time, thus allowing acquisition of full-volume datasets during exercise stress echocardiography.

Table 1
Feasibility and diagnostic accuracy of real-time 3D dobutamine stress echocardiography

Type	Author	Number of patients	Feasibility		Concordance rate (two-dimensional [2D] versus two-dimensional [3D]) (%)	Gold (reference) standard	Sensitivity (%)	Specificity (%)	Accuracy (%)
			Segments visible with conventional imaging	Segments visible with contrast imaging					
Full-volume	Ahmad, et al [10]	253	92%	NA	84 (baseline) 89 (peak)	CAG n = 90 (36%)	3D: 88 2D: 79	3D: 88 2D: 81	3D: 88 2D: 80
Full-volume	Matsumura, et al [11]	56	89%	NA		Tl SPECT n = 56 (100%)	3D: 86 2D: 86	3D: 80 2D: 83	3D: 82 2D: 84
Full-volume	Takeuchi, et al [13]	78	NA	97%	69 (pt) 88 (Vasc)	2D DSE n = 78 (100%)	Pt: 58 Vasc: 66	Pt: 75 Vasc: 92	Pt: 69 Vasc: 88
Full-volume	Pulerwitz, et al [12]	14	75%–87%	97%–99%					
Full-volume	Nemes, et al [14]	36	76%	90%					
Full-volume	Aggeli, et al [15]	56	NA	NA	98 (baseline) 82 (peak)	CAG N = 56 (100%)	3D: 84 2D: 82	3D: 72 2D: 83	3D: 80 2D: 82
Triplane	Eroglu, et al [17]	36	97%	98%		CAG n = 36 (100%)	3D: 96 2D: 93	3D: 78 2D: 78	3D: 92 2D: 89

Abbreviations: CAG, coronary angiography; NA, not available; pt, patient; Tl SPECT, thallium single photon emission computed tomography; Vasc, vascular territory.

Introduction of matrix transducers with smaller footprints will enhance lateral image quality. Increases in the frame rate will avoid the false interpretation of inhomogeneous contraction and relaxation patterns currently seen at higher heart rates.

Summary

Although several preliminary clinical studies have been shown that RT3D echocardiography has tremendous promise on stress echocardiography, further technological refinements and larger size clinical studies will be required for the widespread application of volumetric 3D stress echocardiography.

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Three-Dimensional Echocardiographic Evaluation of Myocardial Perfusion

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One of the most intriguing developments in ultrasound imaging of the heart that brought about a 2-decade-long combination of expectations and disappointments was the introduction of echocardiographic contrast agents. Despite repeated waves of controversy regarding the readiness of this technology for clinical use, it is widely accepted that echocardiographic contrast is a powerful tool that improves our ability to evaluate left ventricular (LV) function and allows differential diagnosis of thrombi and intravascular masses. Another use of echocardiographic contrast media, which has sparked tremendous interest and over the years generated a significant body of research, is the assessment of myocardial perfusion. Nevertheless, to date, the assessment of myocardial perfusion by contrast echocardiography is not as well established as the use of LV opacification. There is still a fair amount of debate in the attempt to establish standardized techniques and clinically usable protocols. While the vast majority of published work has been based on the use of contrast for two-dimensional (2D) perfusion imaging, there are a small number of recent studies aimed at exploring the idea of three-dimensional (3D) assessment of myocardial perfusion, which has the potential to overcome many of the limitations of the 2D methodology. In this article, we provide a brief overview of the 2D work that provided the scientific basis for the emerging 3D methodology and discuss the unique features and promises as well as the challenges posed by this novel approach.

History of 2D perfusion imaging

Although 2D echocardiographic imaging has been playing a pivotal role in the clinical assessment of cardiac function for several decades, its ability to assess myocardial perfusion is not as well established. Since the early reports of successful visualization of myocardial perfusion in the mid 1980s [1–5], a large number of research studies and scientific publications have been dedicated to this cause. A quick literature search on this subject today will result in over a thousand published papers. These studies have been instigated by multiple technological breakthroughs in both the development of improved contrast agents and imaging technologies, such as the development of contrast-targeted modes specifically “tailored” to improve the contrast-enhancing effects of these agents. Among these contrast-targeted techniques, the most widely used are pulse inversion and power modulation, both currently available in commercial scanners. These techniques selectively enhance microbubble-generated reflections, while simultaneously suppressing reflections originating from cardiac structures and tissues, thus resulting in better visualization of intramyocardial contrast.

For more than 2 decades, the evaluation of myocardial perfusion has been frequently referred to as the “holy grail” of contrast echocardiography. The different aspects of this “crusade” have been previously discussed by different authors in over a hundred review papers in the English language alone [6–20]. Thus, it is difficult to briefly review the published work on myocardial contrast echocardiography without unjustly omitting many important studies. Generally speaking, published papers ranged from

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attempts to simply visualize intramyocardial contrast and thus detect perfusion defects using different imaging techniques [1,3,21–30] to methodologically more complex approaches aimed at the quantification of myocardial tissue blood flow [31–44].

With the steady improvements in stability and uniformity of contrast agents as well as the development of more robust imaging techniques, the qualitative perfusion imaging studies have progressively showed incremental improvements in the ability to visualize myocardial contrast, resulting in a steady increase in the confidence of the interpretation of perfusion images. Whereas many of these studies reached clinically acceptable levels of diagnostic accuracy, these levels remained at best only modest in multicenter trials. It is likely that this hurdle mostly reflects the subjective nature of the interpretation and its reliance on the experience of the reader necessary to differentiate between true perfusion abnormalities and attenuation-related artifacts that are more severe in the presence of highly echogenic contrast materials.

The more objective, quantitative perfusion techniques rely on measuring beat-by-beat changes in myocardial contrast, such as contrast inflow or washout following bolus injections [32,34–37,39], or, alternatively, its replenishment after destructive high-energy ultrasound pulses delivered during contrast infusion [14,40,45–47]. Although it is well understood that these changes are essential for the assessment of tissue blood flow dynamics, each specific maneuver has its advantages and disadvantages in terms of ease of use and reliability of information yielded [45,48,49]. As a result, there is no consensus on the specific technique that would be preferable for routine clinical use. Also, quantification offers little if anything in terms of dealing with image artifacts and cardiac translation, which may affect quantitative techniques even more than intelligent visual interpretation capable of immediately recognizing these issues [43].

Importantly, myocardial contrast echocardiography, with or without quantification, proved useful in multiple clinical scenarios. Beyond the obvious detection of resting perfusion defects [1,3,21–30] and evaluation of severity and extent of perfusion deficit [24,30,50–54], it was found useful in detecting stress-induced myocardial ischemia [55–60] and diagnosing acute coronary events in patients presenting with atypical chest pain in the emergency department [61–63], as

well as evaluation of myocardial reperfusion after coronary revascularization [56,64–67].

From 2D to 3D perfusion imaging

Nevertheless, it has been recognized that the ability of conventional contrast-enhanced echocardiographic imaging to provide accurate information on the extent and severity of perfusion abnormalities is limited by its 2D nature, similar to the assessment of LV volume and function (see the article on chamber quantification elsewhere in this issue). Despite the appeal of 3D imaging in this context, its use in humans has not been explored until recently. This is because the 3D approach has required off-line reconstruction from multiple planes, significantly complicating the volumetric evaluation. As a result, 3D assessment of myocardial perfusion remained limited to occasional reports on the visualization of perfusion defects in animals undergoing experimental coronary occlusion or the quantification of the perfusion defect size [68,69] using repeated boluses of contrast media during consecutive acquisitions of multiple planes (Fig. 1). These studies demonstrated that the location and extent of perfusion defects measured on contrast-enhanced 3D images correlated closely with the location and extent of the infarct as assessed by tissue staining. The use of bulls-eye displays generated from these 3D images of the myocardium

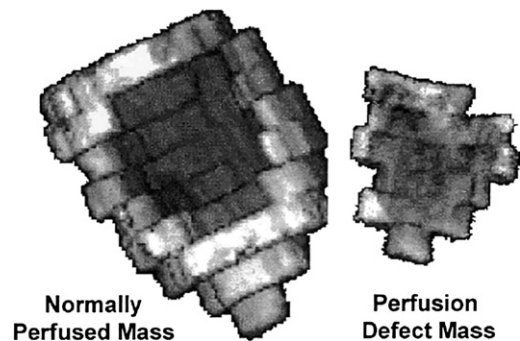


Fig. 1. 3D images of normally perfused myocardial mass and perfusion defect mass reconstructed by manually contouring the above regions in multiple short-axis slices of the left ventricle derived from a contrast-enhanced 3D data set. (Reproduced from Yao J, De CS, Delabays A, et al. Bulls-eye display and quantitation of myocardial perfusion defects using 3D contrast echocardiography. *Echocardiography* 2001;18:581–8; with permission.)

allowed easy visualization of perfusion defects without the need to compensate for the adjacent highly contrasted LV cavity (Fig. 2).

From multiple planes to volume acquisitions

Volumetric quantification of tissue blood flow would require repeated contrast maneuvers, such as bolus injections, that are necessary to assess flow dynamics for each imaging plane, thus rendering this methodology clinically inapplicable. The development of matrix array transducers that allow real-time volumetric imaging has obviated the need for repeated contrast maneuvers since the entire volume is captured during a single maneuver without reconstruction from multiple planes. This major conceptual change has opened new possibilities for the quantitative 3D assessment of myocardial perfusion. The initial experience with real-time perfusion imaging was obtained in an open-chest sheep model of acute ischemia using epicardial imaging with a sparse array transducer (Fig. 3) [70]. This methodology allowed accurate delineation of perfusion defects in close agreement with tissue-staining anatomic reference [70]. These findings were subsequently confirmed in animals undergoing open-chest coronary occlusion using epicardial imaging with a fully sampled matrix array transducer that yielded an incremental improvement in image quality [71,72]. These studies suggested that non-invasive volumetric assessment of perfusion defects

may eventually be feasible in patients with suspected coronary artery disease.

From manual tracing to automated myocardial segmentation

The quantification of tissue blood flow in a certain area of the myocardium, either as absolute values in mL/min/g or as quantitative indices calculated from contrast intensity time curves, requires the definition of a myocardial region of interest (ROI) in which dynamic changes in contrast intensity are then analyzed. Traditionally, quantitative 2D analysis of myocardial perfusion has been based on manual tracing of ROIs in a single imaging plane and frame-by-frame realignment of these ROIs to compensate for cardiac translation. Although this methodology is subjective and time-consuming, it is relatively straightforward and easy to implement in software. In contrast, drawing ROIs in 3D space, a prerequisite for volumetric perfusion analysis, is significantly more complex, both conceptually and from the point of view of implementation. Needless to say, realignment of 3D ROIs throughout the image sequence to compensate for cardiac translation is not simple.

To overcome these limitations, we initially developed a technique for automated identification of myocardial regions of interest for fast, translation-free analysis of myocardial contrast enhancement from 2D images [73]. Our approach

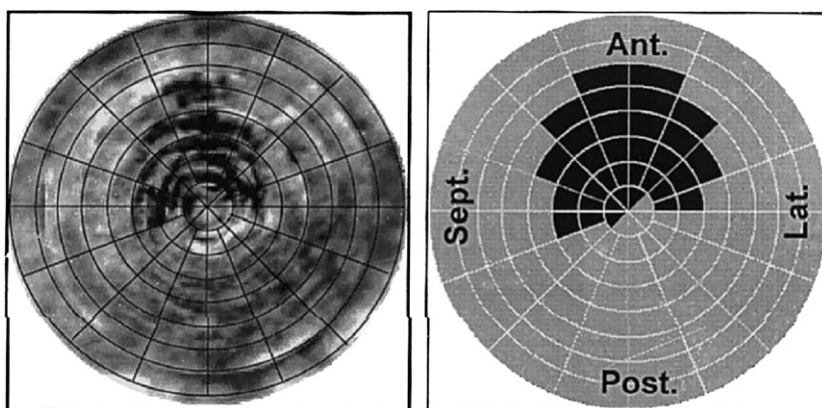


Fig. 2. Bulls-eye image formed from a contrast-enhanced 3D data set (left) and the corresponding binary image showing underperfused sectors (right). (Reproduced from Yao J, De CS, Delabays A, et al. Bulls-eye display and quantitation of myocardial perfusion defects using 3D contrast echocardiography. *Echocardiography* 2001;18:581–8; with permission.)

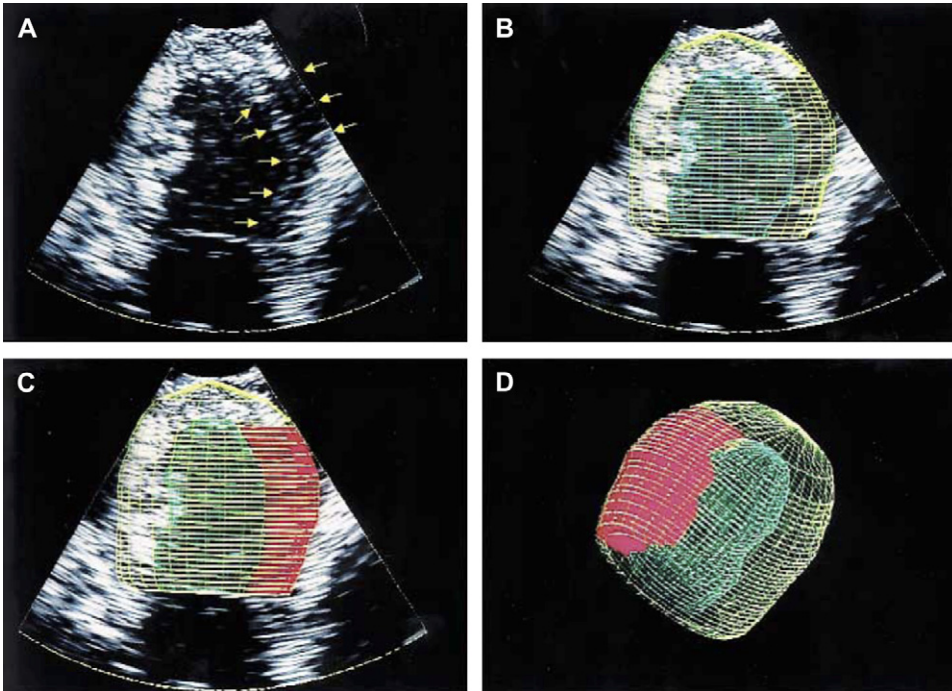


Fig. 3. Representative example of methodology used to quantitatively assess mass of underperfused myocardium from RT3D images in sheep with acute occlusion of circumflex coronary artery. (A) Tomographic view derived from volumetric image showing area of myocardium devoid of contrast opacification (arrows). (B) 3-dimensional rendering of left ventricular (LV) endocardial (in green) and epicardial (in yellow) surfaces generated by computer, based on operator's tracing. Area between both surfaces corresponds to myocardial volume, which is used to calculate myocardial mass. (C) Rendering of LV region without contrast opacification generated by computer, based on operator's tracing of corresponding endocardial surface. Red area represents volume used to calculate mass of underperfused myocardium. After tracing is completed, volumetric image can be freely rotated to examine 3-dimensional appearance of LV endocardial and epicardial surfaces and underperfused myocardium, as shown in (D). (Reproduced from Camarano G, Jones M, Freidlin RZ, et al. Quantitative assessment of left ventricular perfusion defects using real-time 3D myocardial contrast echocardiography. *J Am Soc Echocardiogr* 2002;15:206–13; with permission. Copyright © 2002, American Society of Echocardiography.)

was based on automated detection of the endocardial boundaries, which are relatively easy to detect in the presence of contrast in the LV cavity, followed by outward expansion into the myocardium and segmentation (Fig. 4). We tested this approach on power modulation images obtained in pigs undergoing coronary occlusions, and found that it allowed automated translation-free quantification of regional myocardial perfusion, without the need for ROI tracing [73]. More recently, we extended this concept to 3D images by automatically detecting LV endocardial surface and then defining and segmenting the 3D myocardial shell to allow automated volumetric analysis of myocardial perfusion without ROI tracing. Importantly, since the detection of LV myocardium is automated, it can be performed quickly on every

consecutive frame, thus providing an ultimate solution for the problem of myocardial translation.

From manual boluses to alternative maneuvers

Another important challenge on the way to quantitative evaluation of myocardial perfusion is the choice of the contrast maneuver that would provide access to information about tissue blood flow. Because the effects of contrast boluses on echocardiographic images are difficult to predict, and “on-the-flight” optimization of gain setting for a short-lived bolus is virtually impossible, it has been long recognized that bolus injections are hardly the solution for either 2D or 3D perfusion quantification. The alternative approach, based on the use of continuous contrast infusion and

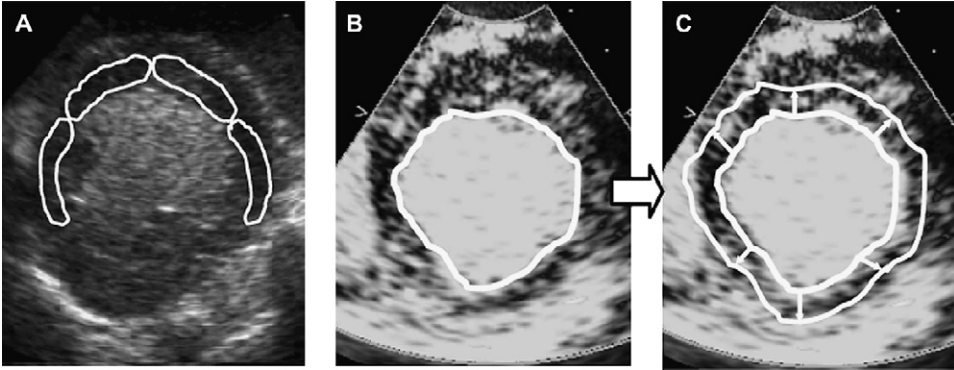


Fig. 4. Regional contrast is usually assessed by manually tracing myocardial regions of interest (A). High-contrast LV cavity is suitable for automated endocardial border detection (B), which allows automated identification of the myocardium (C) in each consecutive end-systolic frame, as a basis for automated, translation-free perfusion analysis. (Reproduced from Caiani EG, Lang RM, Caslini S, et al. Quantification of regional myocardial perfusion using semiautomated translation-free analysis of contrast-enhanced power modulation images. *J Am Soc Echocardiogr* 2003;16:116–123; with permission. Copyright © 2003, American Society of Echocardiography.)

high-energy ultrasound pulses that is widely used for 2D perfusion evaluation [14,40,45–47], is not available because of the excessive energy required for microbubble destruction in the entire heart.

We recently described an alternative contrast maneuver that could be safely used to quantify

perfusion from real-time 3D echocardiographic images. This approach uses continuous infusion of contrast and thus allows ample time to optimize imaging settings. It does not require microbubble destruction by high-energy pulses, but instead uses a brief infusion interruption, which effectively

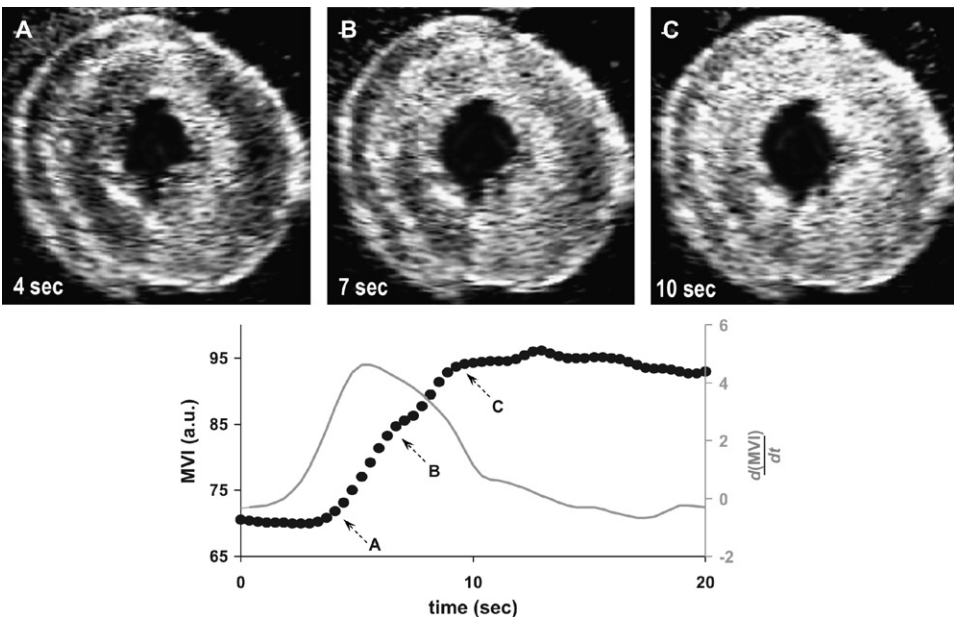


Fig. 5. (Top) Example of short-axis images of the isolated rabbit heart, which are part of a sequence acquired during brief interruption of contrast infusion: (A) at peak contrast clearance, (B) during contrast wash-in, and (C) after reestablishing steady-state enhancement. (Bottom) Myocardial video intensity time curve and its time derivative, which is used to calculate peak contrast inflow rate, a quantitative index of perfusion. Labels A through C depict the time points in the sequence at which the three images in the top panels were obtained.

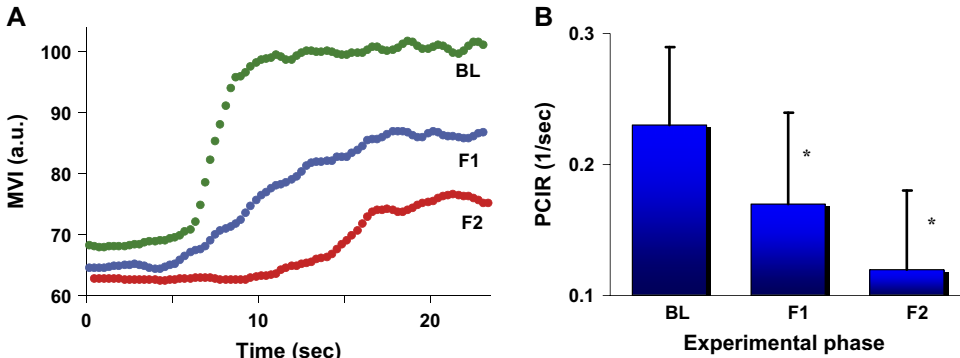


Fig. 6. (A) Myocardial video intensity (MVI) time curves obtained from a 3D slice of an isolated rabbit heart at three levels of coronary flow. BL, baseline; F1, 40% to 60%; F2, 10% to 20% of baseline flow. (B) Average values of myocardial peak contrast inflow rates (PCIR; * $P < .01$ versus BL).

results in a “negative bolus” of contrast [44,49]. We found that in human subjects, the transition from no enhancement to steady-state enhancement occurred within less than 45 seconds, which can be captured in a single data acquisition [44]. Quantitative analysis of image sequences obtained during the replenishment phase of this “bolus” results in peak contrast inflow rate, an index of myocardial perfusion (Fig. 5). This approach was initially tested and optimized with 2D perfusion imaging and was found to be more reproducible, less affected by noise, and more sensitive to changes in myocardial perfusion than the standard analysis of postpulse contrast replenishment using exponential fitting [49]. Subsequently, we used analysis of contrast inflow in conjunction with real-time

3D echocardiographic images, including graded perfusion alterations in an isolated rabbit heart (Fig. 6), localized myocardial ischemia in closed-chest pigs (Fig. 7), and global alterations in myocardial perfusion in humans induced by infusion of adenosine [74].

From fundamental imaging to contrast-targeted modes

Another important recent technological development was the incorporation of harmonic imaging and later power modulation imaging [40] into real-time 3D imaging. Despite the lower spatial resolution, these contrast-targeted modes resulted in incremental improvements in the ability to

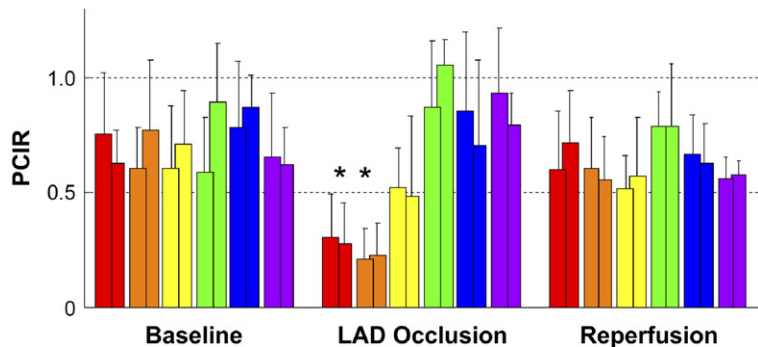
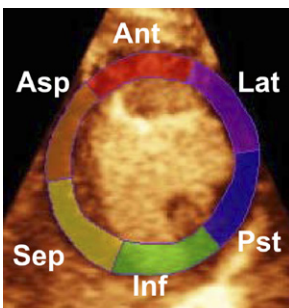


Fig. 7. (Left) En-face view of a short-axis slice of a pig heart with the myocardium divided into six segments. Ant, anterior; Asp, anteroseptal; Inf, inferior; Lat, lateral; Pst, posterior; Sep, septal. (Right) Regional PCIR calculated at baseline, during partial LAD occlusion and reperfusion, averaged over all animals (* $P < .05$ versus baseline). The two bars of each color represent adjacent slices. LAD, left anterior descending coronary artery. (Reproduced from Toledo E, Lang RM, Collins KA, et al. Imaging and quantification of myocardial perfusion using real-time 3D echocardiography. *J Am Coll Cardiol* 2006;47:146–54; with permission. Copyright © 2006, American College of Cardiology Foundation.)

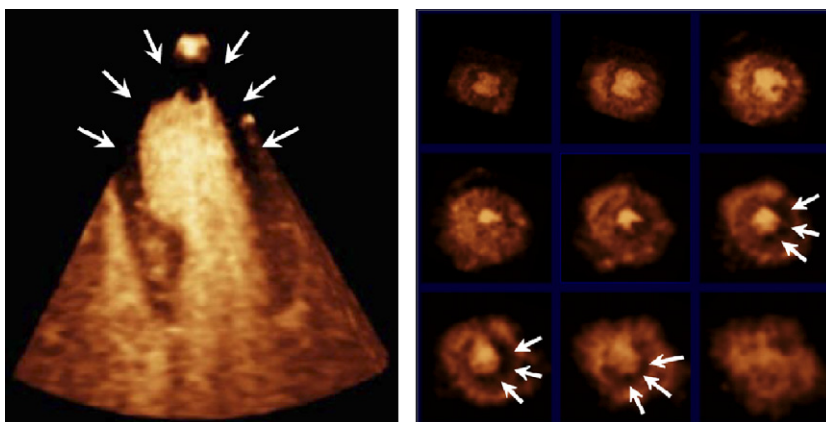


Fig. 8. (Left) RT3DE dataset obtained in a patient with LAD stenosis. Part of the septum lacks contrast enhancement indicating a perfusion defect. (Right) Short-axis slices at different levels of the left ventricle from apex to base extracted from a RT3DE dataset obtained in a patient with 90% stenosis in the proximal left circumflex coronary (LCX) artery. Note the perfusion defect in the LCX territory (arrows).

visualize intramyocardial contrast. The lower temporal resolution, which is an intrinsic property of the multipulse power modulation technique, is not a real limitation in the context of perfusion imaging since only one frame per cardiac cycle is required for perfusion analysis. Our initial experience with the use of this methodology in conjunction with adenosine stress testing in patients with suspected coronary artery disease indicates that it is possible to visualize and quantify myocardial perfusion abnormalities using contrast-enhanced real-time 3D echocardiographic imaging (Fig. 8). We studied a small group of patients with suspected coronary artery disease and found that the presence, location, and severity of perfusion abnormalities detected using this methodology are in agreement with the findings of coronary angiography.

Summary

Real-time 3D echocardiographic imaging allows visualization of myocardial perfusion in any arbitrary slice of the left ventricle and its volumetric quantification using a single contrast maneuver, which is necessary for the assessment of tissue blood flow dynamics. The use of this methodology in humans needs to be validated against accepted techniques for the evaluation of myocardial perfusion, such as positron emission tomography. Its potential clinical value for noninvasive diagnosis of coronary artery disease will need to be established in large groups of

patients undergoing coronary angiography. This methodology may well prove to be a valuable addition to the noninvasive diagnostic cardiac imaging arsenal and become part of the routine cardiology practice.

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Three-Dimensional Echo for the Assessment of Valvular Heart Disease

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Three-dimensional echocardiography (3DE) has been developed during the last 15 to 20 years. Within the last 10 years its clinical value has been proven in many publications around the world [1,2]. The technological improvements in computer speed, transducer technology, and the integration into the ultrasound systems have increased the clinical role of 3DE significantly. Started mainly as a qualitative technology, 3DE more and more has become a precise quantitative tool.

One important application of 3DE is its use for assessing valvular structures [3–5]. Especially in valvular heart disease it is important to understand the complex spatial geometry of the valves [6] and the subvalvular apparatus with its chordae and papillary muscles. Without 3DE, this assessment needs to be done as a kind of mental 3D reconstruction based on 2D echocardiography [2]. 3DE does not require such a mental 3D reconstruction process and is not based on any geometrical assumptions. In addition, it greatly helps to communicate the echocardiographic findings to the cardiac surgeon.

Technical background

The acquisition of 3DE data sets for valvular assessment today is done in two different ways: (1) with 3D TEE multiplane probes using the gating or reconstruction technique or (2) with matrix array transthoracic transducers (TTE) in real time (RT3DE). Both 3DE acquisition methods

are commercially available for several ultrasound systems from various vendors. Recent transducer developments have been done to miniaturize the matrix array real-time transducer into a transesophageal echo (TEE) endoscope (Philips mTEE probe, Andover, Massachusetts) [7].

The 3DE American Society of Echocardiography position paper [1] published in March of this year describes how to assess the valvular morphology in a complete 3DE protocol by acquiring a wide-angle RT3DE data set, starting from a parasternal long-axis view, including RT3DE color interrogation of the aortic, mitral, tricuspid, and pulmonary valve. In addition, another RT3DE data set starting from an apical four-chamber window for the aortic, mitral, and tricuspid valve shall be acquired.

Although RT3DE can provide a real-time 3D reconstruction or display of the beating heart and its valvular structures during the acquisition, 3DTEE based on the gating technique first needs to complete the acquisition process. The average reported acquisition time ranges from 3 to 8 minutes. After that, the 3D reconstruction, display, manipulation, and quantification tools are more or less identical. To visualize an inner structure of the heart like the mitral valve in three dimensions, the heart needs to be sliced or unroofed with a cut plane. Unique en face views of a valve from above (looking down from the atrium like surgical views) and below (looking up from the apex) can be generated in real time (Fig. 1). Besides such 3D displays, oblique cut planes (anyplane echocardiography [8]) or so-called MPRs (multiplanar reconstructions) can be generated easily. For example three different cut planes, a sagittal (corresponds to a long axis view), a coronal (four-chamber view), and a

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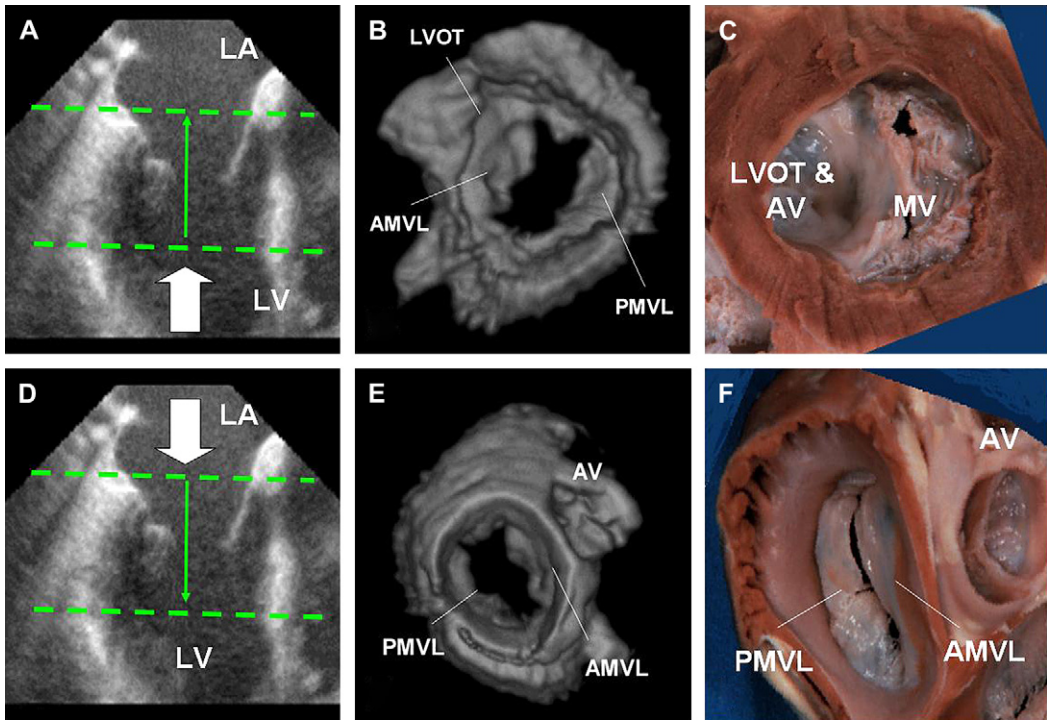


Fig. 1. Assessment of anatomical structures in volume-rendered images requires a proper 3D view adjustment. (A, D) The surgical view of the mitral valve (white arrows) can be defined in 2D images (multiplanar reconstructions) with two clicks only (D↑ art). The results of this view adjustment are shown in B and E. (C, F) The corresponding en face views of a human mitral valve. Abbreviations: AMVL, anterior mitral valve leaflet; AV, aortic valve; LA, left atrium; LVOT, left ventricular outflow tract; LV, left ventricle; MPR, multiplanar reconstruction; PMVL, posterior mitral valve leaflet. (Courtesy of N. Pandian, MD, Boston, MA.)

transverse plane (short axis view) [1] can be displayed side by side in real time.

Morphological and quantitative valve assessment

3DE greatly improved the assessment and understanding of valvular anatomy and function [6]. It can provide a detailed en face visualization of valve structures [9] like leaflet scallops, prolapses, or commissures for example for a better preoperative assessment. Fig. 2A shows a 3DE en face view from the left atrium to the mitral valve (MV), clearly depicting a prolapse. Fig. 2B shows the same MV and the prolapse in a side view.

Mitral valve assessment

The MV can be acquired in a 3DE data set with the 3DTEE or RT3DE approach. For RT3DE, a parasternal or apical window shall be used. The anterior leaflet can be visualized best

from a parasternal long-axis position. As the posterior leaflet has a much smaller excursion compared with the anterior leaflet, it is sometimes more challenging to visualize. Then, an apical four-chamber position is preferable [10].

The imaging of the MV and various pathologies is feasible in most patients [6]. RT3DE gives additional information in the assessment of MV prolapse [11], flail leaflets, mitral stenosis, cleft mitral valves, and MV perforation. It helps to increase diagnostic confidence and to plan the surgical approach (MV repair or replacement) [3,9].

Based on the acquired and digitally stored 3DTEE or RT3DE data set, the MV can be assessed in a qualitative and quantitative way using dedicated MV analysis software tools like 4D MV-Assessment (TomTec Imaging Systems, Unterschleissheim, Germany). Such tools support in particular the interdisciplinary communication between cardiac surgeons and cardiologists/anesthesiologists.

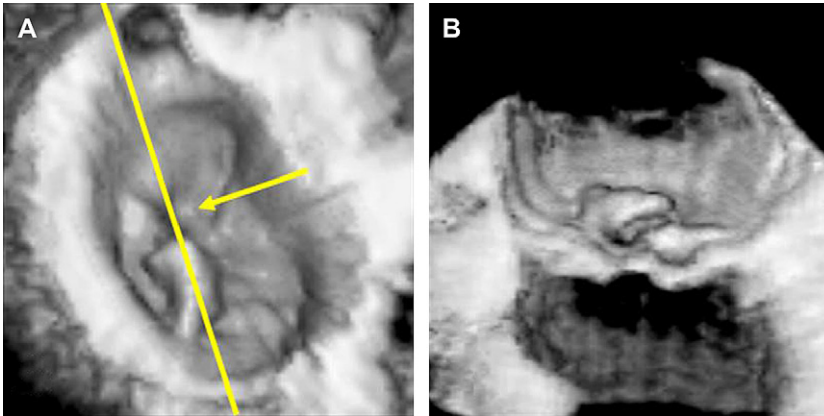


Fig. 2. Morphological assessment of mitral valve with 3D echocardiography. (A, B) A transesophageal 3D reconstruction of prolapsed mitral valve. The spatial location and shape of the prolapse can be assessed in the surgical (A) and side view (B). (Courtesy of A. Franke, MD, Aachen, Germany.)

Fig. 3A shows a 3DTEE en face view or so-called surgical view from the atrium to the MV with the aortic valve (AoV) at 12 o'clock position. The software outlines the MV annulus, which is displayed as an overlay contour (Fig. 3B). In addition it extracts the MV coaptation line from the anteriolateral to the posteriomedial commissure and is labeling the three anterior and posterior mitral leaflet segments (A1, A2, A3, P1, P2, P3). Fig. 4A shows a surgical view of a prolapsed (A2, A3) mitral valve. The white line represents

the MPR shown in Fig. 4B. Leaflets can be segmented (turquoise line) in reconstructed 2D views (see Fig. 4B) and visualized together with anatomical structures in three dimensions (Fig. 4C). In Fig. 5, 3DE color flow information is displayed additionally. Here a simultaneous side-by-side display of three reconstructed cut planes (MPRs) (see Fig. 5A, C, D) and the 3D en face reconstruction (see Fig. 5B) is shown. By cropping the 3D color flow display of the regurgitant jet slightly above the level of the vena contracta, the relationship

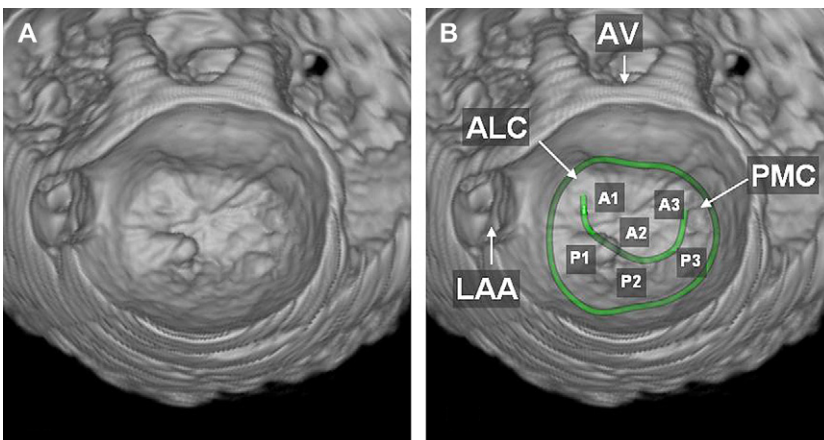


Fig. 3. (A) Transesophageal 3D reconstruction of a prolapsed (P1) mitral valve. (B) The morphological assessment can be simplified by visualizing the mitral valve annulus and the coaptation line into the volume-rendered image (TomTec 4D MV-Assessment CAP, TomTec Imaging Systems, Unterschleissheim, Germany). (B) The major anatomical structures can be labeled automatically if required. *Abbreviations:* ALC, anteriolateral commissure; AoV, aortic valve; LAA, left atrial appendage; PMC, posteriomedial commissure. A1-A3 and P1-P3 refer to the three scallops of the anterior (A) and posterior (P) leaflet.

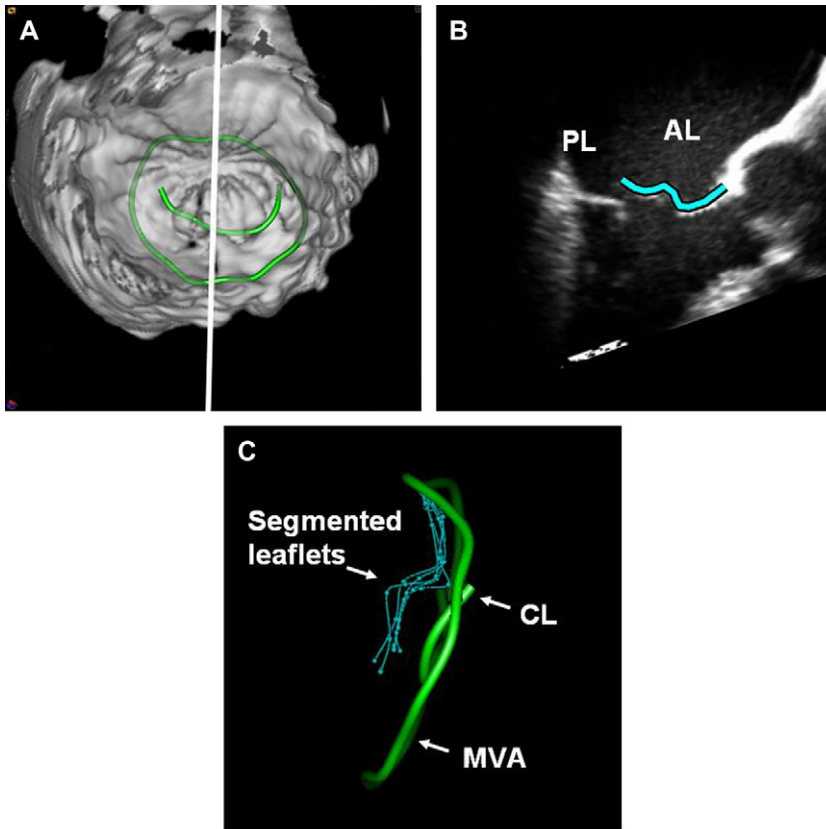


Fig. 4. (A) A surgical view of a prolapsed (A2, A3) mitral valve. The white line represents the multiplanar reconstruction (B). Leaflets can be segmented (turquoise line) in reconstructed 2D views (B) and visualized together with anatomical structures in three dimensions (C). Abbreviations: AL, anterior leaflet; CL, coaptation line; MVA, mitral valve annulus; PL, posterior leaflet (4D MV-Assessment CAP, TomTec Imaging Systems, Unterschleissheim, Germany).

of the jet origin to the valve closure line can be visualized (see Fig. 5B), and the jet origin area can be quantified. In Fig. 6A, a transesophageal 3D reconstruction of MV regurgitation is shown. The relationship between the regurgitant jet, MV annulus, and coaptation line is visualized in Fig. 6B. The jet at the level of the mitral valve is shown in Fig. 6C, allowing easy assessment of its exact spatial location. Fig. 7A shows a mitral valve regurgitation caused by P2 flail. As shown in Fig. 7B, the exact jet origin, size (turquoise line), and the prolapsed area (yellow) are measured.

Global and regional annular ring and coaptation line geometry can be calculated automatically. Fig. 8A, B shows a schematic view of global MV annulus measurements. Fig. 8C displays a selection of automatically generated MV annulus parameters.

Advanced 3D analysis technology allows such segmentation and quantification of MV annulus,

leaflets, and subvalvular apparatus. Tenting area, tenting height, and papillary muscle geometry are visualized in Fig. 9A. Fig. 9B shows the aorto-mitral relationship. Fig. 10 shows the analysis of the displacement (longitudinal motion) of the MV and the valve surface area change over one heart cycle.

Mitral valve prolapse

As shown in Figs. 2–7, a MV prolapse can be visualized and quantified with 3DE [12–18]. Such preoperative assessment of the MV morphology is very important to plan the surgical approach (MV repair is preferable to MV replacement [19]). Here 3D has big advantages compared with 2D echocardiography [20] in the communication with the cardiac surgeon describing which scallops are involved or are prolapsing.

Mitral regurgitation

Accurate quantitative grading of mitral regurgitation (MR) is a powerful predictor of the

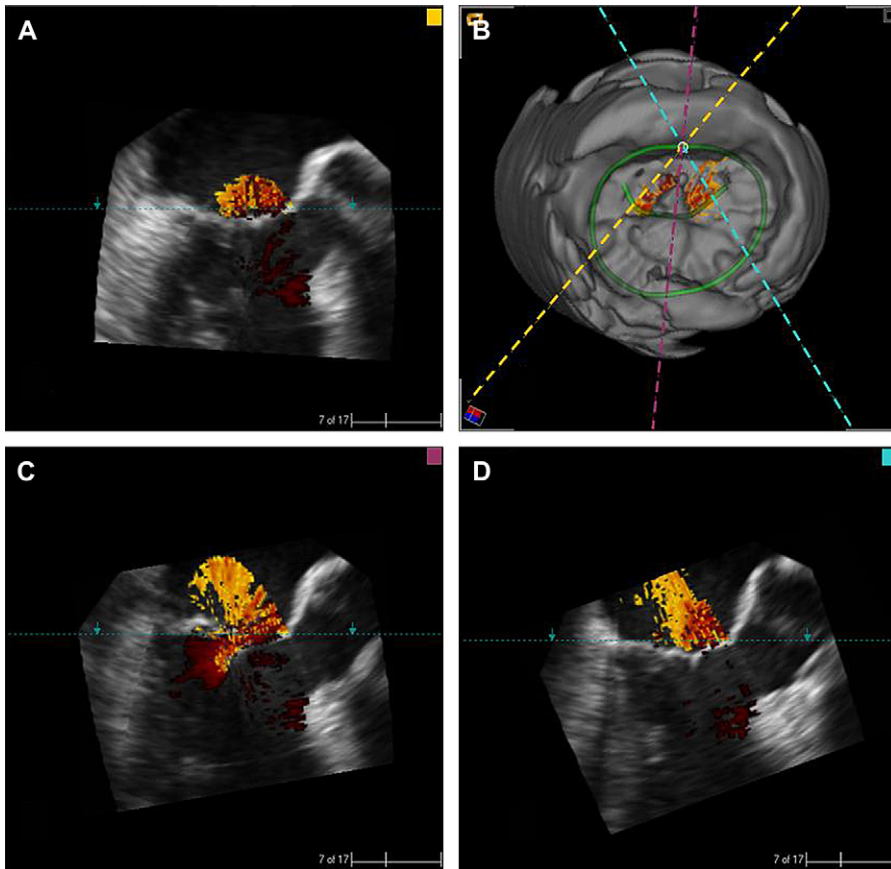


Fig. 5. The simultaneous side-by-side display of three reconstructed cut planes (multiplanar reconstructions) (*A*, *C*, *D*), and the 3D en face reconstruction (*B*) simplifies the morphological assessment of the mitral valve (TomTec 4D MV-Assessment CAP, TomTec Imaging Systems, Unterschleissheim, Germany).

clinical outcome of MR [21]. It would be desirable to precisely quantify the regurgitant flow volume per beat and the effective regurgitant orifice. This is difficult, however, using conventional color Doppler and 2D echocardiography techniques [22]. The addition of color flow to 3DE has provided improved visualization of regurgitant lesions and has the potential to play an increasing role to better quantify MR [23–25]; however, the temporal resolution of 3DE color flow still needs to be enhanced. 3DE can give new insights into the geometry of MR, which can lead to a better surgical strategy planning. It is particularly useful in patients who have multiple or eccentric jets. Fig. 11 shows a patient who had severe MR and presented with heart failure after MV repair. On 2D TEE, there is an echo density at the level of the MV annulus (see Fig. 11A), and on color flow Doppler (see Fig. 11B) there is severe MR,

so that it is difficult to differentiate whether there is valvular or para-ring regurgitation. Using a TEE rotational approach (3DE TEE), a 3D reconstruction of the valve demonstrated dehiscence of the anterior portion of the MV ring (see Fig. 11C) and severe mitral valvular and para-ring regurgitation (see Fig. 11D).

In case of dilated left ventricles (LV) and ischemic cardiomyopathy, MR usually results from a dilatation of the mitral annulus and papillary muscle displacement and tethering of the mitral leaflets, leading to incomplete closure of the leaflets [1]. Here a 3DE-based analysis of the mitral annulus and its motion throughout the cardiac cycle is a promising new approach (see Fig. 10) to better understand MR mechanisms [26].

As 3DE is not based on any geometric assumptions, it can overcome the limitations of the

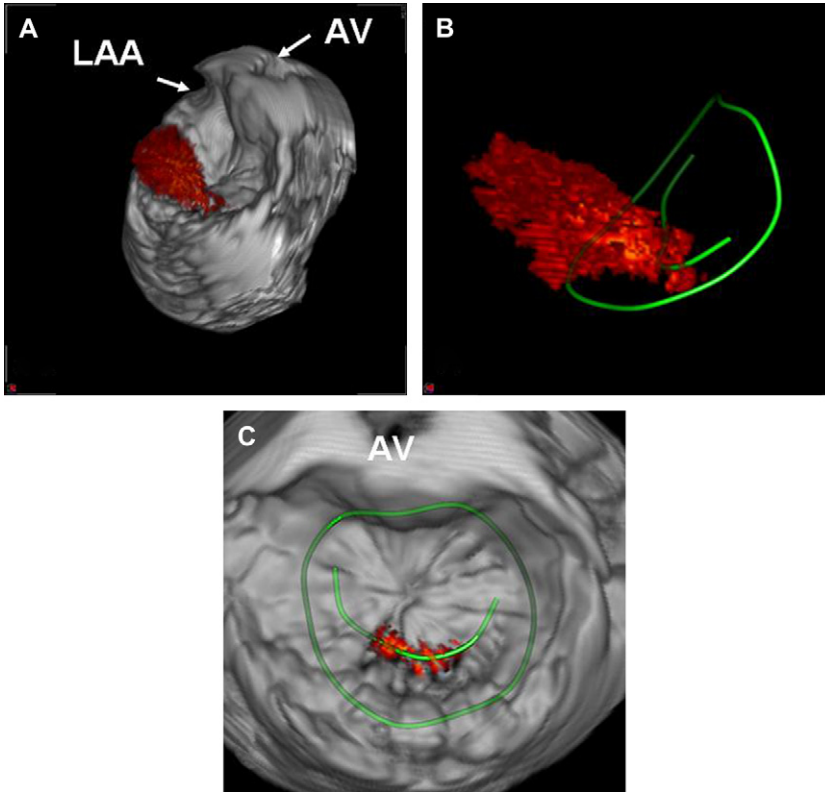


Fig. 6. (A) Transesophageal 3D reconstruction of mitral valve regurgitation. The relationship between regurgitant jet, mitral valve annulus, and coaptation line are visualized (B). The jet at the level of the mitral valve is shown (C), allowing easy assessment of its exact spatial location (4D MV-Assessment CAP, TomTec Imaging Systems, Unterschleissheim, Germany). *Abbreviations:* AoV, aortic valve; LAA, left atrial appendage.

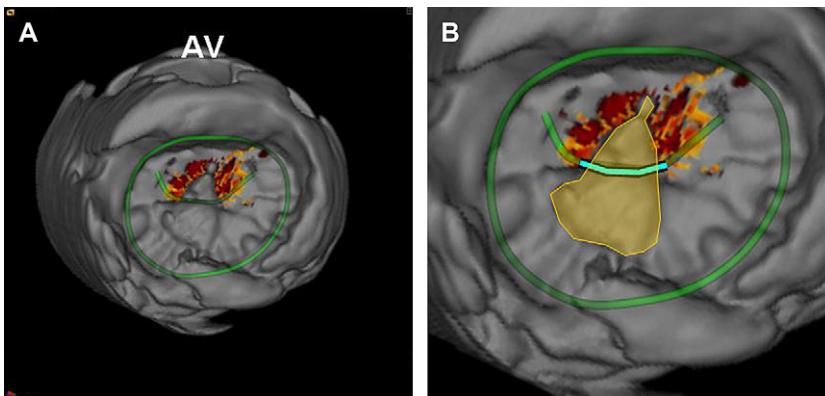


Fig. 7. (A) Mitral valve regurgitation caused by P2 flail. (B) The exact jet origin, size (*turquoise line*), and the prolapsed area (*yellow*) are measured: Jet size = 1.6 cm; Prolapsed area = 3.2 cm². *Abbreviation:* AoV, aortic valve (4D MV-Assessment CAP, TomTec Imaging Systems, Unterschleissheim, Germany).

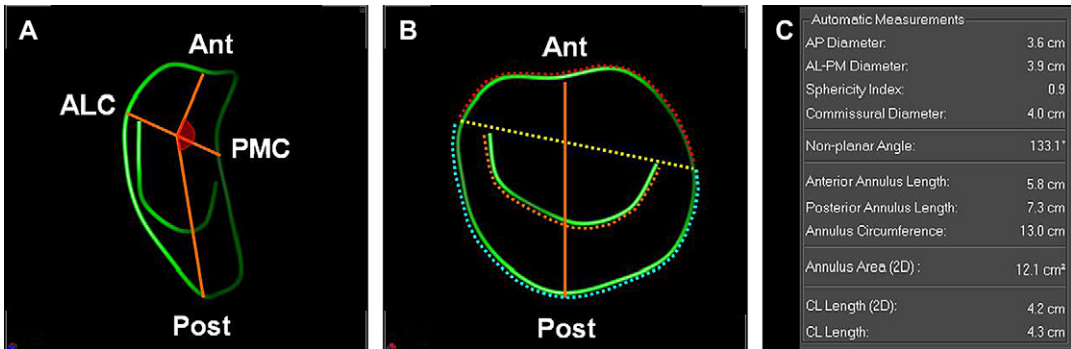


Fig. 8. Global and regional annular ring and coaptation line geometry can be calculated automatically. (A, B) A schematic view of global mitral valve (MV) annulus measurements. (C) A selection of MV annulus parameters. *Abbreviations:* ALC, anteriolateral commissure; Ant, anterior; PMC, posteromedial commissure; Post, posterior (TomTec 4D MV-Assessment CAP, TomTec Imaging Systems, Unterschleissheim, Germany).

2D echocardiography-based proximal isovelocity surface area (PISA) method, which is assuming a perfect hemisphere for the quantification of mitral regurgitation. 3DE can address the real geometry and area of the isovelocity surface [27]. Iwakura and colleagues [28] published a comparison of the mitral orifice area measured by transthoracic 3D Doppler echocardiography versus the 2D echocardiography-based PISA method for assessing MR.

Khanna and colleagues [29] demonstrated the quantification of MR by live 3D transthoracic echocardiographic measurements of vena contracta area.

Mitral valve stenosis

Several studies have demonstrated the utility of 3DE for assessing the severity of mitral stenosis. Sugeng and colleagues [30] validated the accuracy of mitral valve area measurements in comparison with noninvasive 2DE and invasive hemodynamic methods. Zamorano and colleagues published a comparable study based on RT3DE stating that the 3D assessment of the MV area had an excellent correlation with the invasive determined area [31,32]. Fig. 12 is an example of the quantification of the MV orifice in a stenotic MV, before (see Fig. 12A) and after balloon valvuloplasty (see Fig. 12B).

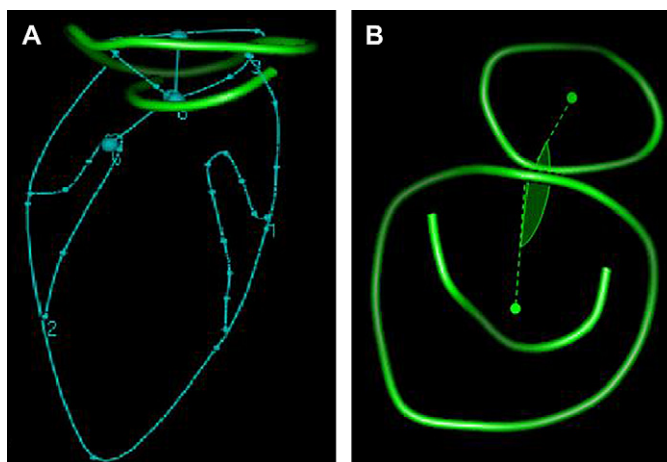


Fig. 9. Advanced 3D analysis technology allows segmentation and quantification of mitral valve annulus, leaflets, and subvalvular apparatus (TomTec 4D MV-Assessment CAP, TomTec Imaging Systems, Unterschleissheim, Germany). (A) Tenting area, tenting height, and papillary muscle geometry are visualized. (B) The aorto-mitral relationship.

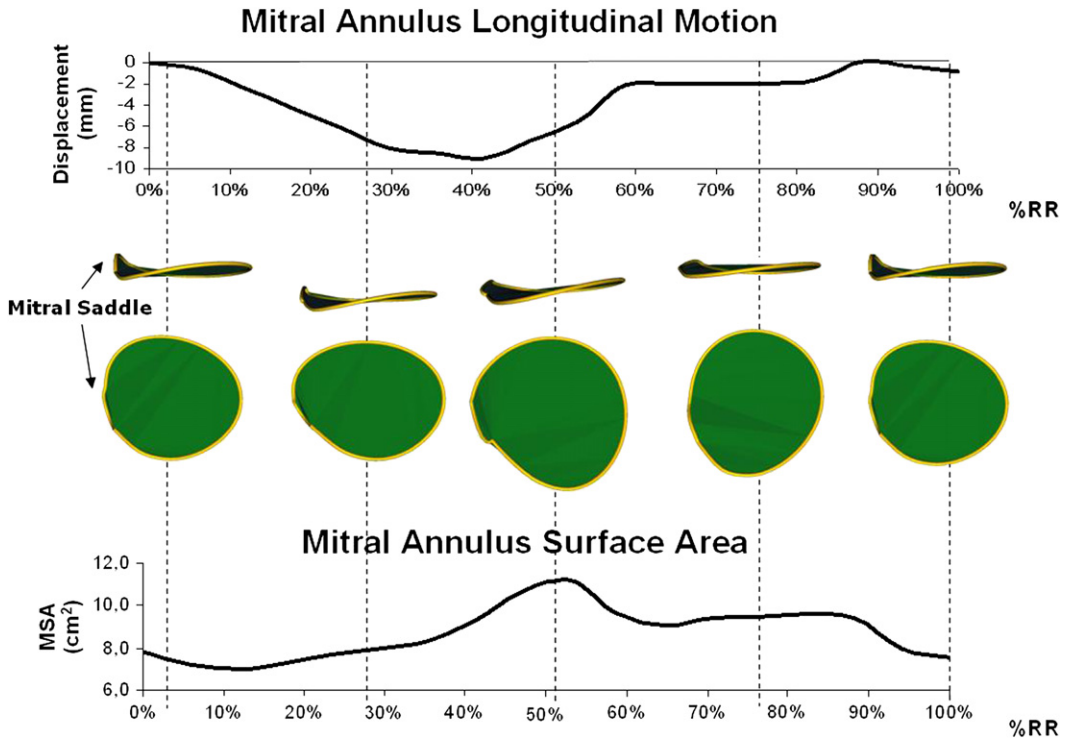


Fig. 10. Numerous parameters can be derived by dynamic annulus analysis. This image shows the dynamic changes in mitral valve longitudinal motion and annulus surface area. (Courtesy of L. Sugang, MD and R. Lang, MD, Chicago, IL.)

Aortic valve assessment

To examine the AoV with RT3DE, a high right or left parasternal approach gives the best results [10]. The apical window is another option but has the AoV positioned in the far field. For a complete valvular assessment, the AoV becomes more and more important. Studies have shown that 3DE improves the morphological assessment of the AoV leaflets, the quantification of the valve orifice area in aortic stenosis, and the quantification of aortic regurgitation. Fig. 13 shows a 3D long-axis view of the aortic valve. Fig. 14 shows a quadricuspid AoV from aortic perspective (see Fig. 14A) and in a 3D long-axis view (see Fig. 14B). The noncoronary cusp (NCC) is marked with a red dot. Fig. 15 shows an aortic valve sclerosis case. Fig. 15A demonstrates the aortic valve seen from an aortic perspective looking down on a sclerosed aortic valve in diastole (see Fig. 15A) and in systole (see Fig. 15B).

Limitations of 3DE for assessing the AoV are the temporal resolution of 3DE. Handke and colleagues [33] evaluated a 3DE prototype solution for a very high temporal resolution to study

the mitral and aortic valve. Especially the rapid AoV opening phase could be analysed in three dimensions with such a high frame rate of more than 160 frames per second. This study could show how AoV movement is influenced by myocardial and valvular factors.

Tricuspid valve and pulmonary valve assessment

Compared with the MV and AoV, much less work has been published to study the tricuspid valve (TV) and pulmonary valve (PV) with 3DE techniques. In order to acquire a RT3DE data set of the TV, it is recommended to use more gain than normal [10] while positioning the RT3DE transducer in a modified parasternal long axis position, centering the TV in the 3D volume. From an apical four-chamber view, the TV can be visualized in relation to other intracardiac structures. Thus RT3DE allows the visualization of all three TV leaflets, their attachment in the TV annulus, and their relation with the interventricular septum [10]. 3DE also can provide an accurate visualization of the TV from a surgical viewpoint from

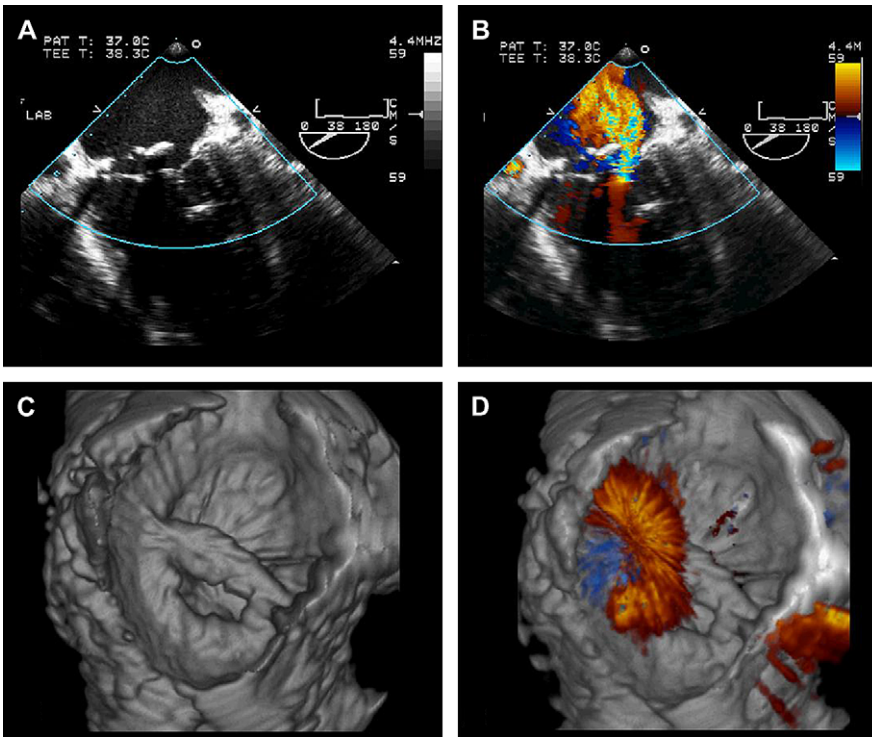


Fig. 11. Patient with severe mitral regurgitation and presented with heart failure after mitral valve repair. On transesophageal echo (TEE) there is an echo density at the level of the mitral valve annulus (A), and on color flow Doppler (B) there is severe mitral regurgitation, so that it is difficult to differentiate whether there is valvular or para-ring regurgitation. Using a TEE rotational approach, a 3D reconstruction of the valve demonstrated dehiscence of the anterior portion of the mitral valve ring (C), severe mitral regurgitation that is valvular, and para-ring regurgitation (D). (Courtesy of L. Sugang, MD, and R. Lang, MD, Chicago, IL.)

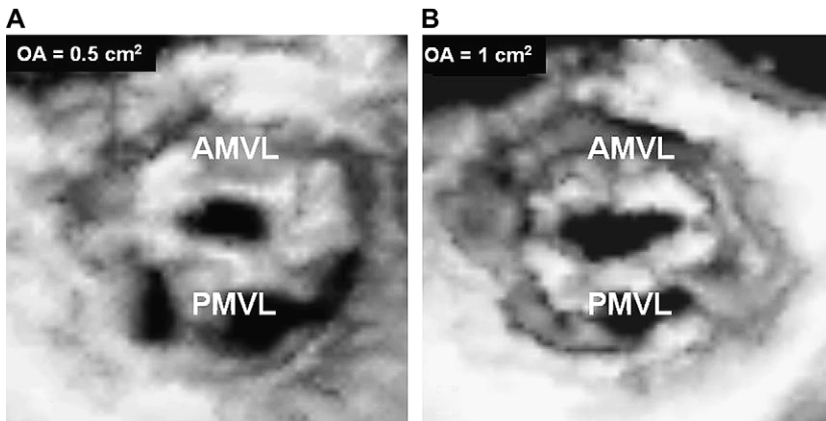


Fig. 12. Patient with mitral stenosis before (A) and after (B) balloon valvuloplasty. Abbreviations: AMVL, anterior mitral valve leaflet; OA, orifice area; PMVL, posterior mitral valve leaflet. (Courtesy of L. Sugang, MD, and R. Lang, MD, Chicago, IL.)

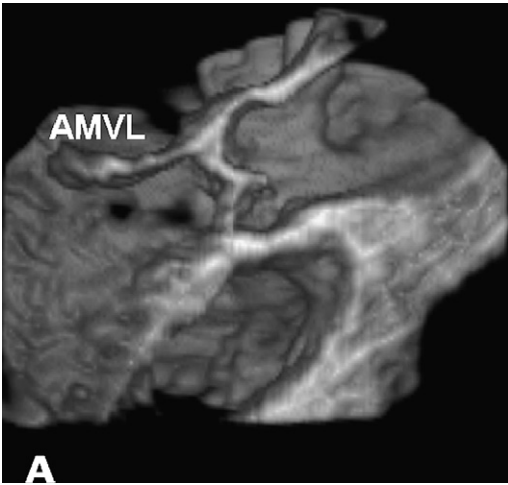


Fig. 13. (A) A side view (3D long-axis view) of the aortic valve. *Abbreviation:* AMVL, anterior mitral valve leaflet. (Courtesy of N. Nanda, MD, Birmingham, AL.)

the right atrium to help in the surgical decision-making process [4].

In a recent publication, Masaki and colleagues [34] studied the tricuspid annular function and dynamics in children who had RT3DE acquired from an apical view. The authors studied the interaction between the TV and the MV and reported the interplay between the TV annulus and its supporting tension apparatus.

The PV can be acquired and visualized from two parasternal positions, first from a modified parasternal short axis, and second from a modified parasternal long-axis view [10]. In 3DE, the visualization of PV leaflet details can be limited.

A better visualization is achieved if the PV is thickened or calcified.

Future outlook

Because 3DE provides unique tools to assess valves preoperatively, it will play an important role in surgical planning in the future. Valve annulus size, shape, and dynamic changes can be determined accurately, and the patient's individual case can be considered in the treatment by developing and providing customized implants. Models of customized implants can be implanted virtually with the help of 3DE data sets to simulate the outcome of the surgery (Fig. 16B). Fig. 16A shows the coronary sinus (CS) together with mitral valve annulus and coaptation line. Future 3D color Doppler technologies may allow quantifying the regurgitation volume (Fig. 16C).

Most of the work for the assessment of valve geometry and function so far has been done for the mitral valve. 3DE enables the collection of completely new parameters describing the valve. Several parameters have been established to describe the mitral annulus geometry and its changes during the cardiac cycle (see Fig. 10). 3DE also has the potential to assess the closing pattern of the leaflets and performed measurements like tenting volume, which has been described by Watanabe and colleagues [33,35]. Because valve pathologies are extremely complex, it is necessary to address the whole valve apparatus, like for the MV, the annulus, the leaflets, the chordae length, and the positioning of the papillary muscles, being influenced by myocardial conditions. 3DE greatly

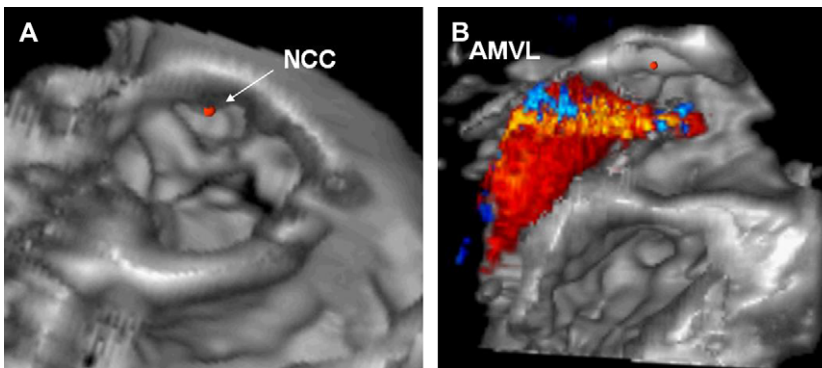


Fig. 14. The same quadricuspid aortic valve from aortic perspective (A) and in 3D long-axis view (B). The noncoronary cusp (NCC) is marked with a red dot. *Abbreviation:* AMVL, anterior mitral valve leaflet.

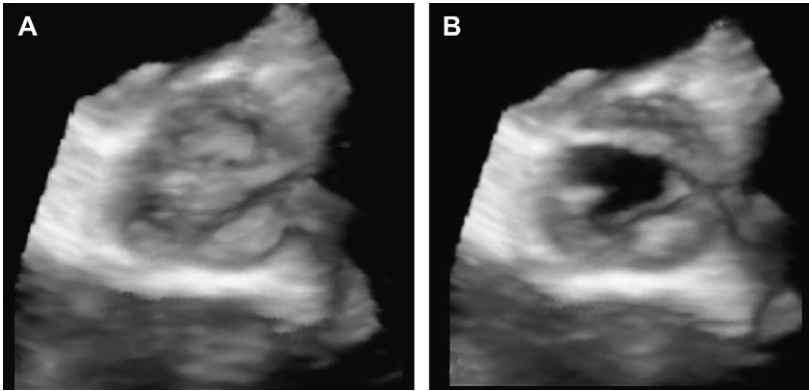


Fig. 15. Aortic valve sclerosis. The aortic valve seen from an aortic perspective looking down on a sclerosed aortic valve in diastole (A) and in systole (B). (Courtesy of L. Sugang, MD, and R. Lang, MD, Chicago, IL.)

improves the understanding of the interaction of those components and therefore leads to a more complete picture of the pathology and to a more profound choice of treatment.

With the improvement of spatial and temporal resolution of 3D color Doppler, the assessment of regurgitations of valves also will enter a new dimension. The current geometric

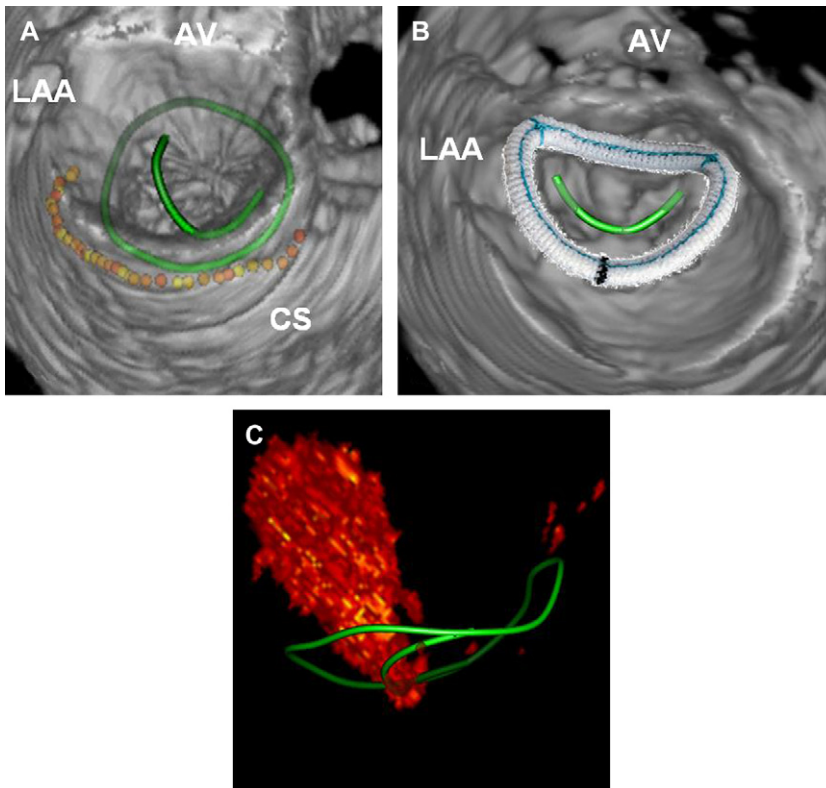


Fig. 16. (A) The coronary sinus (CS) together with mitral valve annulus and coaptation line (4D MV-Assessment CAP, TomTec Imaging Systems, Unterschleissheim, Germany). Visualizing the ring into the volume-rendered image (B) may help to assess the correct ring size preoperatively. Future 3D color Doppler technologies may allow quantifying the regurgitation volume (C).

assumptions for all 2D methods to quantify flow based on color Doppler like the hemispherical surface in the PISA method are not required with 3DE. In 3DE, the flow can be examined in its true dimensions, which will improve understanding and accuracy of the measurements.

Although surgical planning will be one important application of 3DE before treatment, guiding the procedure itself is becoming increasingly important. RT3DE is an ideal tool for offering visual feedback during the procedure, especially with percutaneous interventions like valvuloplasty or minimally invasive aortic valve replacements. This new way of guiding will help to reduce procedure time and will improve the efficiency, quality, and safety of the treatment.

With 3DE overcoming the current limitations of 2D echocardiography, it might change the workflow in laboratories for many applications that do not have to be performed in real time. The ability to reslice a volume offline will transfer a substantial part of the work currently done on the ultrasound system to offline review workstations. Automatic slicing algorithms will display predefined slices of the heart derived from the 3DE data set, but in doubtful cases, the physician still has the option to virtually rescan the patient and generate any 2D slice or 3D view of the structures acquired in the 3DE data volume. Also, physicians from remote places can have access to such a virtual rescan and deliver a second opinion, which makes telemedicine a more realistic scenario rather than just exchanging images and clips.

Summary

3DE is a valuable tool to be used in addition to and not instead of 2D echocardiography by providing complementary information and improved quantitative accuracy and reproducibility compared with 2D techniques [1]. More and more, ultrasound systems will be equipped with a 3DE option. By overcoming the current limitations like the lower temporal resolution, compared with 2D echocardiography, 3DE has the potential to become the standard echocardiographic examination procedure for the assessment of valvular disease.

Acknowledgment

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Current Status of Three-Dimensional Color Flow Doppler

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The first effort to image intracardiac flow in three dimensions to obtain gray-scale reconstructions of jets was performed using a transthoracic sequential multiplanar–rotational gated acquisition. Acquisition of color information from 2D echocardiography images was not possible at the time, resulting in the inability to separate tissue from intracardiac flow [1]. Nevertheless, it permitted visualization of flow convergence zones that set in motion other studies to observe the effects of orifice shape, impact of the geometry of the regurgitant orifice, and enable the validation of 3D echocardiography (3DE) as a more accurate method to estimate the vena contracta area [2–5].

Method of 3D color-flow acquisition

A 3D volume of a color-flow jet was acquired from the transthoracic or transesophageal approach using a rotational gated sequential acquisition method (Fig. 1A). The transthoracic approach required a commercially available transducer to be inserted into a cylindrical device that mechanically rotated the probe. From the transesophageal approach, the image sector was rotated electronically. When using the latter approach, the regurgitant jet was positioned in the middle of the sector. Sequential 2D color-flow images were collected from a single window every 3° to 5° over a 180° rotation gated to the patient's

electrocardiogram and respiration (end exhalation). Images were stored on a disc and subsequently processed on an off-line computer. These images were reformatted in time and space to produce a Cartesian volume data set. Further manipulation of this data usually was performed using special software to allow volume, surface, or wire frame display and quantitation of regurgitant volume. This technique is limited because of the multiple cardiac cycles that need to be acquired to obtain a volume data set. This introduces radial artifacts if the transesophageal echocardiography (TEE) probe moves during data acquisition because of respiration or peristaltic motion. On the other hand, this approach allowed simultaneous data collection and reconstruction of color flow data superimposed on valve leaflet and chamber structures. Another mode of acquisition used in early investigational studies of 3D color flow was a free-hand method (Fig. 1B) using a magnetic sensor and transmitter that was attached to the probe. Multiple images were obtained from a single window in a fan-like manner gated to ECG and respiration. Images were reformatted and analyzed on an off-line computer.

With the advent of a fully-sampled matrix array transducer (Fig. 1C), the number of cardiac cycles required to acquire a color-flow data set was reduced. Data collection necessitated ECG gating and a breath hold by the patient, which reduced the incidence of artifact. Although frame rates are higher using this method, the sector size is narrower along with restricted visualization of the regurgitant volume and surrounding valve leaflets.

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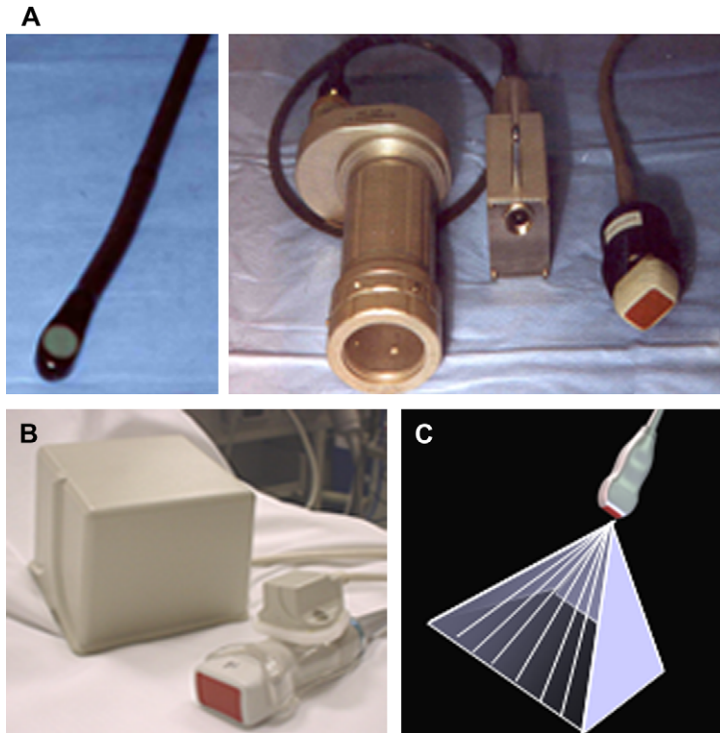


Fig. 1. Acquisition methods. (A) Rotational gated sequential acquisition method using a transesophageal probe or transthoracic transducer coupled in a mechanical rotational device. (B) Free-hand method using magnetic sensor and transmitter. (C) Fully-sampled matrix array transducer acquires a pyramidal volume data set consisting of seven subvolumes for color acquisition.

Regurgitant jets and shunts

Early 3D reconstructions of jets were feasible using a rotational gated sequential method of acquisition using a transthoracic probe coupled with a motorized device. These images provided in still-frame or in a dynamic format an appreciation of the shape, its relative location and size relative to the cardiac chamber, and the jet shape of the flow convergence surface over the regurgitant orifice [1]. With the ability to visualize 3D reconstructions of flow convergence, subsequent studies focused on the quantitation of regurgitant orifice areas and regurgitant volumes derived from 3DE data sets. As the regurgitant orifice shapes are noncircular along with wall-hugging jets, 2D echocardiography easily underestimates the orifice size (35% to 44%) and regurgitant flow (22% to 32%) [6]. These findings also were demonstrated in animal models of aortic regurgitation, confirming that 3DE was more accurate in the estimation of regurgitant orifice area, regurgitant volumes,

and vena contracta [2,7,8]. Similarly, this approach also was applied to pulmonary regurgitant jets to estimate volumes, which agreed well with the reference standard [4]. Most of these studies demonstrating regurgitant jets and flow convergence were derived from video composite data, which have the same variability as 2D color Doppler flow mapping such as gain settings, wall filtering, and aliasing velocities. During this development period, 3D reconstruction of regurgitant jets was also in gray-scale map without velocity information. Differentiation between flow and anatomy were not possible at this time.

3D reconstruction displaying color flow first was demonstrated in patients who had mitral regurgitation (MR) (Fig. 2) [9,10]. 3D mitral regurgitant jets, acquired using a gated sequential rotational TEE approach, were processed off line using the Heidelberg ray tracing method, which enabled display of 3D color flow while simultaneously allowing quantitation of jet volumes [11]. Qualitatively, these reconstructed images of MR

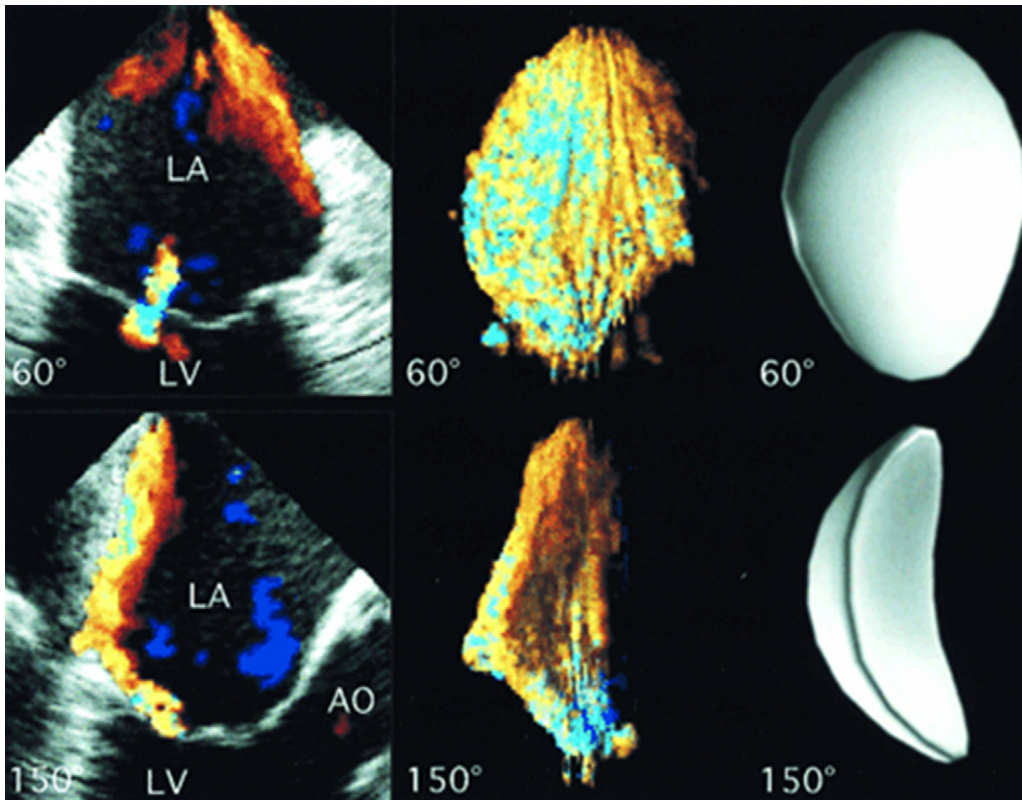


Fig. 2. Mitral regurgitation jet with a spoon pattern in a patient with anterior prolapse. Visualization of the jet in two dimensions at 600 and 1500 only demonstrates portion of the jet (left, top, and bottom panels). 3D reconstructions, using the Heidelberg Ray tracing method enables display of 3D color flow (middle panels) and surface-rendered images (right, top, and bottom panels). (From De Simone R, Glombitza G, Vahl CF, et al. 3D color Doppler: a clinical study in patients with mitral regurgitation. *J Am Coll Cardiol* 1999;33:1646–54; with permission.)

aid in demonstrating jets in three dimensions rather than with mental conceptualization using multiple 2D views. The direction of the jet, extent, and geometry were recognized using this 3DE technique. Besides having a display of jet geometry, the more significant strength of this methodology lies in its ability to quantitate. When 3D jet volumes were compared with 2D quantitative methods for MR (continuity method for regurgitant volume and fraction and jet area), 3D jet volume had a better correlation compared with 2D methods using angiography as the reference standard. In addition, 3D jet volumes of eccentric jets were significantly larger compared with calculated 2D methods. One may conclude that 3DE correctly identifies severe mitral regurgitation when 2D methods underestimate severity, particularly when using the jet area calculation, and

to a lesser degree if the regurgitant volume formula is used [11,12]. Nevertheless, there are limitations to the previous 3D methods that are not real-time; the jet size is dependent on gain settings, velocity scale, frame rate, and filters, and a transesophageal approach was required in a controlled setting (under general anesthesia). Moreover, comparison of 2D jet volumes with more current 2D quantitative method such as flow convergence was not used and angiography, as the gold standard has its own set of limitations for assessing MR. The absence of gray-scale information such as the valve morphology and left atrial chamber also provided an incomplete demonstration of the relation of the jet to cardiac anatomy.

The ability to incorporate both color-flow data and gray-scale information has enabled the

quantitation of MR severity using 3DE by visualizing the vena contracta, measuring the proximal isovelocity surface area (PISA) radius, or estimating tricuspid or mitral regurgitant volume relative to the atrial chambers. In an in vitro setting, 3D quantitation of flow-convergent zones are more accurate (2.6% underestimation) compared with 2D or M-mode methods, which underestimate regurgitant volumes (44.2% and 32.1%, respectively) [13]. Recent development of a fully sampled matrix array probe allows color-flow Doppler and gray-scale information to be acquired simultaneously over seven cardiac cycles (Fig. 3A, B). When comparing 3D derived vena contracta (Fig. 3C) measurements for tricuspid regurgitation (TR) jets, the minimum diameter measurements were similar to 2D measurements but in an orthogonal view. The maximum diameters were larger in three dimensions compared with two dimensions. Whereas for mitral regurgitant flow, 3D derived maximum and minimum vena contracta measurements were significantly larger than 2D measurements but more circular/oval than TR vena contractas,

which appear more elliptical in shape [14]. Similarly, a comparison of 3D derived vena contracta area to MR angiography demonstrated a better agreement for quantitative assessment of MR than 2D derived vena contracta width and jet/left atrial (LA) area ratio to estimate the severity of MR. When comparing 3D MR jet/LA volume ratios and TR jet/right atrial volume ratios with 2D MR jet/LA area and 2D TR jet/right atrial area ratios, 3D ratios were significantly smaller than 2D ratios (Fig. 4D). This could be explained by the larger atria volumes, low frame rates in 3D imaging, poor delineation of the jet, and averaging of high velocity flow leading to smaller 3D jet volumes [15].

Assessment of function

Measurements of stroke volume (SV) and cardiac output (CO) using the Thermodilution method are useful for serial hemodynamic monitoring. This methodology requires an invasive procedure that may result in complications while

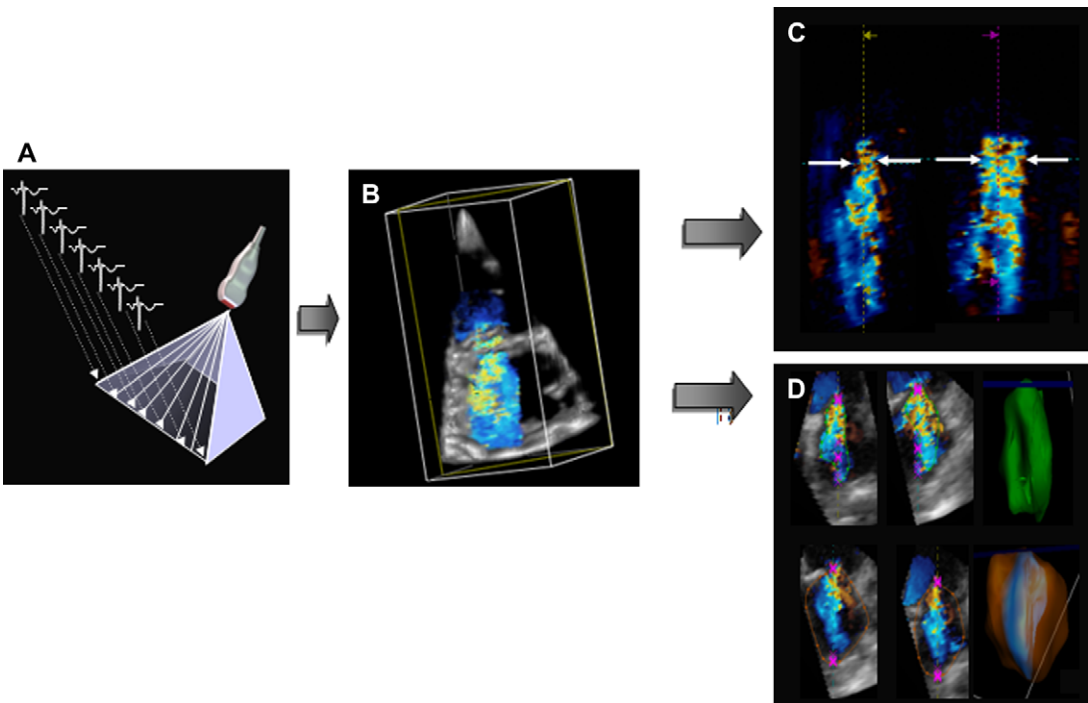


Fig. 3. (A) A fully sampled matrix-array transducer acquires seven subvolumes gated to ECG, resulting in a pyramidal data set and displayed as a 3D image of mitral regurgitation (B). A 3D jet is shown in two orthogonal planes showing the minimum and maximum vena contracta width (C). A 3D mitral regurgitant jet along with the entire left atrium is traced to derive a jet/left atrial volume ratio. (D) The jet is viewed with a transparent left atrial cast on the bottom right image.

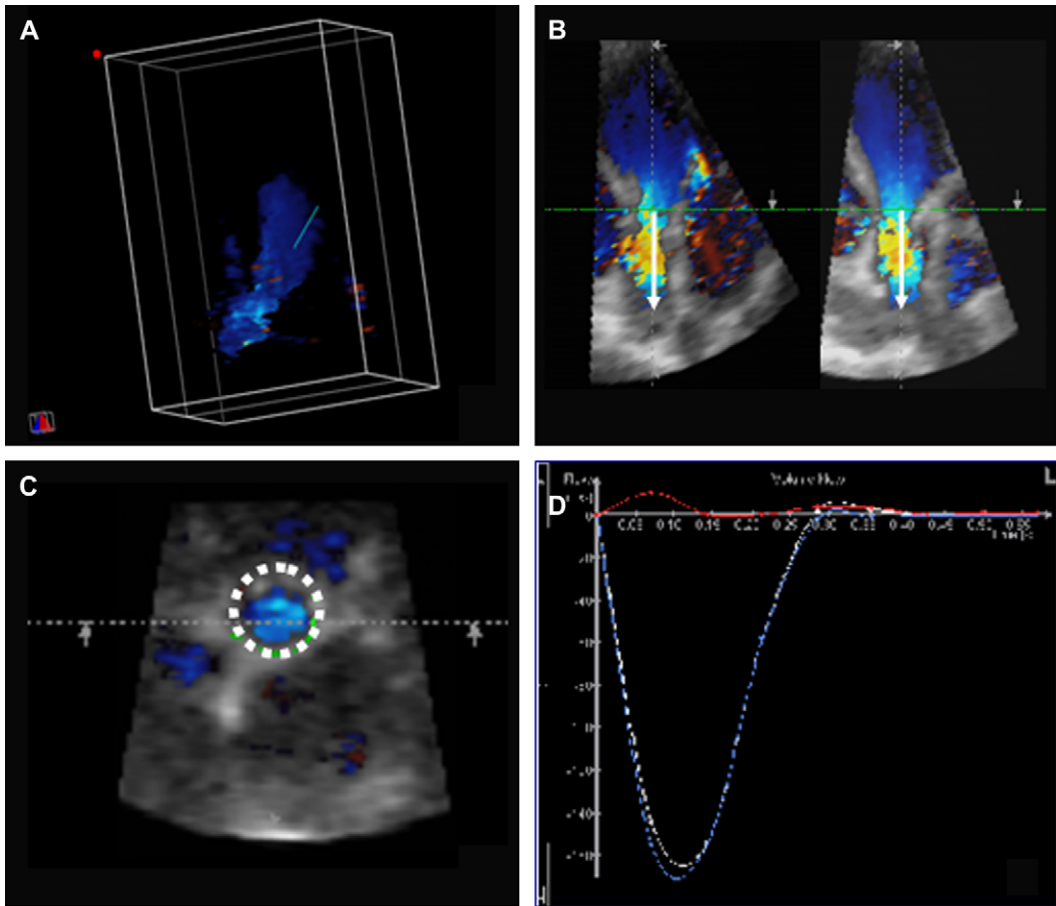


Fig. 4. Cardiac output estimation using off-line analysis software to quantitate flow rate (TomTec Imaging Systems, Unterschleißheim, Germany). A 3D color Doppler volume data set (A) subsequently is displayed in two orthogonal planes (B). Arrows (white) indicate the direction of flow, which automatically is aligned perpendicularly along a curved surface. In a third multiplanar view, a circular region of interest is drawn to calculate flow rate (C and D).

being prone to inaccuracies. Noninvasive methods such as 2D echocardiography and pulsed wave Doppler measurements of cardiac output provide an estimate of these measurements but are also fraught with limitations because of geometric assumptions of the left ventricular outflow tract (LVOT), alignment of Doppler flow, and inaccuracies with the LVOT velocity profile. Real-time 3DE data contain Doppler and gray-scale volume information that are obtained initially using an optimized 2D echocardiography image acquired in a biplane view. Subsequently, a region of interest is placed surrounding the LVOT and aortic valve to calculate aortic flow. Gated to ECG and using a breath hold, a 3D volume is acquired over seven cardiac cycles. Thus, the final volume consists of seven subvolumes with smaller

color subvolumes contained within the region of interest. 3D color Doppler may overcome these limitations by using a semiautomated method of integrating flow traversing the LVOT to derive SV and CO calculations. The foundation of this method was established in-vitro and later in vivo in animal studies that determined the feasibility and accuracy of 3DE [16–21]. Of note, calculation of stroke volume from real-time 3DE data performed in an in vitro study depends on the depth of imaging. Stroke volumes are less accurate with depths greater than 13 cm, particularly with higher SV caused by decreased resolution and reduced frame rates [22].

Human studies have yielded similar correlations against gold standards, such as thermodilution and 2DE [23,24]. Both studies used real-time

3DE color volume data set and off-line analysis (TomTec Imaging Systems, Unterschleißheim, Munich, Germany) to quantitate flow volumes based on Gaussian control surface theory. Direction of flow automatically is aligned perpendicularly along a curved surface; thus the flow rate is equal to the sum of all vectors [25]. Placement of this curved surface is defined in two orthogonal views. Subsequently, in a third multiplanar view a circular region of interest is drawn to calculate flow rate (Fig. 4 A–D). Using this methodology, stroke volumes derived using 3DE correlate well with 2D echocardiography, but when 2D echocardiography and 3DE calculations were compared against thermodilution, 3DE had better correlations ($r = .94$ and $r = .75$, 3DE versus 2D echocardiography, respectively) with smaller biases and narrower limits of agreement (1.84 ± 16.8 versus -8.6 ± 36.2 ml). When this methodology was applied to mitral inflow in children, it also compared well against phase velocity MRI at the ascending aorta and left volumetric MRI measurements [26]. Similarly, mitral valve inflow using 3DE compared better than 2D echocardiography ($r = .93$ and $r = .75$, respectively) [23].

Limitations

Real-time 3DE acquisition using a fully sampled matrix array probe has improved and overcome significantly many of the limitations encountered with previous methods of data collection. This technology allows shorter data collection and concurrent color Doppler information and gray scale. Shortcomings of this technology still exist, however. The 3D volume data set consists of seven subvolumes that are acquired over 7 to 14 cardiac cycles during a breath hold. This introduces the possibility of stitch artifact, seen as misalignment between subvolumes, caused by either movement of the probe, inability to maintain a breath hold, or arrhythmias during acquisition. Another drawback is that the sector sizes for both color Doppler and gray scale are too narrow to compensate for low frame rates, particularly if one wants to image the extent of the jet contained within an atrial chamber. If the region of interest is either the flow convergence or the outflow tract, this latter drawback is not as problematic. As technology advances, a single-volume acquisition would be preferable with high frame rates, depending on the density of the 3D volume.

Another major impediment of using 3D Color Doppler clinically is that data analysis must be performed off line. Other challenges are the continued presence of aliasing and color bleeding. Although current software enables the operator to adjust for aliasing by shifting Doppler baseline during off-line analysis, overt baseline shifting results in overestimation of cardiac output. Color bleeding may be adjusted by changing write priority (parameter or threshold that balances between 3D color and gray scale), but this also may confound the results.

Though much has been learned about the potential advantages of 3D color Doppler over 2D echocardiography, the feasibility of performing 3D color studies in patients in a clinical practice is challenging. Reasons for these continued obstacles are poor acoustic windows, inadequate color gain settings, and respiratory artifacts [23].

Summary

3D color Doppler has provided new physiologic insight into regurgitant jets, an alternative method for quantitation, and more accurate estimates of regurgitant volume, vena contracta, and effective regurgitant orifice areas. It is a relatively new noninvasive tool that also enables quantitation of cardiac output, stroke volume, pulmonary outflow, and shunt calculations. With further advances in computer and ultrasound technology, this modality will become a viable tool in clinical practice.

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Three-Dimensional Echocardiography: An Alternative Imaging Choice for Evaluation of Tricuspid Valve Disorders

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Historically, precise echocardiographic depiction of the tricuspid valve anatomy has proven to be illusive. Simultaneous visualization of all leaflets has not been achieved routinely from standard two-dimensional echo (2DE) imaging views, especially the posterior leaflet [1]. Therefore, 2DE evaluates the valvular structure and function with only two leaflets represented within the imaging plane. The result is that determination of individual tricuspid leaflet involvement is challenging when pathologic processes are present, and is perhaps accomplished best by acquiring a multiple cardiac cycle capture with an anterior to posterior sweep.

Conversely, the left-sided valves are visualized easily en face from parasternal short axis view. The aortic valve is of course particularly well visualized en face, and very frequently all three leaflets are visualized easily. Imaging for the bileaflet mitral valve is also often quite pleasing by 2D imaging in the parasternal short axis view.

Real-time three-dimensional (RT3D) imaging previously has been used to aid quantification of tricuspid regurgitation using color flow [2]. In addition, a series of 29 patients has been presented with various tricuspid pathologies. In this series, the main advantage of the RT3D was the ability

to see all three leaflets. The authors particularly re-emphasized that the posterior leaflet is particularly difficult to visualize by 2DE [3]. This article presents an approach to RT3D imaging the tricuspid valve from three different views. This is followed by some representative cases that illustrate these views and some unique tricuspid valve abnormalities, including one case of corrected transposition.

Approaches to 3D imaging of the tricuspid valve

Like 2DE, there are three main views for use with RT3D imaging: parasternal, apical, and subcostal. In RT3D imaging, however, there is also the truly real-time acquisition, and then there is the four cardiac cycle full volume. Both of these approaches are useful for tricuspid valve imaging, particularly from the apical and parasternal views. A major advantage that RT3D imaging offers in terms of physical imaging is the ability to steer the 3D beam without actually moving the transducer. Here, in addition to basic RT3D imaging, the authors provide some tips for using the beam steering and some examples.

Parasternal views

From the parasternal long axis view, sweeping to the right will yield the tricuspid valve. With the 3D matrix probe, again, the beam can be steered

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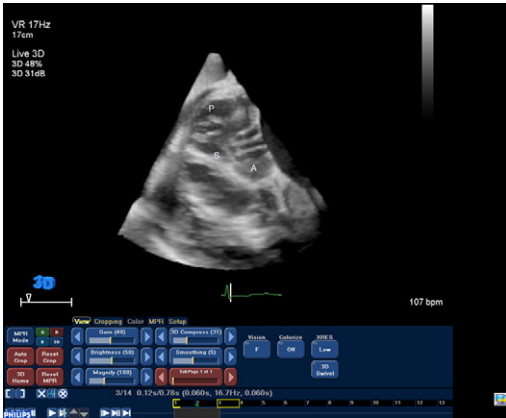


Fig. 1. Subcostal view of the tricuspid valve showing all three leaflets (case 1). In this case, the tricuspid valve is viewed from the right ventricle and looking toward the right atrium. The individual valve leaflets are depicted as A, anterior, P, posterior, and S, septal.

electronically, a major advantage for this particular purpose. That is because viewing the tricuspid valve from this vantage often requires a very acute angle between the transducer and the skin. The combination of the acute angle to the skin and the need to fit between a rib interspace to discover an optimal ultrasound window do indeed welcome the electronic steering. Often initial 2D scanning is used to identify the tricuspid valve, and then switching to real-time

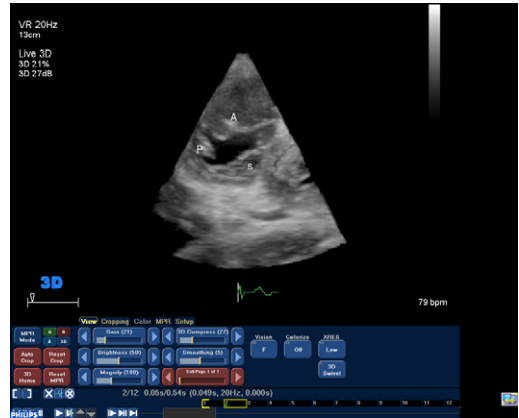


Fig. 3. The tricuspid valve obtained from the parasternal short axis view with tilting toward the right. Electronic beam steering was employed to optimize the image (case 3).

3D imaging (RT3D) will yield the tricuspid valve in an enface view, although often slight manipulation of the transducer either manually or with electronic steering is necessary to optimize the image to simultaneously view all three leaflets. Examples are provided in cases 3,4,5, and 6.

Apical imaging

From the apex, the tricuspid valve can be imaged in a similar plane as would be used for 2D imaging. Optimization for the right heart structures of course is required. In addition,



Fig. 2. Apical 4 chamber view. Full volume obtained from the apical view shows the tricuspid valve en face. The image has been cropped from apex to base, showing the tricuspid valve looking from the right ventricle toward the RA (case 2). Note the interventricular septum. Valve leaflet designation same. AoV depicts aortic valve. The aortic valve and left ventricular outflow tract are not imaged optimally.

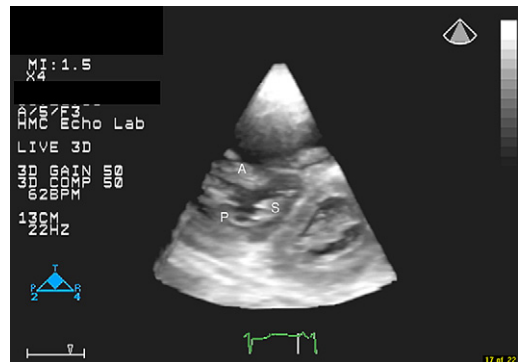


Fig. 4. Parasternal short axis view with the right ventricle cropped in order to view the tricuspid valve from the right ventricle side. Right ventricular volume overload is noted with compression of the interventricular septum in diastole (case 4).

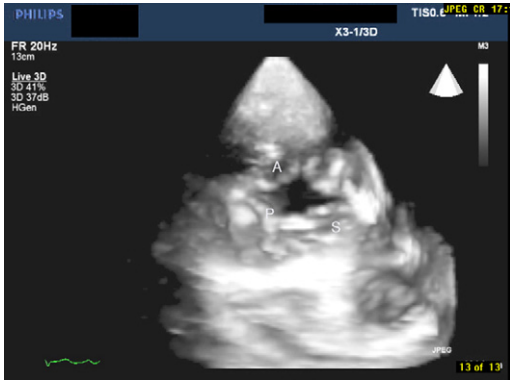


Fig. 5. Parasternal long axis FV. Full-volume acquisition is shown obtained from the parasternal long axis view. The view is seen looking into the right atrium from the parasternal long axis and was obtained by angling toward the right heart and cropping from the right ventricle apex toward the tricuspid valve to show this tri-leaflet tricuspid valve. The view is looking into the right atrium (case 5).

acquisition of a full-volume data set (a stitching together of four cardiac volumes) will allow the widest field of visualization for the tricuspid valve from this view. Once the full-volume data set has been acquired, cropping from either the apex toward the base or from base to apex frequently will yield side-by-side views of the tricuspid and mitral valves, and both can be viewed from either the apical or basilar side. And of course the main advantage is visualization of all three leaflets of the tricuspid

valve with the ability to distinguish the anterior leaflet from the posterior leaflet. Cases 2 and 7 provide examples.

Subcostal imaging

In some patients, the subcostal view is also useful for obtaining similar views for the tricuspid valve. Beam steering again can be advantageous for this view given the acute angle to the skin that often is required to place the probe adjacent to the liver and under the costochondral junction. Case 1 is an example.

Cases

The authors describe seven cases involving eight patients who had particularly outstanding views of the tricuspid valve that were all obtained en face from various imaging planes/angles. They further describe in detail as much as possible how the images were obtained. Note that there are still frames as well as movie (avi) clips for all of these cases.

Case 1. This patient had underlying mitral stenosis leading to an enlarged right heart. The tri-leaflet tricuspid valve was imaged from a subcostal short axis at the base of the heart. This demonstrates that various imaging windows may yield an optimal RT3D image of the valve en face (See Fig. 1).

Case 2. A 37-year-old woman who had mild pulmonary hypertension and a mildly enlarged right ventricle presented with dyspnea. A full 3D volume acquired from an apical four-chamber view allows for simultaneous visualization of the

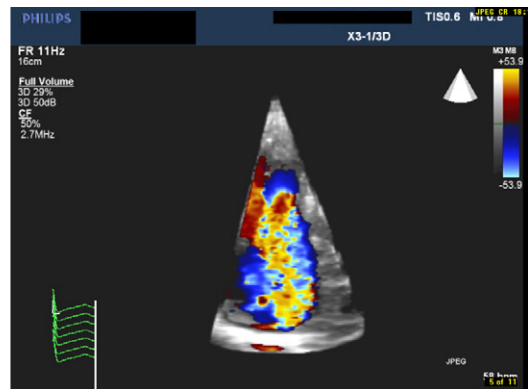


Fig. 6. Parasternal long axis view. (A) In this patient status post endocarditis of the tricuspid valve. It was clear from 2D imaging that there was lack of coaptation between two of the tricuspid valve leaflets. Which two leaflets failed to coapt was much less clear. The view that the authors obtained from the parasternal long axis view showed unequivocally that the septal leaflet was normal, and it was lack of coaptation between the anterior and posterior leaflets that resulted in the severe tricuspid regurgitation. (B) The severe tricuspid regurgitation 3D color jet (case 6).

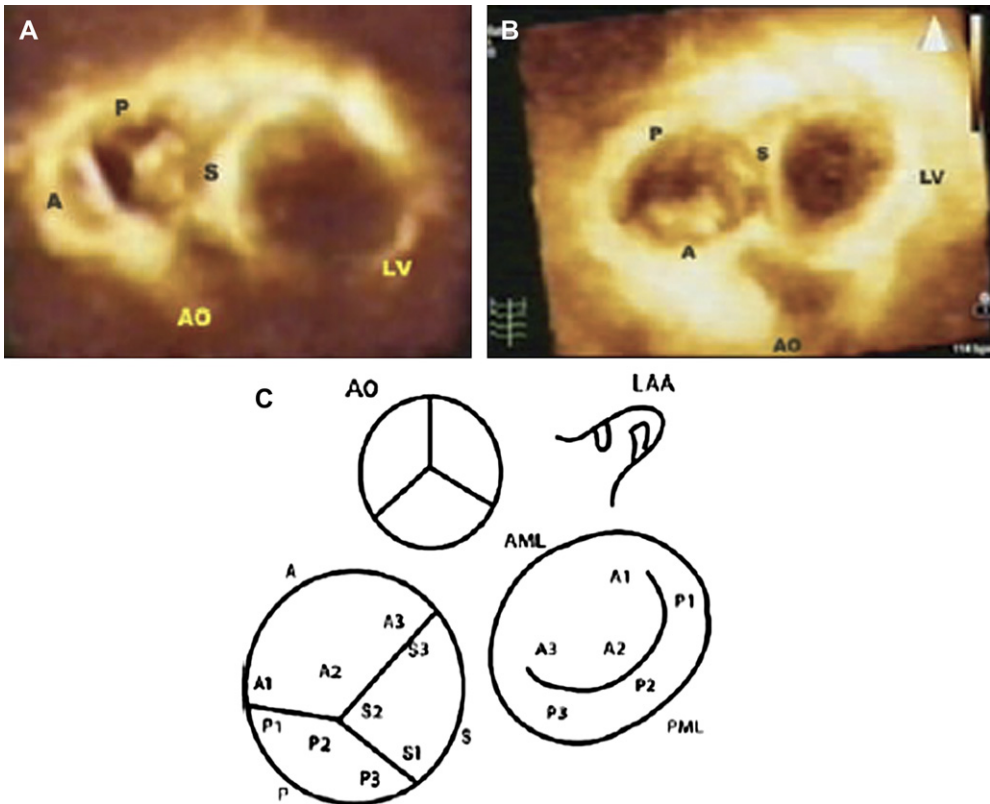


Fig. 7. Apical 4 chamber view full volume. Two patients with tricuspid valve prolapse are shown in this full-volume data set obtained from the apical view. (A) En face view from the atrial side showing prolapse of S1, S2, A2, A3, P1, and P2 tricuspid valve segments. (B) Another en face view in a patient with prominent systolic prolapse of A1, A2, A3, S2, and S3 tricuspid valve segments. Also present is mild prolapse of the P2 segment. (C) Schematic of a proposal for divisions of the segment for the tricuspid valve. Abbreviations: AML, anterior mitral leaflet; LAA, left atrial appendage; PML, posterior mitral leaflet. (Reproduced from Pothineni KR, et al. Live/real-time 3D transthoracic echocardiographic assessment of tricuspid valve pathology: incremental value over the 2D technique. *Echocardiography* 2007;24:541–52; with permission.)

leaflets. Cropping the full volume from the RV apex toward the base will reveal the TV en face as demonstrated here. 3D cropping is important to understand when trying to maintain proper orientation and identification of the anatomy (See Fig. 2).

Case 3. This image was obtained from a 95-year-old woman who sustained chest trauma and suffered from atrial fibrillation. A trileaflet tricuspid valve can be imaged from the parasternal window both from the long and short axis. This TV was imaged from a parasternal short axis (PSAX) window with image optimization focused on the right heart. The leaflets are seen from the right ventricular side of the valve. Medial and anterior angulations may be necessary to obtain

visualization of all leaflets. The 3D matrix probe's electronic beam steering was used for this case (See Fig. 3).

Case 4. A 45-year-old man who had severe pulmonary hypertension presented with dyspnea. His right ventricle was dilated severely with severely reduced systolic function. This image was obtained from a PSAX with the RV apex cropped to view the valve from the ventricular side (See Fig. 4).

Case 5. A 51-year-old woman with end-stage renal failure and severe pulmonary hypertension presented with an arterio-venous fistula infection. The right ventricle was dilated moderately, and systolic function was reduced severely. A full volume from the parasternal long axis was obtained

by angling toward the right heart and cropping from the RV apex toward the TV to show this trileaflet TV. The view is looking into the right atrium (See Fig. 5).

Case 6. This patient had a history of endocarditis leading to noncoaptation of the valve leaflets. The question was which leaflets. The view that the authors obtained from the parasternal long axis view showed unequivocally that the septal leaflet was normal, and it was coaptation between the anterior and posterior leaflets that resulted in the severe tricuspid regurgitation (See Fig. 6).

Case 7. Two patients with tricuspid valve prolapse are shown. Both images are obtained from the apical view with cropping from the atrial side. In both cases, the prolapsed sections are coming into the plane of view (See Fig. 7).

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Discussion

Imaging of the tricuspid valve by 2DE is limited severely by the inability to view all three leaflets simultaneously. For years, this limitation has been overcome partially by using an anterior/posterior sweep to see both the anterior and posterior leaflets in the apical four-chamber view or the subcostal view. The echocardiographer then interpolates the results of the sweep into his or her own imagined 3D image of the entire valve. The advent of RT3D imaging largely eliminates for this exercise when all three leaflets are viewed en face. This can be accomplished in three ways:

1. Parasternal short axis imaging with beam steering
2. Apical imaging with full-volume acquisition and subsequent cropping

3. Subcostal views, again with either short-axis orientation, sometimes optimized with beam steering, or with full-volume acquisition and cropping

It should be pointed out that full-volume acquisition is of course not truly real-time, as typically four cardiac cycles are stitched together. In situations where full-volume acquisition is sub-optimal, such as patient movement or irregular heart rhythm, beam steering can be a particularly useful feature of RT3D, because imaging planes not possible with transducer movement only are made imminently approachable just by steering the ultrasound beam electronically.

Summary

In 2DE imaging, the tricuspid valve presents a challenge for pinpointing individual leaflets, because it is rare to see all three in one two-dimensional image plane. RT3DE circumvents this problem, with the additional plane of elevation such that all three leaflets are seen.

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The Use of Three-Dimensional Echocardiography for the Evaluation of and Treatment of Mitral Stenosis

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Rheumatic mitral stenosis remains an important public health concern in both developing and developed countries, the latter because of immigration from the former. Percutaneous mitral valvuloplasty (PMV) has developed into the treatment of choice for selected patients who have favorable mitral valve anatomy [1]. Choosing the subset of patients with mitral stenosis who are the most favorable for PMV requires precise evaluation of valve and particularly commissural anatomy. More specifically, echocardiography is used to define the valve area, the degree of calcification, valve mobility and thickening, the degree of mitral regurgitation, and finally, degree of commissural fusion.

Dating back to the 1950s, the catheter-based Gorlin's equation has been considered the standard for estimation of the mitral valve area. Gorlin's equation, however, uses hemodynamics obtained from fluid-filled catheters. It is invasive, uses numerous assumptions, and clearly can result in complications and has numerous limitations. Most notably, it is inaccurate when significant valvular regurgitation is present. In clinical practice, two-dimensional echocardiography (2DE), coupled with Doppler evaluation of mitral valve gradient and pulmonary artery pressure, has

become the mainstay for evaluating mitral valve disease and more particularly mitral valve area (MVA). MVA is assessed indirectly by the PHT method or directly by planimetry. There are advantages and limitations to both methods. PHT-derived MVA can be obtained easily, but may be influenced by hemodynamic factors (heart rate, cardiac index, cardiac rhythm, left ventricular systolic and diastolic dysfunction, left ventricular and atrial compliance, left ventricular hypertrophy, and concomitant valvular disease [2,3]. These hemodynamic factors change rapidly during the immediate post-PMV period, which may explain the significant discrepancies observed in earlier studies between the PHT-derived MVA and the Gorlin's-derived MVA. In addition, there is the issue of the presence of an atrial septal defect (ASD) formed during the procedure during transseptal puncture. This is another cause for inaccuracy of the Gorlin formula [4].

Planimetry of the valve orifice has the advantage of being relatively hemodynamically independent, although one might imagine that the orifice could be truly larger when left atrial pressure is high. Until the recent development of 3D techniques, planimetry of the valve orifice was performed by 2DE, a technique that has multiple limitations (Fig. 1). The greatest limitation is that measurements of the mitral valve orifice area are made in the short axis view with no

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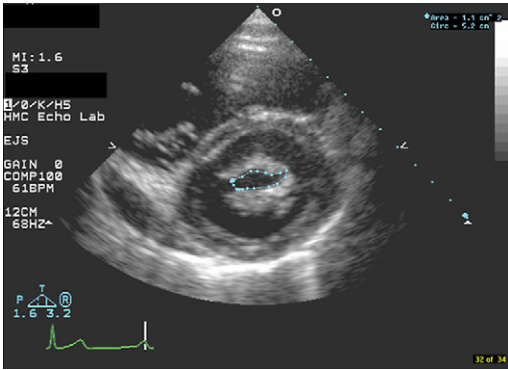


Fig. 1. Example of planimetry of a stenotic mitral valve using standard 2D imaging. Note that the extreme medial and lateral edges of the mitral orifice have dropped out of the grey scale, making accurate assessment of the area difficult. Also, there is no verification from an orthogonal plane that the measurement is at the mitral leaflet tips.

simultaneous independent imaging to verify that the imaging plane corresponds to the smallest and most perpendicular view of the mitral orifice. Because of this disadvantage, the 2D method requires significant experience and operator skill to obtain the correct imaging plane that displays the true mitral valve orifice. This limitation is amplified the more diseased the valve is and after PMV. As the disease process progresses, the border of the valve orifice becomes more calcified and irregular, making the tracing of the orifice more challenging. Likewise, after PMV, the commissural fusion can split in an asymmetric fashion, again making the tracing of the orifice less reproducible between observers. Many, but not all of these limitations are overcome with the use of 3D echo (3DE).

Advantages of 3D echocardiography

One of the most significant developments of the last decade, particularly in the field of cardiac imaging, has been real-time 3DE (RT3DE). Even before that time, other methods of 3DE were used to evaluate the mitral valve, but the required reconstructive process made them much less practical. 3DE provides unique orientations of the cardiac structures not obtainable by standard 2DE. 3DE has evolved from a research tool to having practical utility, one of them being the accurate planimetry of the MVA in rheumatic

mitral stenosis. 3DE can provide not only adequate imaging of the anatomic structure of the mitral valve orifice (commissural splitting and leaflet tears) [5], but also information on the optimal plane of the smallest mitral valve orifice area (Figs. 2–4). In addition, planimetry using 3DE is not limited to the parasternal window as 2DE is, but rather it also can be performed from the apical window. This imaging view has been slower to be adopted in routine clinical practice, because it requires postprocessing, specifically cropping the acquired image, which can be time-consuming and tedious. The combination of the dense array [6] matrix transducer and the newest cropping software, however, has streamlined this process considerably.

3D echocardiography performed with transesophageal echo

3DE acquired with TEE and subsequent 3D reconstruction had shown promise for evaluating patients with mitral stenosis before the advent of RT3DE. Before rotational 3D TEE even developed by commercial vendors, the group from the Thorax center had developed its own system and studied 15 patients with it, showing good correlation between MVA by this methodology and pressure half-time [7]. In 1998, TEE acquired 3DE was shown to predict response to PMV based on commissural fusion. The visualization of commissural splitting after PMV also correlated with larger valve area [5]. Later, in a series of more than 40 mitral stenosis patients, three-dimensional reconstructions were performed from 2D TEE acquisitions. MVA correlated closely with traditional methods, and visualization of the commissures was superior to what was seen by 2DE [8]. Similar results were obtained by others [9].

Real-time 3D echocardiography compared with classic methods for the assessment of the mitral valve area

In 2003, a series of five patients with mitral stenosis was studied with RT3DE and showed favorable results compared with the traditional methods of Gorlin's equation and pressure half-time. It was suggested that RT3DE was more accurate, particularly compared with 2DE, because it was more reproducible and correlated better with the Gorlin's equation valve area. Also, in one of the cases, postprocedure mitral

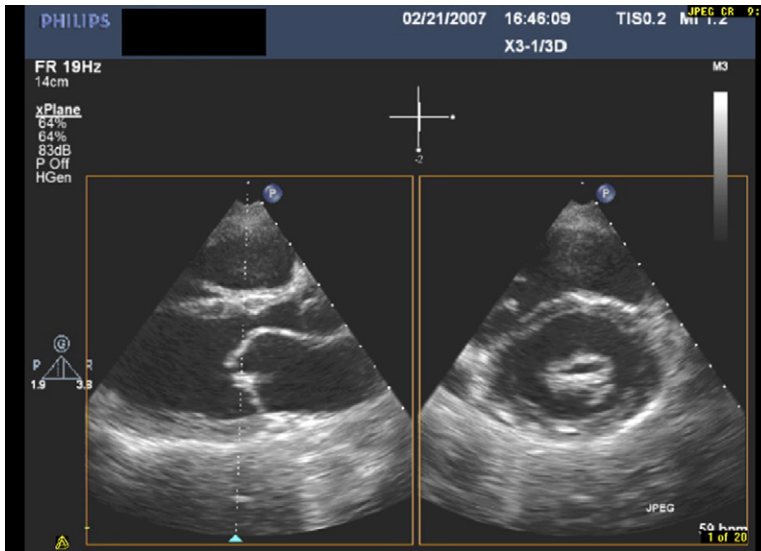


Fig. 2. Example of a view of a stenotic mitral valve using biplane 2D imaging. The 3D transducer allows simultaneous display of more than one 2D view. The advantage of this is the ability to confirm that the parasternal short axis view of the mitral orifice is in fact at the tip of the mitral leaflets.

regurgitation developed, and RT3DE detected an area of systolic noncoaptation between the mitral leaflets that was not seen by 2DE and correlated with the mitral regurgitation [10]. In a series of 48 patients, RT3D (in a subset of the group) and 3D TEE were used to evaluate mitral valve area and response to PMV. Valve area correlated well with Gorlin and pressure half time valve areas. The clear visualization of commissural fusion by 3DE was the most reliable predictor of a positive response to PMV, more so than the Wilkins valvuloplasty score [11].

Then, in a larger group of 80 patients, the accuracy of current 2DE methods (2D planimetry, PHT, and proximal isovelocity surface area method (PISA) was compared with RT3DE for the assessment of MVA in patients who had rheumatic mitral valve disease. RT3DE was compared to the standard of the invasively determined Gorlin's equation [12]. RT3DE was performed en face at the ideal cross section of the mitral valve orifice during its maximum diastolic opening. The ideal cross section was defined as the most perpendicular view in the plane with the smallest mitral valve orifice (Fig. 3). This plane also should be parallel to the flow through the most limiting part of the mitral orifice.

The PMV Wilkins score was determined by both 2DE and RT3DE. RT3DE planimetry and mitral score were measured by two independent

observers and then repeated by one of them. Intermethods agreement was evaluated by means of the intraclass correlation coefficient. The analysis demonstrated a superior agreement when comparing the invasively determined MVA with RT3DE MVA than when comparing it with the current 2DE methods (Table 1) [13]. Further, the interobserver variability was nearly twice as good with RT3DE than with 2DE for the PMV Wilkins score (Table 2) [13]. Finally, RT3DE measurements had excellent inter- and intraobserver variability and the best interobserver agreement for morphologic evaluation. This study showed that RT3DE was the most accurate echocardiography parameter for measuring MVA. Similar results have been reported by others [14–16].

Real-time 3D echocardiography compared with classic methods for the assessment of mitral valve area after a mitral valvuloplasty

As previously stated, traditional methods of MVA measurement have even more limitations immediately after PMV; therefore, MVA was evaluated by RT3DE following PMV [17]. Many studies have demonstrated considerable discrepancies after PMV between MVA measurements obtained using the PHT method and invasive hemodynamic evaluation using Gorlin's equation

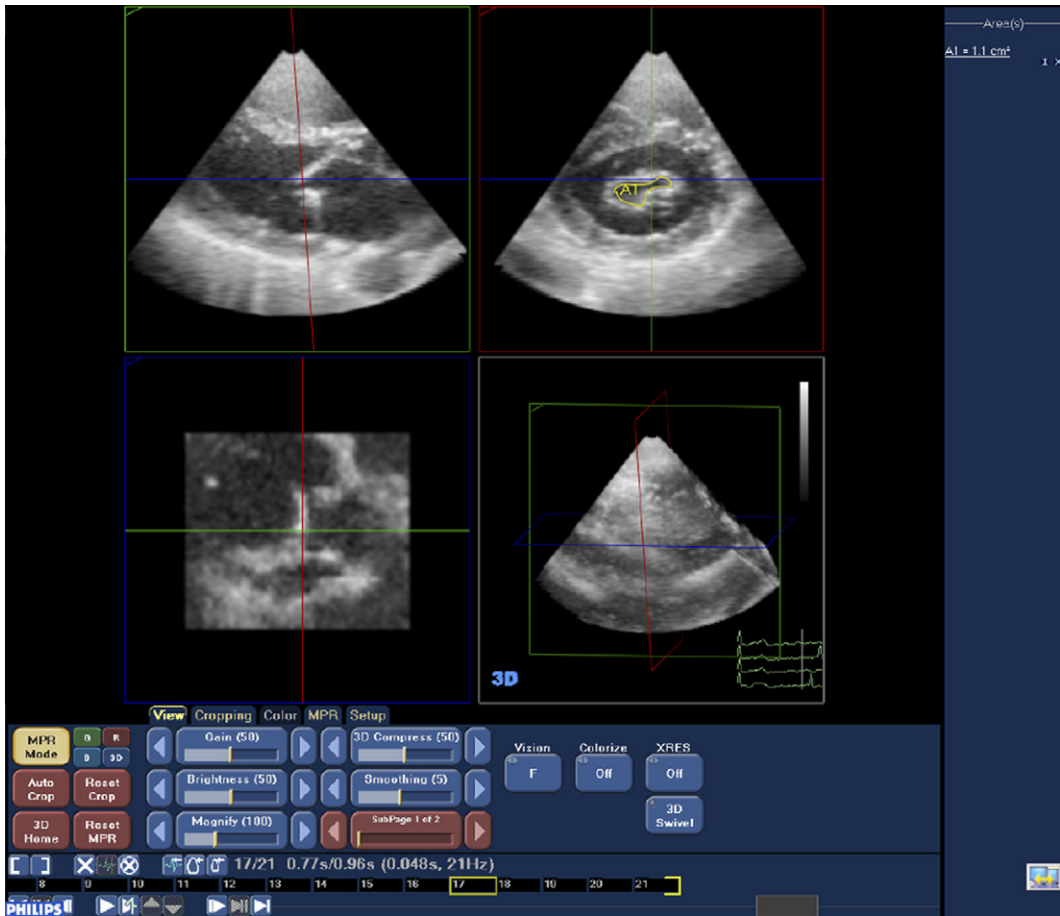


Fig. 3. A full-volume acquisition obtained from parasternal view. The data set has been cropped such that the smallest mitral valve orifice can be measured. The upper left image shows the mitral valve in parasternal long orientation, while the upper right image shows the mitral valve in parasternal short orientation. The bottom right image is a compilation of the entire volume data set. The upper left image has been used to place the cursor at the very tip of the mitral leaflets, so that the corresponding mitral valve area shown on the right is the smallest possible. See corresponding measurement.

[4,18–23]. There are several reasons for this inaccuracy. Perhaps the most obvious, especially as it adversely affects the PHT method, is the development of an atrial septal defect as an unavoidable side effect of the transeptal puncture [4,22]. Also, the PHT method assumes stability of left atrial and left ventricular compliance, an assumption that is not valid in the immediate post-PMV period [24,25]. 2D planimetry of MVA is not as dependent on hemodynamic variables [26–31], and theoretically it should be more accurate than PHT after PMV. It is not exempt of inaccuracies, however, because following PMV, the mitral orifice becomes irregular and is technically difficult to trace, particularly if significant

calcification is present. Because of the variable geometry of the stenotic mitral valve orifice, correct plane orientation frequently becomes difficult, and hence minor changes in depth and angle of the ultrasound beam lead to an overestimation of the MVA that ranges between 63% to 88% [14].

RT3DE allows a unique and superior evaluation of the mitral valve apparatus, enhancing the ability to obtain an accurate measurement of the MVA. To evaluate RT3DE-based planimetry after a PMV, 29 consecutive patients who had rheumatic mitral valve disease were enrolled and underwent PMV. MVA was calculated before and after PMV using the PHT method, 2DE planimetry, RT3DE planimetry and the invasive

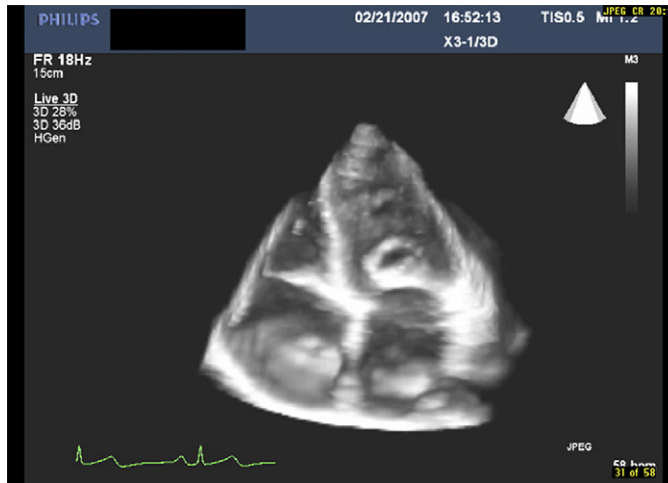


Fig. 4. Similar to Fig. 3, but obtained from an apical view, a full-volume data set is shown cropped to show the mitral orifice.

determination using the Gorlin's equation. The Gorlin's equation was considered the standard. The main findings were that RT3DE was the most accurate ultrasound technique for measuring MVA, with a superior pre- and postprocedural agreement with the Gorlin's derived MVA (see Table 2) [16]. After PMV, the agreement with the Gorlin's-derived MVA was better than two-dimensional planimetry and pressure half-time-derived MVA (Fig. 5, Table 3, Video 1).

Access video on Mitral Stenosis post cracked commissures of this article at: <http://www.cardiology.TheClinics.com>

Mitral valve shown with 3D rendering after having undergone percutaneous mitral valvuloplasty. In this video, the medial commissure is

Table 1

Intraclass correlation coefficient between the different echocardiographic methods and invasive estimated mitral valve area (Gorlin method)

Method	ICC (95% confidence interval)
Gorlin	
RT3DE	0.83 (0.74–0.89)
PHT	0.6 (0.39–0.75)
2D planimetry	0.57 (0.38–0.72)
PISA	0.48 (0.24–0.66)

Abbreviations: ICC, intraclass correlation coefficient; PHT, half pressure time; PISA, proximal isovelocity surface area; RT3DE, real-time 3D echocardiography.

particularly well shown, having undergone splitting resulting in a larger orifice area.

In this study, the interobserver variability of Wilkins score [32] by using 2DE and RT3DE also was evaluated. Leaflet mobility, calcification, and subvalvular involvement were assessed using 2DE and RT3DE by two independent observers. As previously noted, the RT3DE assessment showed the best interobserver agreement for the morphologic evaluation of the rheumatic mitral valve.

In conclusion, real-time 3DE is also a very suitable technique for monitoring the efficacy of the PMV, with better accuracy compared with

Table 2

Intraclass correlation coefficient between the different echocardiographic methods and invasive estimated mitral valve area before and after percutaneous mitral valvuloplasty

Method	Intraclass correlation coefficient
Pre-PMV Gorlin	
Pre-PMV RT3DE	0.79
Pre-PMV 2D planimetry	0.6
Pre-PMV PHT	0.49
Post-PMV Gorlin	
Post-PMV RT3DE	0.64
Post-PMV 2D planimetry	0.5
Post-PMV PHT	0.2

Abbreviations: PHT, half pressure time PMV, percutaneous mitral valvuloplasty; RT3DE, real-time 3D echocardiography.



Fig. 5. The mitral valve is shown with 3D rendering after having undergone percutaneous mitral valvuloplasty. The commissures have been split, optimizing the mitral orifice.

2D planimetry and pressure halftime-derived MVA.

*Real-time 3D echocardiography.
The new standard for the mitral valvular area quantification?*

RT3DE offers the possibility of accurately measuring the mitral valve orifice area because of its ability to crop the volume data set in any position in space, and therefore, select the en face view that includes the smallest mitral valve area. In a study by Zamorano and colleagues [33], the MV orifice area was imaged further using RT3DE. In this investigation, the gold standard was different, because it was composed of a median mitral valve orifice area calculated from the three classical 2DE methods: 2D planimetry, pressure halftime, and PISA method. This

composite value was compared with MV orifice areas obtained with RT3DE planimetry and the Gorlin’s method. Intraclass correlation coefficient was used to compare the different methods. Analysis showed that the accuracy of RT3DE planimetry is superior to the accuracy of the invasive Gorlin’s method for assessing MVA in rheumatic mitral valve stenosis when the median (or composite data set) was used as the standard.

Summary

RT3D is a major advance in cardiac imaging, because it allows visualization of the entire mitral valve apparatus and the optimal plane to measure the smallest mitral valve orifice area. Currently, it can be argued that sufficient evidence has been compiled to prove that 3D imaging is superior to

Table 3
Advantages and limitations of the different methods to evaluate the mitral valve area

Method	Influence of hemodynamic conditions	Acoustic window needed	Useful after percutaneous mitral valvuloplasty	Invasive technique
2D planimetry	–	++	+	–
PHT	++	++	–	–
PISA	+	++	+	–
RT3DE	–	++	++	–
GORLIN	++	–	++	++

Abbreviations: PHT, half pressure time; PISA, proximal isovelocity surface area; RT3DE, real-time 3D echocardiography.

traditional 2D techniques and should be used routinely to quantify the MVA in mitral stenosis, particularly in the immediate postpercutaneous mitral valvuloplasty period, where other methods have been proven to be inaccurate [16,33–35]. RT3D is also useful to obtain accurate Wilkins score. RT3DE should be integrated into the routine echocardiographic examination, and perhaps, in the near future should replace Gorlin's method as the reference method to quantify the MVA in rheumatic mitral valve stenosis.

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Live/Real-Time Three-Dimensional Transthoracic Assessment of Mitral Regurgitation and Mitral Valve Prolapse

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Evaluation of the mitral valve requires appreciation of its complex geometry. In vertical space, the mitral annulus takes the shape of a saddle or ski slope, with the anteroseptal portion being more cephalad [1,2]. In pathologic conditions, this geometry is perturbed (eg, the annulus flattens when stretched in conditions such as dilated cardiomyopathies) [3]. When viewed en face, the mitral valve is composed of an anterior leaflet that can be divided into three segments:

- A1, anterolateral
- A2, middle
- A3, posteromedial

and a posterior leaflet composed of three scallops:

- P1, anterolateral
- P2, middle
- P3, posteromedial (Fig. 1) [4]

To accurately guide surgical interventions and describe pathology, familiarity with this nomenclature and orientation of the valve in 3D space is necessary. For this reason, 3D transthoracic echocardiography (TTE) is an immense improvement over the cumbersome mental reconstruction required by 2D TTE.

Mitral regurgitation

Accurate grading of mitral regurgitation (MR) severity using qualitative and quantitative color Doppler 2D TTE techniques has been challenging [5]. The most commonly employed measure is the ratio of the regurgitant jet area to left atrial area (RJA/LAA), but this is really a semiquantitative or qualitative technique. Techniques using volumetric approaches or the proximal flow convergence provide quantitative assessment but are limited by being time-consuming and involve calculations based upon assumptions that introduce inaccuracies [6,7]. Measurement of vena contracta width (VCW) by 2D TTE has been validated against regurgitant fraction and angiography [8,9]; however, grading criteria assume a circular or elliptical shape that may not represent the true geometric appearance of the vena contracta [10]. For these reasons, the authors evaluated 3D TTE measurements of vena contracta area (VCA), with comparisons to 2D TTE measures of RJA/LAA and VCW and to angiographic grading by left ventriculography [11]. As demonstrated by the authors and others, quantification of MR by 3D TTE is superior to 2D TTE measures, which especially are hampered when the assumed geometry is not realized in practice [11–13].

Using a Philips Sonos 7500 (Andover, Massachusetts) ultrasound system equipped with a 4 × matrix transducer, B mode, and color Doppler, 3D data sets were acquired from the apical and parasternal long axis views. Color Doppler gain was set at 70%, and the Nyquist limit was set between 43 and 69 cm/sec, because VCA

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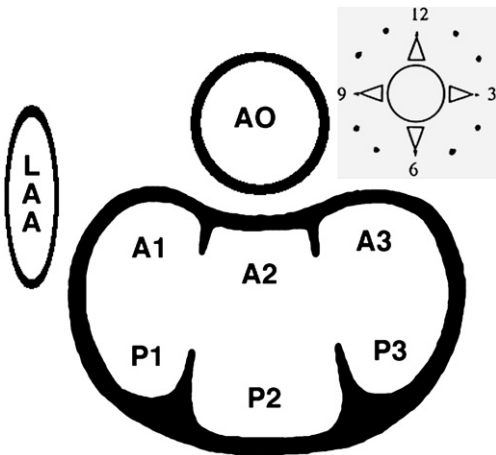


Fig. 1. Schematic diagram of the segmental classification used to describe the prolapse of mitral valve, as viewed by the surgeon. *Abbreviations:* A1, A2, and A3, anterolateral, middle, and posteromedial segments of anterior mitral valve leaflet; AO, aorta; LAA, left atrial appendage; P1, P2, and P3, anterolateral, middle, and posteromedial scallops of posterior mitral valve leaflet. (Reproduced from Ahmed S, Nanda NC, Miller AP, et al. Usefulness of transesophageal 3D echocardiography in the identification of individual segment/scallop prolapse of the mitral valve. *Echocardiography* 2003;20: 203–9; with permission.)

measurements remained relatively constant in this range. Most cropping was performed from the apical views as demonstrated in Fig. 2. First, the best vena contracta image was obtained in long axis by anterior-to-posterior cropping (see Fig. 2A). Second, by cropping from the top of the data set, an imaging plane was placed at the level of the vena contracta, at or just below the mitral valve leaflet tips in a plane that was parallel to the orifice (see Fig. 2B). The image then was rotated, to view the vena contracta en face (see Fig. 2C), and the previously cropped anterior portion was added back to obtain the maximum VCA (see Fig. 2D). This procedure was recorded in its entirety on a VHS tape. Measurements of VCA were obtained by:

Direct video planimetry (using the VCR function on the ultrasound system to play back the recorded cropping, the depth markers viewable in the initial image, Fig. 2A, were used for calibration, and then the VCA was traced)

Off-line (using a Tom Tec Cardio view-RT, Munich, Germany)

The authors' subsequent experience with the Q laboratory software suggests that measurements with this software package may slightly underestimate those performed in their original publication.

Using this technique, the authors assessed MR by measurements of VCA with 3D TTE and other standard 2D TTE measurements in 44 patients who underwent left ventriculography [11]. Results revealed close agreement for 3D TTE VCA measurements and angiographic grading, with discernment between angiographic grades using the following diagnostic criteria: $<0.2 \text{ cm}^2$ for mild (grade I), 0.2 to 0.4 cm^2 for moderate (grade II), and greater than 0.4 cm^2 for severe (grade III) MR (Fig. 3). Direct video planimetry and off-line computer analysis agreed well, and interobserver variability and intraobserver variability were very low (sum of residuals $r^2 = .99$ and 0.97 , respectively) for this parameter. 3D TTE measurements of VCA were superior when compared with the angiographic standard as opposed to the traditional 2D TTE measurements of RJA/LAA, RJA, VCW, and calculated VCA. A subsequent study by Iwakura and colleagues [12] yielded similar incremental value for 3D TTE measures of regurgitant orifice area over 2D TTE quantification of proximal isovelocity surface area (PISA), especially in patients who had elliptical orifice shapes. In clinical practice, the authors have found this technique robust as a clinical tool for diagnosing and following patients with MR, because 3D TTE VCA offers a quantifiable indirect measure of the hole in the mitral valve that is not load-dependent and that appreciates the complex geometry of the mitral valve and its regurgitant orifice.

In addition to quantifying MR, the three-dimensional TTE data set is useful in assessing anatomy responsible for valvar insufficiency. Leaflet geometry can be assessed with available software packages, and this may be useful in surgical decision making [14,15]. Chordae rupture and flail leaflets can be seen, improving diagnostic confidence in patients who have acute MR and often obviating the need for a transesophageal echocardiography (TEE) exam. In addition, the authors have found 3D TTE particularly useful in evaluating patients with endocarditis. En face views permit correct characterization of valvar perforations, and systematic cropping is useful in excluding abscess formation. The 3D dataset can be cropped to accurately describe and measure vegetations, which may provide a prognostic

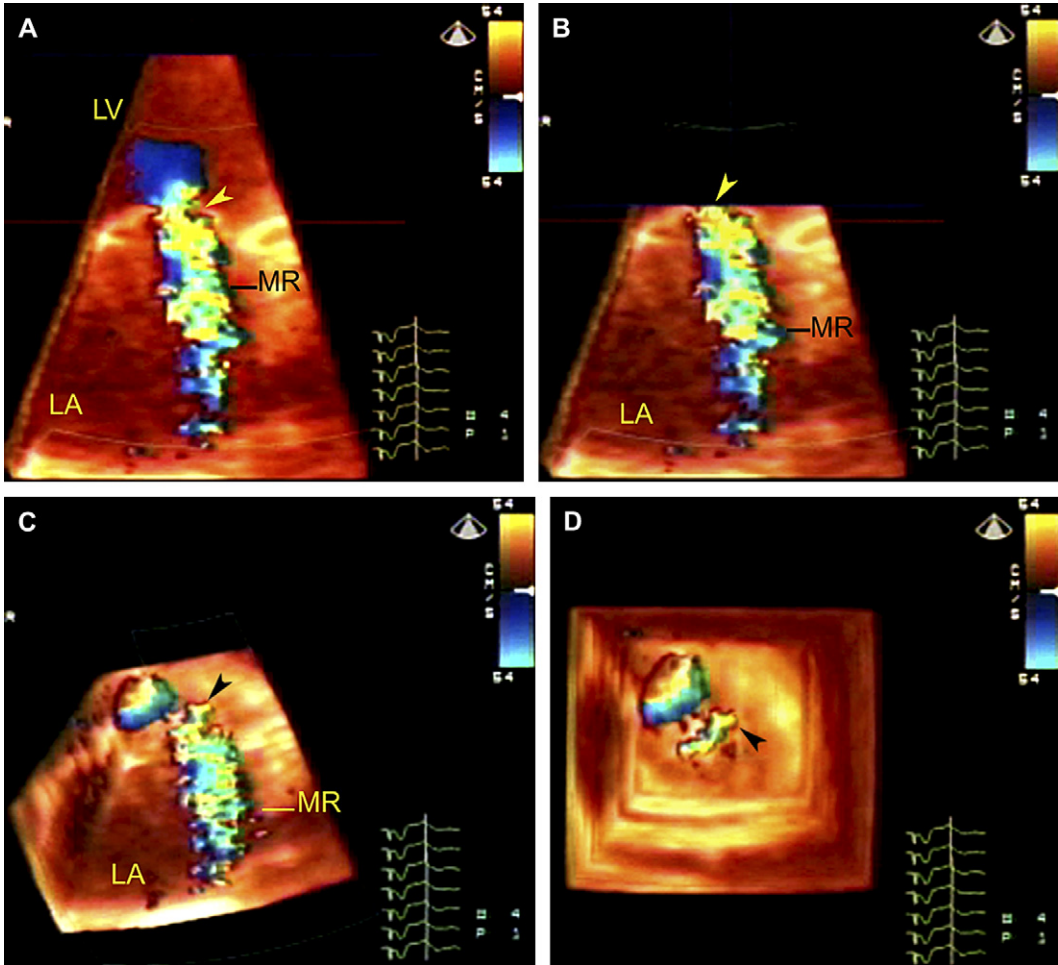


Fig. 2. Live 3D color Doppler transthoracic echocardiographic technique for assessment of vena contracta area. 3D color Doppler data set showing mitral regurgitation (MR, *A*) is cropped from top to the level of the vena contracta (*arrowhead*, *B*) and tilted to view it en face (*C*, *D*). The vena contracta then is planimetered by copying onto a videotape. Abbreviations: LA, left atrium; LV, left ventricle. (Reproduced from Khanna D, Vengala S, Miller AP, et al. Quantification of mitral regurgitation by live 3D transthoracic echocardiographic measurements of vena contracta area. *Echocardiography* 2004;21:737–43; with permission.)

index for embolization [16,17]. Because the 3D dataset contains the entire mitral valve apparatus, comprehensive evaluation with 3D TTE is possible in a time-efficient manner.

Mitral valve prolapse

Because mitral valve repair is always preferable to replacement for mitral valve prolapse (MVP) [18–20], preoperative evaluation of the mitral valve for suitability for repair and precise

identification of the prolapsing segment/scallop (see Fig. 1) is necessary [21]. 2D TTE and TEE have been used primarily to delineate and localize MVP, and to evaluate chordae integrity, the subvalvular apparatus, annular calcification, and left ventricular size and function. Determining which segment/scallop is prolapsing is difficult by 2D echocardiography, however, and the authors and others have found utility in 3D assessment [4,22–31].

The authors evaluated 34 patients in whom surgical intervention was undertaken for severe

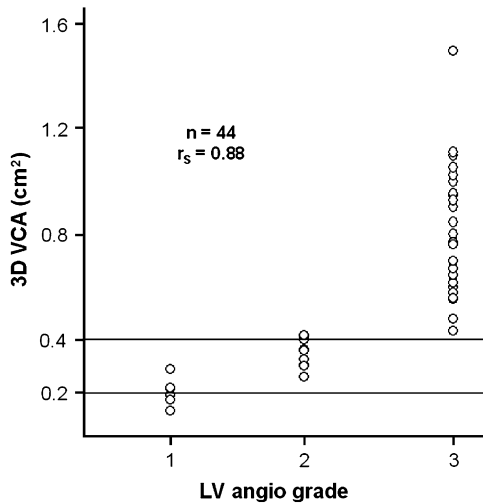


Fig. 3. Mitral regurgitation vena contracta area by live 3D color Doppler transthoracic echocardiography (3D VCA) correlated with left ventricular angiographic assessment. (Reproduced from Khanna D, Vengala S, Miller AP, et al. Quantification of mitral regurgitation by live 3D transthoracic echocardiographic measurements of vena contracta area. *Echocardiography* 2004;21:737–43; with permission.)

mitral insufficiency caused by MVP [22]. Parasternal and apically acquired 3D datasets were analyzed using the Q laboratory 4.1 software package. By cropping from the left atrial side to just above the mitral annulus, a short axis view was obtained. Individual prolapsing parts of segments or scallops were identified by their increased echogenicity from this view. To view all parts of the saddle shaped mitral valve, two or three oblique planes were used. This procedure was performed using the apically acquired dataset (Fig. 4) and the dataset from the parasternal window (Fig. 5). Segments/scallops were identified based upon their anterior (closer to the aorta) or posterior (deeper in the left atrium) and medial (closer to the ventricular septum), middle, or lateral positions as: A3 and P3, A2 and P2, A1 and P1 for posteromedial, middle, and anterolateral segments/scallops of the mitral valve, respectively (see Fig. 1). In this report, the authors accurately determined MVP location when compared with surgical findings with 95% sensitivity and 87% specificity, and with low inter- and intraobserver variability. The authors now routinely perform 3D TTE exams on all

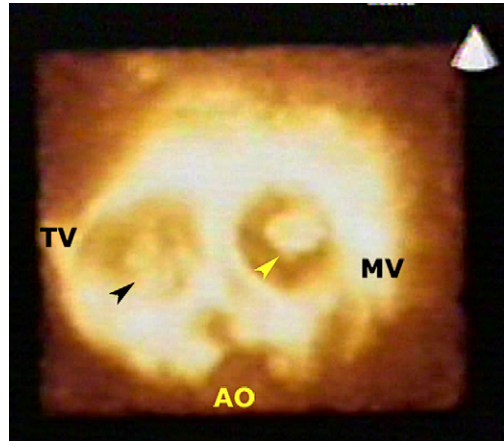


Fig. 4. Live/real-time 3D transthoracic echocardiography in the assessment of mitral valve prolapse. Apically acquired four-chamber data set was cropped from bottom to the level of mitral valve and tilted to view mitral (MV) and tricuspid (TV) valves en face. Yellow arrowhead shows prominent and echogenic prolapse of P2 scallop. Black arrowhead points to prolapse of the middle segment of septal TV leaflet. Abbreviation: AO, aorta. (Reproduced from Patel V, Hsiung MC, Nanda NC, et al. Usefulness of live/real-time 3D transthoracic echocardiography in the identification of individual segment/scallop prolapse of the mitral valve. *Echocardiography* 2006;23:513–8; with permission.)

patients the day before surgery to help guide, and hopefully improve likelihood of mitral valve repair.

Summary

Taken together, assessment of MR may play the leading role in the current echocardiography laboratory as an indication for a 3D TTE examination. In this role, 3D TTE offers incremental value over 2D techniques by providing a quantifiable measure of MR for accurate diagnostic grading and for reproducible longitudinal follow-up. Additionally, the ability to prospectively locate and quantify pathological changes provides guidance for surgical interventions, making preferable valve repair more likely. Because these direct measurements of valve anatomy and insufficiency are load-independent, time-efficient, and do not involve calculations based on assumptions, 3D TTE assessment of the mitral

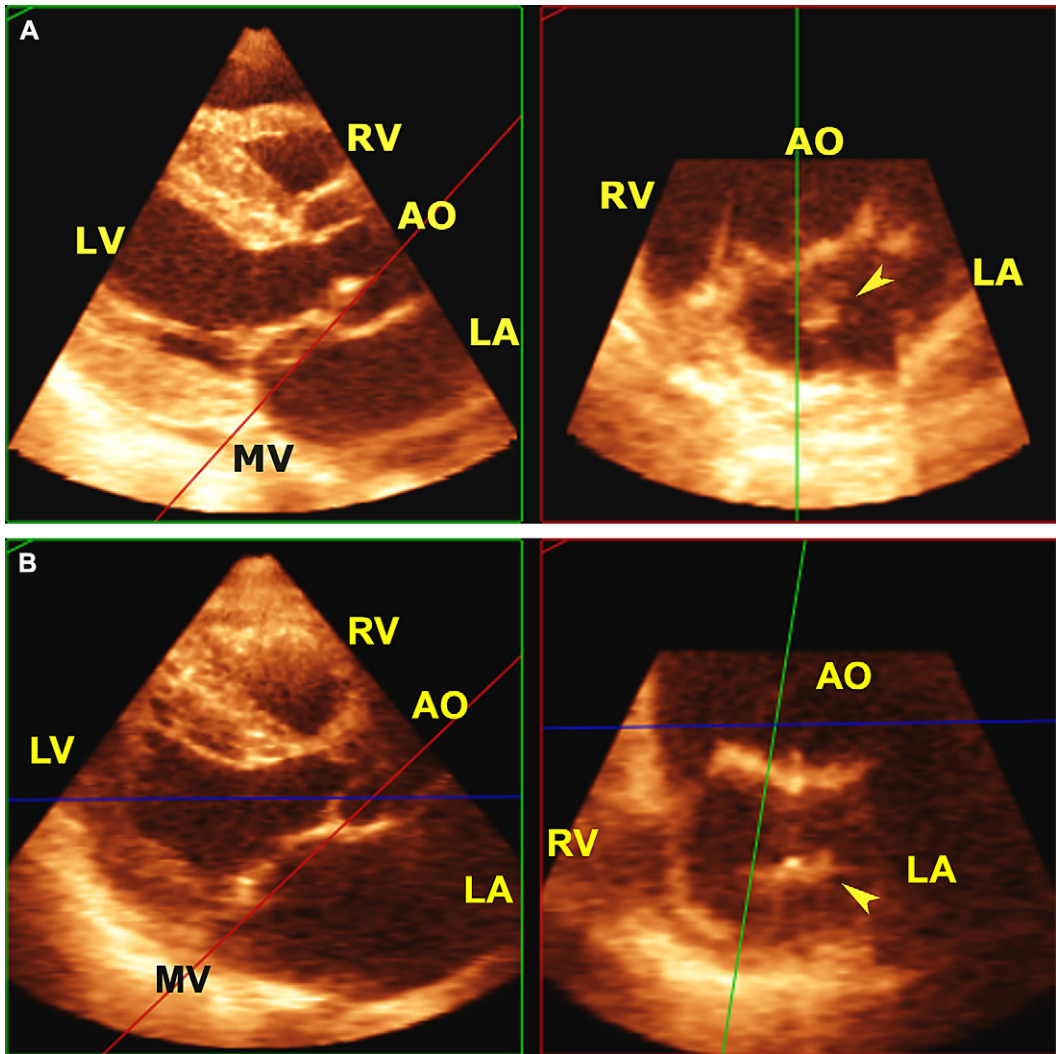


Fig. 5. Live/real-time 3D transthoracic echocardiography in the assessment of mitral valve prolapse using parasternally acquired data sets and offline Q laboratory 4.1 software. (A, B) The cropping plane (red) was placed at the level of mitral valve annulus in parasternal long axis view (left panels) and the prolapsing segment identified in the corresponding short axis view (right panels). The position of aorta (AO) and the right ventricle (RV) was used for anatomical orientation. Anterior mitral valve (MV) leaflet prolapse will appear in the left atrium anteriorly (adjacent to aorta), while posterior leaflet prolapse will be located more posteriorly. Depending on whether prolapsing MV leaflet tissue is located medially toward the ventricular septum, in the middle, or laterally, posteromedial (A3/P3), middle (A2/P2), and anterolateral (A1/P1) segment/scallop prolapse can be identified. Arrowheads show A2 prolapse in A and P2 prolapse in B. Abbreviation: LA, left atrium. (Reproduced from Patel V, Hsiung MC, Nanda NC, et al. Usefulness of live/real-time 3D transthoracic echocardiography in the identification of individual segment/scallop prolapse of the mitral valve. *Echocardiography* 2006;23:513–8; with permission.)

valve is an important addition to the echocardiography armamentarium.

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Three-Dimensional Transthoracic Echocardiographic Assessment of Aortic Stenosis and Regurgitation

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Noninvasive echocardiographic methods have revolutionized the assessment of patients who have valvular heart disease. Transthoracic 2D echocardiography (2DTTE) with color Doppler is the standard modality for the initial evaluation of the patient who has aortic valvular disease to help with the diagnosis and quantification of the severity of the condition. Color-guided continuous-wave Doppler, however, has important limitations in the assessment of aortic stenosis (AS) and aortic regurgitation (AR). This article outlines the limitations of conventional echocardiographic methods and describes the 3D echocardiographic assessment of AS and AR.

Aortic stenosis

Limitations of transthoracic 2D echocardiography/color Doppler

2DTTE/color Doppler has several limitations in the assessment of AS. Errors in the measurement of the left ventricular outflow tract (LVOT) diameter may occur because of calcification at the junction of the aortic root and the outflow tract. LVOT velocity also may be erroneous depending on how close or far from the aortic valve (AV) it is estimated. The AS jet has a 3D configuration and consists of a central core of high-velocity flow and an outer region of relatively low-velocity flow. Thus, even if it appears that the cursor lies parallel by color Doppler, it may not be in the central core

(Fig. 1) [1,2]. Occasionally, an eccentric stenotic jet escapes accurate recording despite meticulous technique, possibly leading to underestimation of the true gradient. In a significant number of patients, Doppler may overestimate AS severity because of various reasons. These include erroneous identification of a jet (the high velocity jet of mitral regurgitation can be mistaken for aortic regurgitation), contamination of the AS jet by the jet of mitral regurgitation, downstream pressure recovery, possible detection of localized high-velocity gradients [3] around the AV that do not represent the true gradient across the valve itself, nonrepresentative jet selection (for eg, a postextrasystolic beat), and coexisting stenotic lesions present in tandem [4,5]. The pressure recovery phenomenon (caused by the change of kinetic to potential energy downstream of the stenosed aortic valve) results in the overestimation of AS severity, especially in the presence of tubular rather than discrete AS, domed bicuspid or tricuspid aortic valves, a small ascending aorta (<3 cm width just beyond sinotubular junction), and a narrow LVOT diameter (≤ 2 cm) [6,7].

Incremental value of 3D transthoracic echocardiography

Live, real-time 3D transthoracic echocardiography (3DTTE) has the potential to become a new noninvasive modality that complements conventional techniques in the assessment of AS [5,8–12]. 3DTTE can be used for assessing the aortic valve and root morphology and also to calculate the valve area in aortic stenosis. First, a parasternal long-axis or apical five-chamber view of the AV

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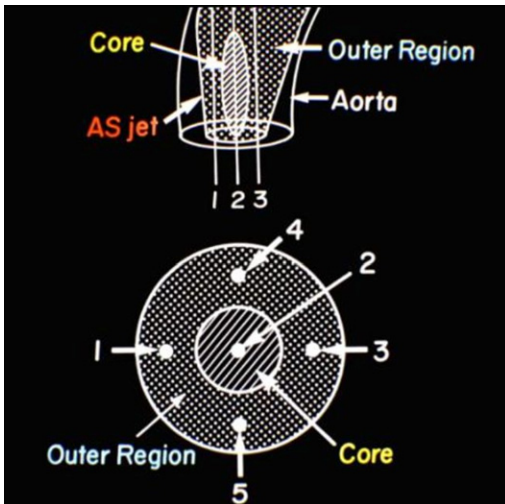


Fig. 1. Because a stenotic jet consists of a small central region or core of high velocity and a larger outer region of lower velocity, the continuous wave Doppler cursor must be positioned in the jet core in addition to being aligned parallel to the jet direction to measure the maximum jet velocity. The 3D structure of the jet may cause the continuous wave cursor to appear to be positioned correctly in the jet while, in reality, the cursor may not be placed properly in the jet core. Therefore, after the initial alignment of the continuous wave cursor in the visualized jet, minimal transducer angulations still are required to interrogate the jet core, which may be in the azimuthal plane. Failure to interrogate the core results in an underestimation of the peak transvalvular velocity and thus the severity of the stenotic lesion. In this illustration, the aortic stenosis (AS) jet is shown to consist of a central core, which has the highest velocity, and this central core is surrounded by an outer region of lower velocity flows. The highest velocity thus is obtained if the continuous wave Doppler cursor is aligned parallel to the core of the jet (cursor 2), while lower velocities are recorded if the cursor is positioned outside the core (cursors 1, 3, 4, 5). (Reproduced from Nanda NC (editor). Atlas of Color Doppler Echocardiography. Philadelphia: Lea & Febiger; 1989:112; with permission.)

is obtained in a standard manner using the 3D transducer. The patient then typically is asked to hold his or her breath for a few seconds to acquire and store several electrocardiogram-triggered subvolumes. These subvolumes are then time-aligned to render a full-volume 3D color data set. From the 3D pyramidal data set, a cropping plane aligned exactly parallel to the flow-limiting AV orifice (AVO), viewed in long axis, is used to obtain a short-axis 3D image of the AVO. The AVO area then can be measured accurately by direct

planimetry, because the face of any 3D structure is a 2D image. More conveniently, AVO orifice can be planimeted using an online software system provided by the manufacturer [5].

Direct imaging of the 3D contoured anatomy allows an excellent appreciation of spatial anatomy. 3DTTE also affords the opportunity to obtain 2D cut planes using the 3D data set, allowing imaging at any plane desired by the interpreter [13]. This is especially useful in assessing domed AVs and angulated orifices, as the cropping plane in the 3D data set can be aligned perfectly parallel to the flow-limiting tip of the stenosed AV orifice, allowing for accurate visualization of the aortic orifice, the area of which can be obtained by planimetry (Fig. 2). Another advantage of 3DTTE is the ability to estimate the AV orifice area in patients who have combined AS and other stenotic lesions in tandem like supra-valvular stenosis and discrete subaortic stenosis. These lesions can be studied in detail also [14]. In addition, measurements like LVOT width and LVOT/AV velocity that can introduce significant errors in calculating the AV orifice area using the continuity equation are not required with 3DTTE. On occasion, reliable identification of the aortic orifice may be practically impossible by 3DTTE in patients who have severe calcific AS caused by immobility of the valve leaflets. In this situation, color Doppler 3DTTE may be used to detect the initial appearance of flow at the onset of systole. These color Doppler signals can be cropped at the valve level using a parallel plane to estimate the orifice area.

Limitations of 2D transesophageal echocardiography

2D transesophageal echocardiography (2DTEE) has the advantage of allowing for direct estimation of the aortic valve area and superior quality imaging as compared with 2DTTE. It is especially useful when there is a poor acoustic window that prevents a satisfactory 2D examination. Careful advancement of the transesophageal probe from the supra-valvular area until it first encounters the tip of the aortic orifice is required, and it is dependent on operator skill. This is because overshooting the tip and measuring the area or near the base will underestimate the severity of stenosis. Depending upon the anatomic relation of the esophagus to the aortic valve, the 2D echocardiographic plane may not be aligned parallel to the flow-limiting tip of the aortic valve,

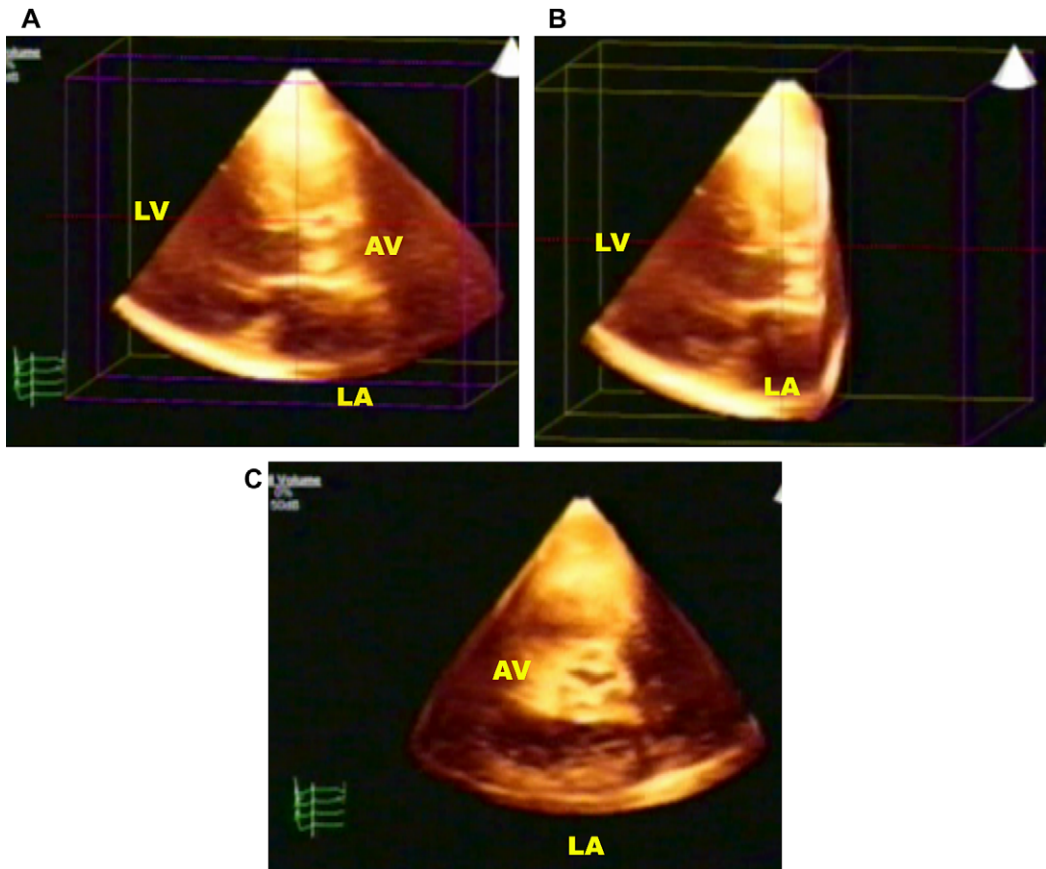


Fig. 2. Live, real time 3D echocardiography in aortic stenosis. (A) The aortic valve (AV) is viewed in the parasternal long-axis view showing calcified leaflets. The data set then was cropped from right to the level of the flow-limiting tip of the AV leaflets (B) and rotated en face to view the very narrow aortic orifice in short axis consistent with severe stenosis (C). The patient has the so-called acquired bicuspid aortic valve because of fusion of two of the three cusps. *Abbreviations:* LA, left atrium; LV, left ventricle.

leading to inaccurate estimation of the orifice. Other limitations include the semi-invasive nature of the procedure, associated patient discomfort, and the accompanying risks including laryngospasm, arrhythmias, aspiration and very rarely, esophageal rupture.

Incremental value of 3D transesophageal echocardiography

3DTEE accurately assesses the severity of AS and provides additional complementary information about valvular morphology as compared with 2DTTE. The TEE probe is inserted in the usual manner and 3D echocardiographic data acquisition is performed by transducer rotation at 3° to

5° increments over a span of 180° using a predetermined heart rate window [15]. It must be noted that slightest motion on part of the patient or examiner interferes with proper data acquisition, and the process has to be repeated. 3D images subsequently are reconstructed, allowing clear delineation of the aortic orifice, allowing direct and accurate planimetry [15,16]. The direct measurements obtained from 3DTEE would be expected to be more accurate than 2DTTE/TEE and cardiac catheterization. In addition, leaflet morphology, severity, and extent of valvular thickening and calcification can be demonstrated graphically (Fig. 3). 3DTEE is limited by the fact that 3D reconstruction of 2D transesophageal images is difficult and full of artifacts when there is patient

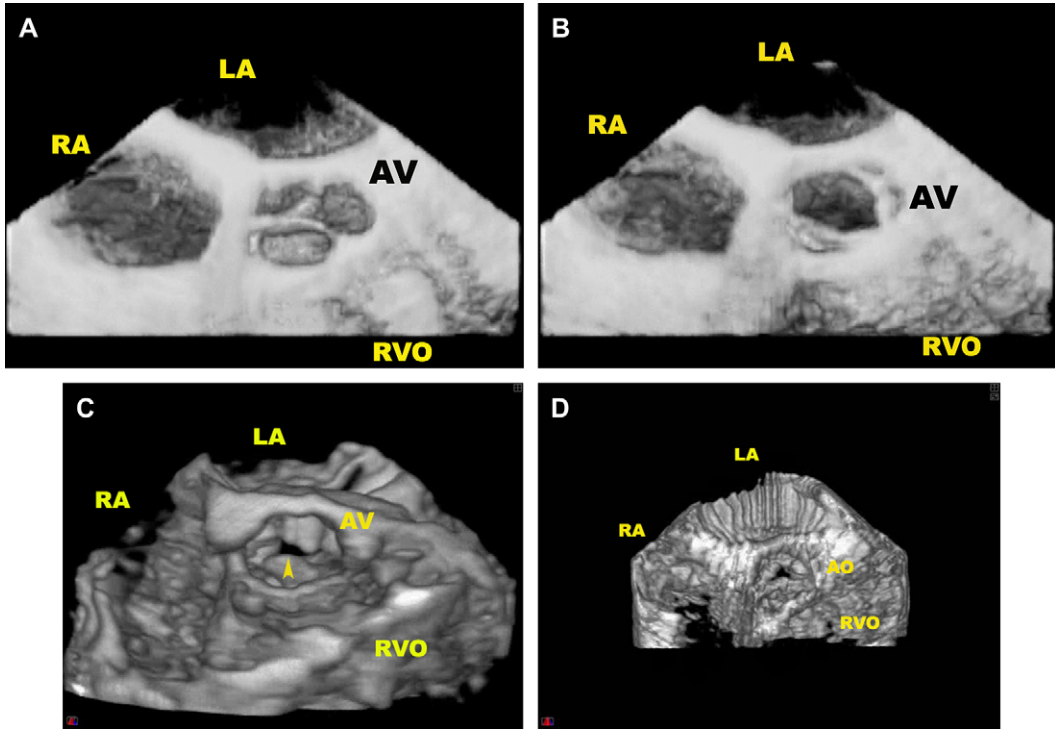


Fig. 3. 3D transesophageal echocardiographic reconstruction in aortic valve stenosis. Thickened bicuspid aortic valve without significant stenosis, shown in the closed (A) and open (B) positions. (C) Severe, calcified bicuspid aortic valve stenosis. Note the transversely oriented very small aortic orifice (arrowhead). (D) Another patient with calcific severe stenosis. Note that despite severe calcification, the tricuspid morphology of the valve is evident. *Abbreviations:* AO, aorta; RA, right atrium; RVO, right ventricular outflow tract. (Reproduced from Dod HS, Nanda NC, Baweja G, et al. Three-dimensional transesophageal echocardiographic assessment of aortic valve pathology. *Am J Geriatric Cardiology* 2003;12:209–13; with permission.)

motion and in scenarios like atrial fibrillation because of variation in RR intervals with consequent increased time for acquisition of cardiac cycles [12]. This would also be a problem in hemodynamically unstable patients who have wide variations in heart rate and respirations. 3DTEE is not commercially available as a live or real time modality so far.

Aortic regurgitation

Limitations of 2D transesophageal echocardiography/color Doppler

Conventional echocardiographic methods have several limitations in the assessment of AR just as in AS. The reliable and accurate quantification of the severity of AR using various qualitative and quantitative 2DTTE/color Doppler techniques

continues to be a challenge. This is primarily because they use a 2D plane to describe and quantify a 3D object. Quantitative methods of assessment like the volumetric approach and proximal flow convergence are limited, because they require assumptions that are mostly inaccurate [17]. Assessing the deceleration slope and pressure half-time of the continuous-wave Doppler spectrum is limited by the fact that the flow velocity profile is dependent on systemic vascular resistance and left ventricular compliance [18,19]. Measurement of the regurgitant fraction and volume by pulsed-wave Doppler determination of aortic forward flow combined with left ventricular volume by 2DTTE cannot be used in the presence of mitral regurgitation, and it requires assumptions of the left ventricular shape and of the aortic flow profile [20,21]. Although color Doppler allows measurements of different components of the jet by allowing

visualization of velocity flow maps in real time, there are important limitations. The proximal flow-convergence method for determining regurgitant volume is limited by geometric assumptions and also requires, in many instances, angle correction for AR [22,23]. The proximal jet width or height taken on the ventricular aspect of the aortic valve essentially represents the vena contracta (the size of the regurgitant jet within the leaflets and extending for a variable extent downstream into the LVOT) [24]. The regurgitant volume may be calculated by multiplying the vena contracta area (VCA) with the velocity time integral (VTI) of the continuous-wave Doppler waveform of the AR jet. Only one dimension of the AR jet is visualized in the two-dimensional parasternal long-axis or apical five-chamber views, however, and hence the VCA cannot be measured unless one makes the assumption that its shape is circular or elliptical, which is mostly incorrect [25]. Capturing the complex geometry of the vena contracta by obtaining a short-axis view of the aortic valve is limited when using two-dimensional echocardiography because of cardiac motion, making it difficult to ascertain whether one is measuring the jet width at the level of the aortic valve or at a level further downstream, where it tends to be larger [26]. In addition, it is difficult to ascertain that the 2DTTE short-axis plane is aligned exactly parallel to the AR jet imaged in short axis. This is especially important in patients who have eccentric AR. Studies have shown that the AR jet in short axis does not correlate with the aortographic criteria of AR severity as reliably as the proximal jet width divided by LVOT width [24,27].

Incremental value of 3D transthoracic echocardiography

3DTTE has demonstrated feasibility and accuracy in quantifying aortic regurgitation [25,28,29]. After completion of the standard 2DTTE, live and real time 3DTTE images can be obtained in the apical and parasternal views. Vena contracta width can be measured as the smallest neck of flow at the level of the aortic valve interposed between the area of flow acceleration and the jet [28,30]. Systematic cropping of the acquired 3DTTE data set can be used to measure VCA. The first step is obtaining the best AR jet in long axis from a parasternal long axis view or from an apical view (when the parasternal window is poor) by posterior-to-anterior cropping of the 3DTTE data set. Then the 3DTTE color

Doppler data set can be cropped from the aortic or left ventricular side to the level of the vena contracta, at or just below the aortic valve leaflets, in a plane exactly perpendicular to the AR jet viewed in long axis. The image now is tilted en face, and the cropped portion of the data set is added back to obtain the maximum area of vena contracta viewed in short axis in systole (Fig. 4). In patients who have more than one AR jet, the VCW may be taken as the sum of all individual vena contracta widths. Measurements of VCA can be obtained by direct planimetry or by using an online or offline software system like the Q-Lab (Phillips, Bothell, Washington) [28]. There are several advantages to using 3DTTE for assessing AR by the method described. The VCA can be multiplied with the velocity time integral obtained by color Doppler-directed continuous wave Doppler to accurately estimate the regurgitant volume. In addition, 3DTTE has the advantage of being fairly simple and more accurate, and it obviates the need to make mostly incorrect assumptions that the vena contracta is circular or elliptical in shape, which is done when using 2DTTE/Doppler [25].

A more confident estimation of the VCA is possible, because the entirety of the vena contracta can be appreciated and planimeted by using imaging planes exactly perpendicular to the AR jet in long axis. The 3DTTE-measured VCA essentially signifies the actual regurgitant hole in the aortic orifice in diastole [31,32].

Summary

3D echocardiography is a safe, noninvasive imaging modality that has the potential to be complementary to 2D imaging in the assessment of both AS and AR. 3DTTE can be used to increase the confidence level of assessment of AS and AR, especially when there is discordance between 2D echocardiographic and clinical findings. Unlike cardiac catheterization and 2DTTE/Doppler, which are indirect methods of assessment, 3DTTE allows direct visualization of the aortic valve orifice in aortic stenosis and therefore can be expected to be more reliable. En face delineation of aortic valve stenosis allows direct planimetry and thus accurate estimation of severity. In the assessment of AR, aortography has been the time-honored gold standard for assessing severity but is limited by factors such as different background densities between two orthogonal

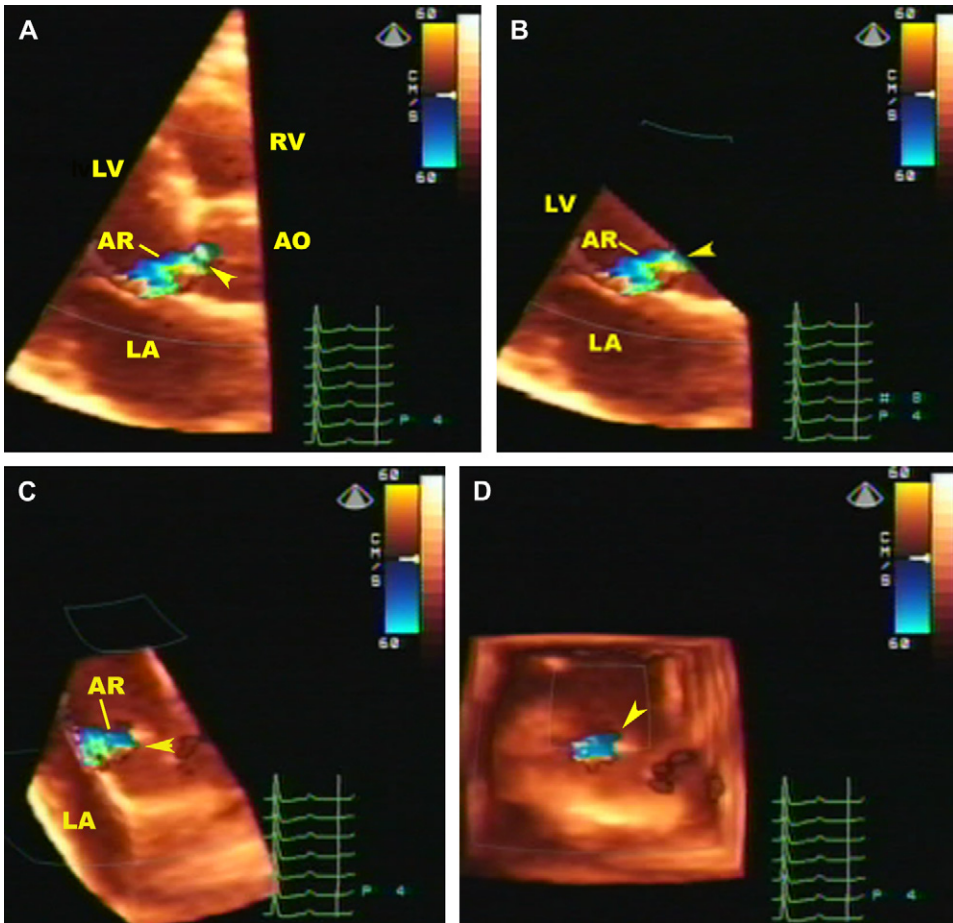


Fig. 4. Live 3D color Doppler transthoracic echocardiographic technique for assessment of aortic regurgitation (AR) vena contracta. The 3D color Doppler data set showing AR (A) is cropped using an oblique plane to the level of the vena contracta (arrowhead, B) and tilted to view it en face (C, D). The vena contracta then is planimetered. *Abbreviations:* AO, aorta; LA, left atrium; LV, left ventricle; RV, right ventricle. (*Reproduced from* Fang L, et al. Assessment of aortic regurgitation by live 3D transthoracic echocardiography measurements of vena contracta area: usefulness and validation. *Echocardiography* 2005;22:775–81; with permission.)

projections and the presence of dysrhythmias. Additionally, it is especially variable in patients who have enlarged ventricles [33]. Similarly, 2DTTE/color Doppler has several limitations as described previously. Because it is frequently eccentric in shape, the AR jet cannot be appreciated easily in its totality by 2DTTE. The ability of 3DTTE to dissect the complex geometry of a regurgitant jet makes it a more accurate method to appreciate the true geometry and spatial extent of jet flow, enabling accurate quantification of the severity of AR. Future improvements in technology and further research will continue to expand the role of 3DTTE for evaluating both AS and AR.

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Interventional Three-Dimensional Echocardiography: Using Real-Time Three-Dimensional Echocardiography to Guide and Evaluate Intracardiac Therapies

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The growing movement toward less invasive therapies for disease creates a need for improved imaging guidance as more complicated procedures are contemplated. Echocardiography, with its ability to provide real-time imaging and resolve soft tissue structures without using ionizing radiation or very special environments required by other imaging modalities such as CT and MRI, holds promise in addressing those needs. A major limitation of 2D echocardiography is its ability to image only in a thin 2D slice, making it distinctly unusual to see a device's relative position to its surrounding environment. To obtain an understanding of the 3D position of a device, the echocardiographer must acquire several views and then integrate them into a mental 3D model to determine the actual spatial location of the device. This interpreter-based approach has proven to be effective for many years as echocardiographers have applied it to the understanding of complex objects such as the mitral valve. Relying upon the operator to assemble a series of images in his or her head, however, is not feasible during an intervention, because the devices are moving constantly. Real-time 3D echocardiography (RT3DE) has the potential to address this limitation of echocardiography.

The use of RT3DE for this purpose is in its infancy. 3D echocardiography can visualize intracardiac tools such as biotomes, pacemaker wires, and ablation catheters along most of their course by the addition of depth or the elevation dimension, whereas typically with 2D echocardiography, only short segments are seen where they cross the imaging plane. The third dimension has proven to be helpful locating the right ventricular (RV) biotome used during endomyocardial biopsy [1–3]. Others have reported viewing pacemakers by means of 3D echocardiography. Finally, a few other anecdotal cases illustrate the use of the technology for general catheter location, potentially aiding movement of the catheter through the heart and detecting masses on the catheters. Early experiments also have been undertaken to examine the feasibility of 3D echocardiography to guide more complex intracardiac procedures.

Visualization of right ventricular biotome by 3D echocardiography

Like catheters, the RV biotome, used to perform right RV endomyocardial biopsies frequently can be visualized along its entire course by RT3DE as opposed to only part of the device by 2D echocardiography (Figs. 1 and 2). There have been three studies that have evaluated the use of RT3DE for guiding a biotome while performing RV biopsy. Most recently, in a study by Amitai and

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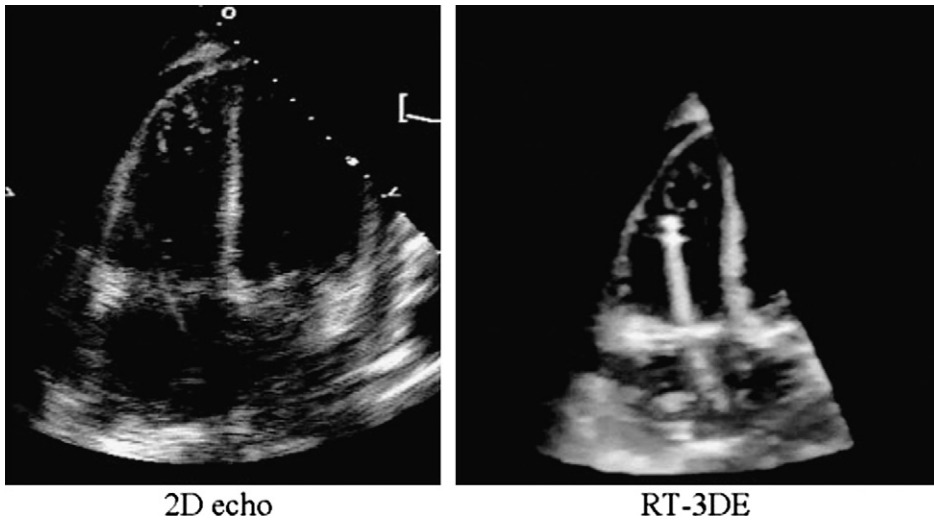


Fig. 1. Example of 2D (*left*) and 3D (*right*) echocardiography of a right ventricular biopptome for performing endomyocardial biopsy. Note that as opposed to the 2D image, which shows only a partial view of the biopptome and poor visualization of the tip, the 3D image shows the complete biopptome and tip. (Courtesy of D. Liang, MD, PhD, Stanford, CA.)

colleagues, 38 consecutive endomyocardial biopsies performed under fluoroscopic guidance in 26 patients were monitored using 2D echocardiography and RT3DE alternately [1]. It is important to emphasize that the operators of the biopptome were using fluoroscopy for their primary guidance and were blinded to the echocardiography images. A total of 243 biopsy attempts were made during the 38 endomyocardial biopsy procedures. The location of the biopsy could be determined in 74% of the biopsies by RT3DE compared with only 43% located by 2D echocardiography ($P < .0001$). With regard to specific location of the biopptome tip, RT3DE was superior to 2D echocardiography in 23 of 38 biopsies, compared with 1 of 38 for 2D echocardiography. In 14 of the 38 biopsies, there was no difference between 2D echocardiography and RT3DE. Arguably the most important finding of this study, despite it not being emphasized in the statistical evaluations, is that more than half the time when the biopsy site could be identified by echocardiography, it was suboptimal and potentially unsafe. It was noted in this study that no cooperation was needed between the biopsy operators and the echocardiographers to obtain diagnostic 3D images; this is in contrast to 2D imaging when there often has to be interaction between the two to capture the tip of the biopptome and the site of biopsy.

In a study by Scheurer and colleagues [3], RT3DE was performed in 28 consecutive children, aged 18 months to 16 years, who were undergoing endomyocardial biopsy. This group also found that RT3DE was a reliable method to properly

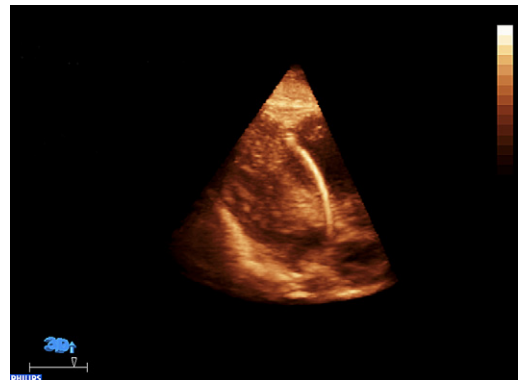


Fig. 2. Real-time 3D echocardiography shows the tip of the biopptome as it pulls away a piece of endocardium resulting in actual eversion of the right ventricular apex (in fact apical free wall, in fact a dangerous area for biopsy because of risk of rupture, nicely demonstrated by RT3D). (See video. Access video in the online version of this article at: <http://www.cardiology.theclinics.com>.) The still image shows the biopptome everting the right ventricular apex moments before extracting some myocardial tissue. (Courtesy of L. Ward, RCS, RVT, Bothell, WA, and G. Shirali, MD, Charleston, SC.)

direct the bioptome. Over time, the need for fluoroscopic guidance was less. There was no comparison done in their study to 2D echocardiography. Also, the operators were not blinded to the echocardiography results, and in fact over time, learned how to use the echocardiography results to minimize fluoroscopy time. This approach was particularly taken in children because of the issue with radiation in young children. It is interesting that of the nine patients who underwent biopsy with 3D guidance, one was a patient with intact pericardium done for evaluation of cardiomyopathy. Although this study was more a report of the operators' experience with RT3DE, there were no complications while guiding biopsy with RT3DE, particularly no new tricuspid valve flail leaflet or pericardial effusion.

In 2001, McCreery and colleagues [2] also reported the use of RT3D for endomyocardial biopsy. The early system used in this study did not produce a volume rendering of the volume containing the heart and the bioptome. Instead a series of 2D slices encompassing the region of interest was produced in real time. Despite the limitations of such a system, the position of the biopsy was identified. They reported that with fluoroscopic guidance, the bioptome was placed against the RV free wall, a suboptimal and potentially dangerous location, in 19% of patients. Further, 1% of patients had the bioptome in the coronary sinus.

In all three of these studies, the value of 3D echocardiography in tracking bioptomes in the heart through its more complete coverage of heart has been demonstrated.

Evaluation of pacemaker leads by real-time 3D echocardiography

The use of RT3DE for evaluation of pacing leads is reported sparsely currently and hence essentially is limited to a few case reports. Despite this, anecdotally, both authors have had experience with using 3D echocardiography for this purpose. Particularly, they have used RT3DE to evaluate the relationship between the RV pacing lead and the tricuspid valve leaflets and subvalvular apparatus in patients who have severe tricuspid regurgitation. The relationship between the pacing RV pacing lead and all three pacing leaflets often can be discerned (Fig. 3). Often in this situation the pacing lead is causing the tricuspid regurgitation by one of the following mechanisms:

- Perforation of a tricuspid leaflet
- Pinning one of the leaflet against the ventricular wall resulting in lack of coaptation

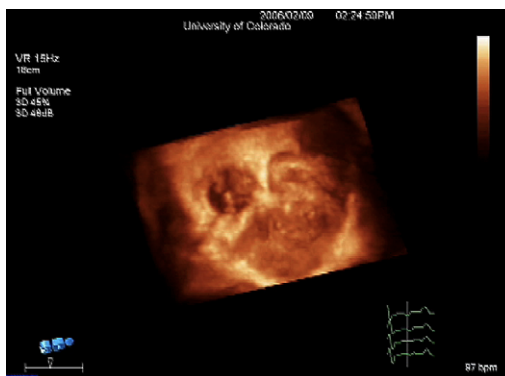


Fig. 3. Short axis of tricuspid valve with pacing wire passing through the tricuspid valve. In this case, the pacing wire can be seen in an optimal position between all three leaflets. (Courtesy of S. Popylisen, RDCS, Denver, CO, and L. Ward, RCS, RVT, Bothell, WA.)

Contributing to endocarditis of the lead/valve
A combination of one or some of the previous three

RT3D can help with all of these diagnoses.

RT3DE has been used to visualize the pacemaker lead in a patient with the wire perforating the interventricular septum (Fig. 4). The patient presented after a syncopal episode and had a chest radiograph, 2D echocardiogram, and CT scan, none of which were conclusive for malposition of the pacemaker. Interrogation of the pacemaker showed episodes of ventricular noncapture and



Fig. 4. Real-time 3D full-volume data set showing pacemaker present in the left ventricle, implying that it has perforated the interventricular septum. (From Daher IN, Saeed M, Schwarz ER, et al. Live 3D echocardiography in diagnosis of interventricular septal perforation by pacemaker lead. *Echocardiography* 2006;23(5):428-9; with permission.)

ventricular oversensing, suggestive of lead malfunction. A full-volume RT3D data set was acquired and conclusively showed the pacer wire in the left ventricle, diagnostic of interventricular septal perforation [4].

Masses, vegetations on pacer wires, catheters

RT3D has detected vegetations successfully on a pacemaker/defibrillator lead when other imaging technologies could not. The patient was a 71-year-old man who had history of cardiomyopathy with ejection fraction of 20% and nonsustained ventricular tachycardia. The patient had been treated with a biventricular pacer/defibrillator. The patient had had a transesophageal echocardiogram and a transthoracic 2D echocardiogram, and no definitive diagnosis had been made, but there was suspicion for vegetation, and the blood cultures were positive for methicillin-resistant *Staphylococcus aureus*. A full-volume RT3D echocardiography data set was acquired and cropped revealing a clear mass on the pacer wire (Fig. 5). The pacer wire subsequently was extracted. The diagnosis was confirmed and the patient did well [5].

Complex intracardiac procedures

The groundwork also has been laid in animal models for more complex intracardiac procedures guided by 3D echocardiography. Early work by Downing and colleagues demonstrated that even with a sparse array system adequate resolution

was achieved for visualizing tools and anatomy needed to repair atrial septal defects [6]. Following these studies, Suematsu and colleagues, beginning in 2003, undertook a series of studies to develop the use of 3D echocardiography for guiding atrial septal defect repairs. Initial studies were based upon a mechanically scanned 2D echocardiography probe [7]; however frame rate limitations led to subsequent studies being performed with 2D matrix transducers [8–10]. In these studies, 3D echocardiography demonstrated accurate suture placement (deviation 1.7 plus or minus 0.7 mm from desired target) and a 21% improvement in speed over 2D guided suture placement in an in vitro experiment [8]. The value of 3D echocardiography subsequently has been verified further in in vivo experiments [10]. Limited visualization of small details by RT3D echocardiography, however, have led to subsequent experiments combining videocardioscopic guidance with RT3DE [11].

RT3D echocardiography also has been shown to be a potential guidance tool for mitral valve repairs using an edge-to-edge technique [8].

Precise catheter placement also has been shown to benefit from RT3D echocardiography guidance. Cannulation of the coronary sinus has been shown to be improved significantly with epicardial RT3D echocardiography [12]. Intramyocardial injections, such as those that may be required for delivery of pharmacologic and biologic treatments, also have been shown to be guided accurately by RT3D [13].

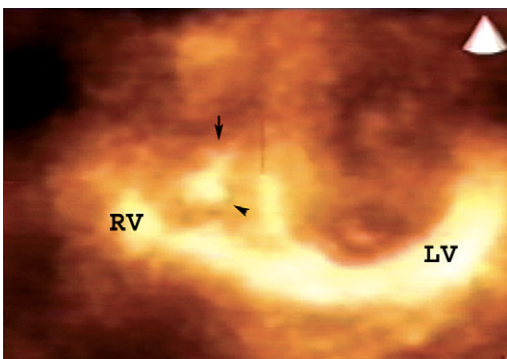


Fig. 5. A real-time 3D full-volume data set is shown with cropping revealing a mass on the pacing wire going through the tricuspid valve. (From Pothineni KR, Nanda NC, Patel V, et al. Live/real-time 3D transthoracic echocardiographic detection of vegetation on a pacemaker/defibrillator lead. *Am J Geriatr Cardiol* 2006; 15(1):62–3; with permission.)

The future

Surprisingly, electrophysiology procedures where catheter guidance perhaps would benefit most from RT3DE have yet to be studied extensively. This may be in part because of the limited ability of currently available transthoracic real-time 3D systems to image the atria where much of the anatomy relevant to treatment of arrhythmias is situated. The value of 3D anatomic information in electrophysiology procedures has been demonstrated by nonreal-time reconstructed 3D intracardiac ultrasound imaging [14–16]. Future developments in intracardiac real-time 3D ultrasound [17–19] and real-time 3D transesophageal echocardiography [20] may address the challenges posed in acquiring high-quality 3D visualization of the atria.

Presenting the information gathered by three-dimensional echocardiography to the physician performing the procedure is an additional area that may benefit from future work. 3D echocardiography data so far have been presented either as a volume-rendered image on a 2D display or by means of a series of 2D slices extracted from the 3D dataset. Although depth cues may be presented in the form of shading and other rendering techniques, they do not mimic the full set of cues that are available when directly viewing an object with one's eyes; thus information on spatial relationships that make 3D imaging powerful may be lost. Handke and colleagues explored the use of stereoscopic glasses to reconstruct some of the binocular cues lost in rendering 3D data onto a 2D display [20]. Wang and colleagues investigated the ability of a true 3D display to improve physician perception of physical relationships within 3D ultrasound data and found that with the use of a true 3D display, the time to perform a task requiring assessing spatial relationships between objects in the ultrasound image was reduced by nearly 50% when compared with volume-rendered images on a 2D display [21].

Summary

RT3DE already has demonstrated its utility in guiding intracardiac procedures. With further enhancements in image quality and display techniques, RT3DE has great potential for serving as an essential tool for visualizing minimally invasive and catheter-based therapies within the heart.

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Three-Dimensional Echocardiography for Studies of the Fetal Heart: Present Status and Future Perspectives

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Structural congenital heart disease (CHD) occurs in about 1% of live births and contributes a large proportion of the perinatal mortality [1–3]. Although it is also among the most frequently missed anomalies in prenatal ultrasound studies, prenatal detection can improve perinatal outcome significantly at least in certain types of CHD [4–7]. Prenatal detection rates depend on different factors like operator training and experience and vary widely [8–10]. Screening for and diagnosis of fetal heart disease are two distinct aspects of prenatal ultrasound, with differences in indications, levels of operator training and experience required, and the complexity of the technology used [11]. Teaching the correct technique for prenatal screening, for example, to include the outflow tracts in addition to the four-chamber view, is the main aspect of all attempts to improve prenatal screening for CHD [12]. Regarding technology, three-dimensional echocardiography has been shown to improve detection rates of cardiac malformations in adults and children [13], and it also promises to improve the prenatal diagnosis of CHD.

This article reviews the current clinical applications of three-dimensional echocardiography in fetal echocardiography. After a brief introduction and historical overview focuses on the application of fetal cardiac 3D imaging from automatically reconstructed mechanical sweeps, providing exemplary references of an already large and rapidly growing body of literature. Finally, the emerging

field of fetal cardiac volume and mass quantification and real-time 3D ultrasound systems using 2D matrix arrays is described briefly.

Two- and three-dimensional fetal echocardiography

Fetal echocardiography was introduced more than 25 years ago [14,15], and today is an established tool in prenatal diagnosis. Guidelines for 2D fetal echocardiography have been established [16,17]. Most routine studies aiming at the detection of structural heart disease are done at around 20 weeks of gestation, but attempts at even earlier gestational ages such as at 11 to 14 weeks also have been made and evaluated [12,18–22].

Over the last decade, prenatal 3D ultrasound has been used increasingly, both for general imaging and with regard to the fetal heart [23–26]. In addition to the general technical challenges of 3D ultrasound imaging of the human heart, in the human fetus, there are several additional specific obstacles.

At the time of the typical screening examination of the developing fetus in midgestation (at about 20 weeks' gestation), the fetal heart is about the size of a cherry, and the fetal heart rate is high, between 110 and 160 beats per minute, requiring high temporal resolution. Additionally, the fetus moves and assumes random positions, often making it impossible to obtain standard views. Fetal echocardiography in general, and three-dimensional echocardiography in particular, also are limited by the physical properties of the intervening tissue (eg, maternal abdominal wall, placenta,

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or amniotic fluid or lack thereof). Finally, an ECG cannot be recorded routinely (eg, for gating of reconstruction algorithms).

Conventional prenatal ultrasound screening for CHD can be time-consuming and involves a very operator-dependent acquisition and mental reconstruction of a sequence of individual cross-sectional images. Ideally, the instantaneous acquisition of a sequence of full fetal cardiac volumes (ie, 3D for at least one complete cardiac cycle) with the ability to review all possible sections from these volumes at any time during the cardiac cycle might facilitate fetal cardiac screening. Different technical approaches for fetal three- and fourth-dimensional screening have been used.

Reconstructed fetal 3D echocardiography

Reconstructed 3D echocardiography (as opposed to real-time 3D fetal echocardiography) currently is the dominant clinical technology. It makes use of computational power of the diagnostic ultrasound system, which stores large amounts of data, integrates cross-sectional information, and displays the volume data in various views or aspects, either as static or moving

displays. Typically, a sequence of sonographic data from a series of cross-sectional images is obtained over time and stored in the computer memory while the sonographer or an automated probe sweeps the ultrasound plane across the fetal heart. Then, off-line reconstruction yields either one cardiac volume acquired over a short period of time (less than 1 second) randomly with respect to cardiac cycle, or one virtual cardiac cycle comprising data from multiple heart beats that have been arranged using some form of spatial and temporal correlation [27].

For reconstruction of data obtained over periods longer than a fraction of a heart cycle duration, a form of assignment of temporal order (so-called gating) has to be applied to arrange the cross-sectional images according to the timing of their acquisition [28]. Another distinction in data recording of reconstructed 3D volumes uses the different technologies that have been employed with regard to acquisition of the sweep, either manual or automatic [13,29,30]. Manual sweeps and ungated 3D acquisition of B-mode sequences and using Power Doppler also have been used to study the normal and abnormal fetal heart and vasculature [31,32].

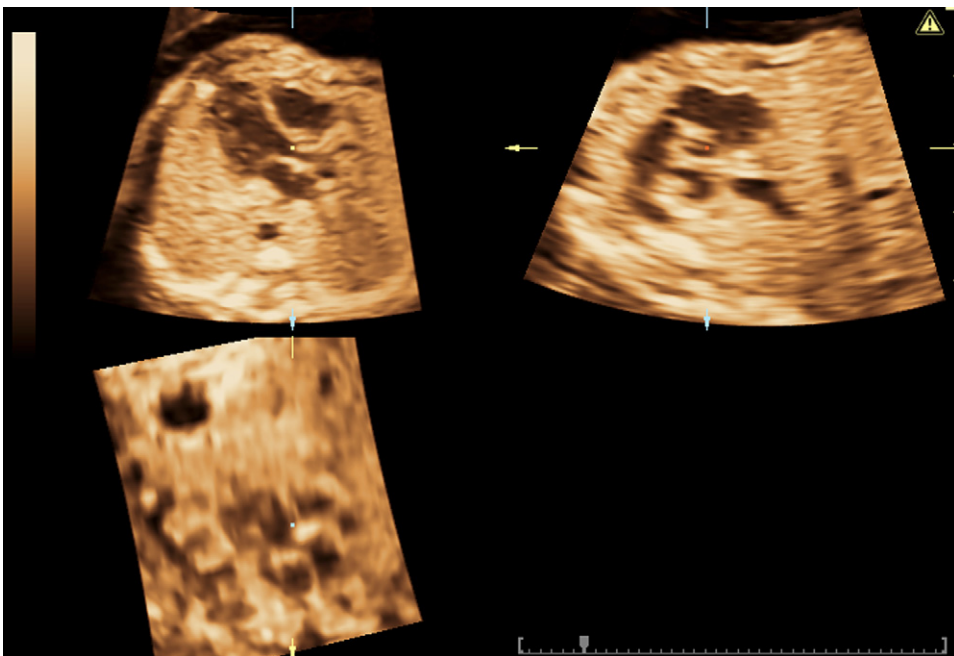


Fig. 1. Multiplanar imaging of a volume containing three orthogonal cross sections of a normal fetal heart (21 weeks' gestation) with the aortic valve in the center of all three planes. Top left: five-chamber view with the aorta arising from the left ventricle. Top right: adjacent aortic and pulmonary artery origin. Bottom left: third orthogonal plane.

Nelson and colleagues [13] were the first to suggest using tissue excursion concurrent with the cardiac contraction or relaxation to extract the temporal information regarding the cardiac cycle. This was used to compute the correct order in which cross-sectional images had to be rearranged to compensate for heart movements during the acquisition time of the volume. Another similar technique had been proposed using M-mode [33] and more recently using tissue Doppler data for fetal cardiac gating [34].

There were also successful studies using free-hand acquisition of volumetric data using power Doppler for vascular studies [31,32] or using an external position sensor attached to a conventional high-resolution 2D ultrasound system plus Doppler gating from the umbilical artery sampled immediately before free-hand sweep volume acquisition [35,36] or from concurrent Doppler recording of cardiac motion filtered for gating of a free-hand sweep over the fetal heart [37].

Spatial-temporal image correlation

The technique of computing cardiac gating from tissue excursion first was introduced into a commercially available ultrasound system by Kretz Ultrasound (now GE Kretz Medical Systems, Zipf, Austria) and was termed spatial-temporal image correlation or STIC. STIC now is incorporated in ultrasound systems also from other companies (Philips, Bothell, Washington; Medison, Seoul, Korea).

The most widely used approach is the STIC technique, because it has been integrated successfully in systems ready for clinical use. After its initial description [38–40], STIC has become a most valuable diagnostic tool for fetal echocardiography. Multiplanar imaging, reconstruction of 3D views (so-called rendering), the combination with color Doppler [41] and tomographic and invert mode [42–44], and the ability to quantify fetal

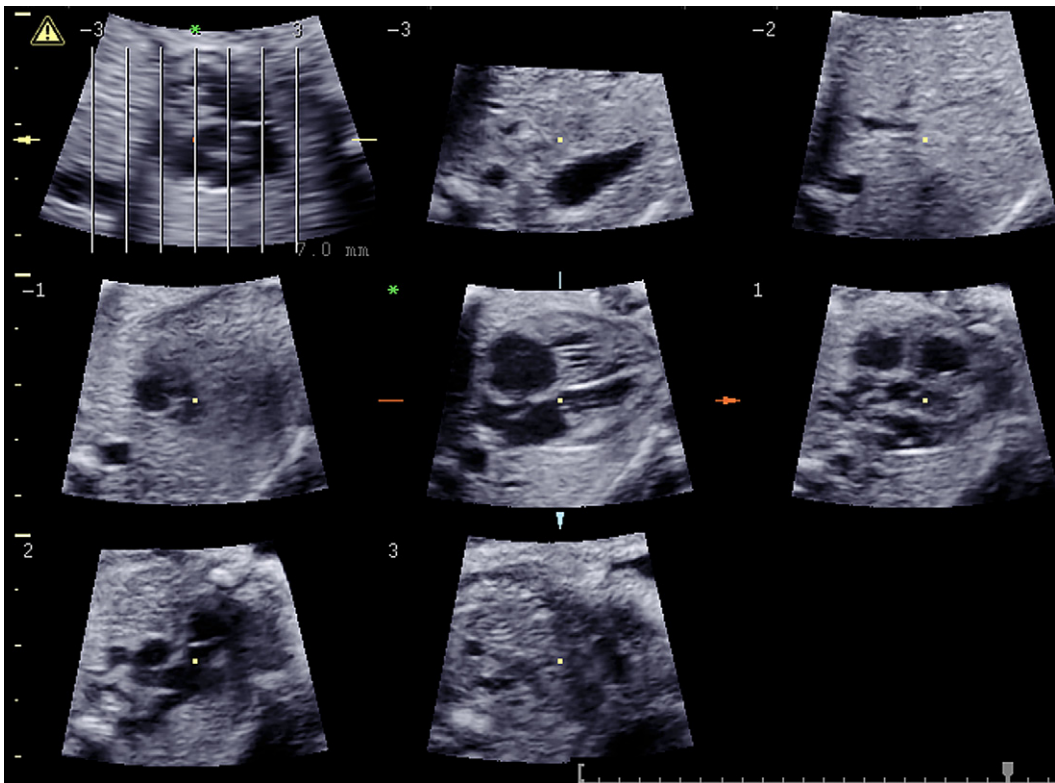


Fig. 2. Tomographic imaging of a volume containing parallel cross sections of the upper fetal abdomen (images 2 and 3 with the fetal stomach) and the thorax (image 1 with aorta and inferior vena cava; *indicating the level of the four-chamber view; images 1 and 2 with longitudinal sections of the ascending aorta and branching pulmonary artery, respectively, and image 3 with the upper mediastinum). The top left image shows a sagittal section orthogonal to the other views, indicating the spatial relationships of the horizontal sections (see also “Video TI abd thor.avi”).

cardiac volumes [45–47] have provided exciting new insights into the fetal heart.

Display modalities

3D volumes or volumes sequences of the fetal heart can be displayed in different ways. A cross-

sectional plane (or several planes orthogonal to each other) can be placed at any angle through the volume, enabling the examiner to interactively scroll through a volume either in the plane of acquisition (highest spatial resolution) or any other plane that is reconstructed (or calculated)

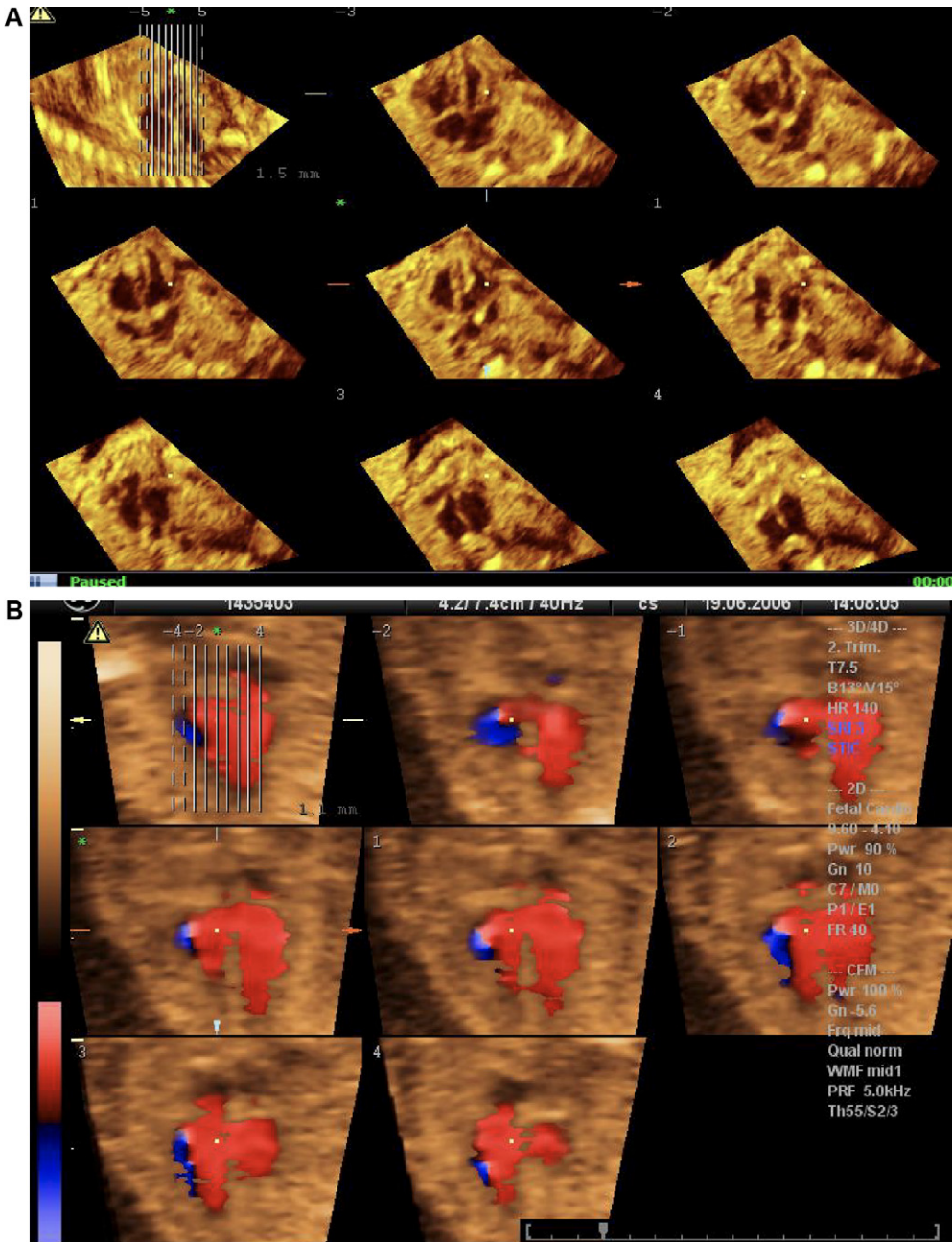


Fig. 3. Tomographic imaging through parallel planes neighboring the four-chamber view of (A) a normal fetal heart and (B) biventricular inflow with color Doppler.

from the volume. Multiplanar imaging typically describes a display with three orthogonal planes that can be rotated freely in the volume data set (Fig. 1). If a volume sequence has been generated encompassing a whole cardiac cycle, every structure can be inspected at different time points during the cardiac cycle.

Obtaining neighboring cross-sectional planes from a volume scan is particularly useful for the examining the great arteries, one of the key elements to be included in the fetal cardiac screening examination beyond the four-chamber view. In principle, the outflow tracts can be visualized using 2D echocardiography only by moving the transducer beam cephalad to obtain cross sections and by rotation to obtain views along the entire vessel. This may be difficult in many instances, however, because of fetal position, fetal movements, or lack of experience in obtaining these sections [48]. In 3D echocardiography, generating a stored volume (sequence) that can be manipulated off-line, these limitations can be eliminated or at least ameliorated. Because of the fixed relative position of the normal structures toward each other, it should be possible to navigate and display the advanced views like the outflow once the standard four-chamber view has been identified, provided the volume scanned covers all structures of

the heart and its vessels, and there is no extensive shadowing from adjacent bones (ribs, spine, or a fetal extremity between the transducer and the heart). Failure to be able to do so may even indicate structural anomalies. In most clinical situations, the acquisition of a fetal cardiac volume will be done from the four-chamber view, and cross or longitudinal sections of these vessels can be extracted from the volume following a simple algorithm (eg, the spin technique) [48].

Traditionally, 2D echocardiography uses imaging planes based on standard sections aligned with one of the ventricular axes. Other digital imaging modalities like MRI and CT typically display and describe the structures in relation to standard anatomical orientations (sagittal, coronal, transverse) as stacks of parallel planes or cross sections. 3D echocardiography can combine the accepted 2D imaging and orientation standards to provide a combination of both approaches. The term tomographic imaging refers to the simultaneous display of several cross-sectional planes through the same volume similar to a typical CT or MRI image sequence (Fig. 2 and accompanying “Video TI abd thor.avi”).

Available at: “Video TI abd thor.avi”

The tomographic representation of parallel sections through a volume obtained by ultrasound

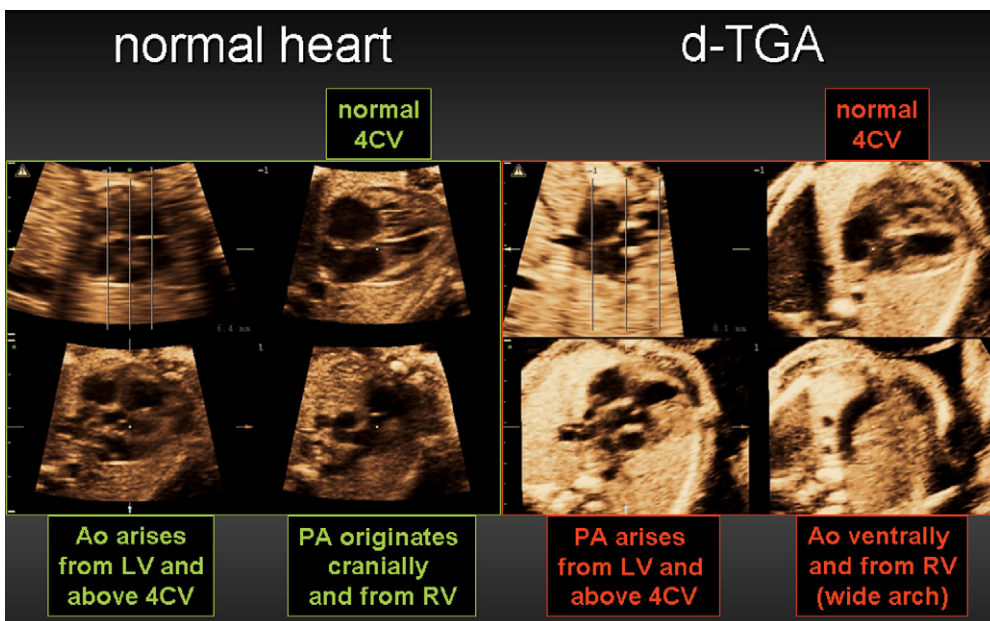


Fig. 4. Tomographic imaging derived from spatial-temporal image correlation sequences showing a normal fetal heart (left) and a fetal heart with d-transposition of the great arteries displayed using the same settings for parallel sections at three different levels at and above the four-chamber view (see also “Video TI_nl_TGA.avi”).

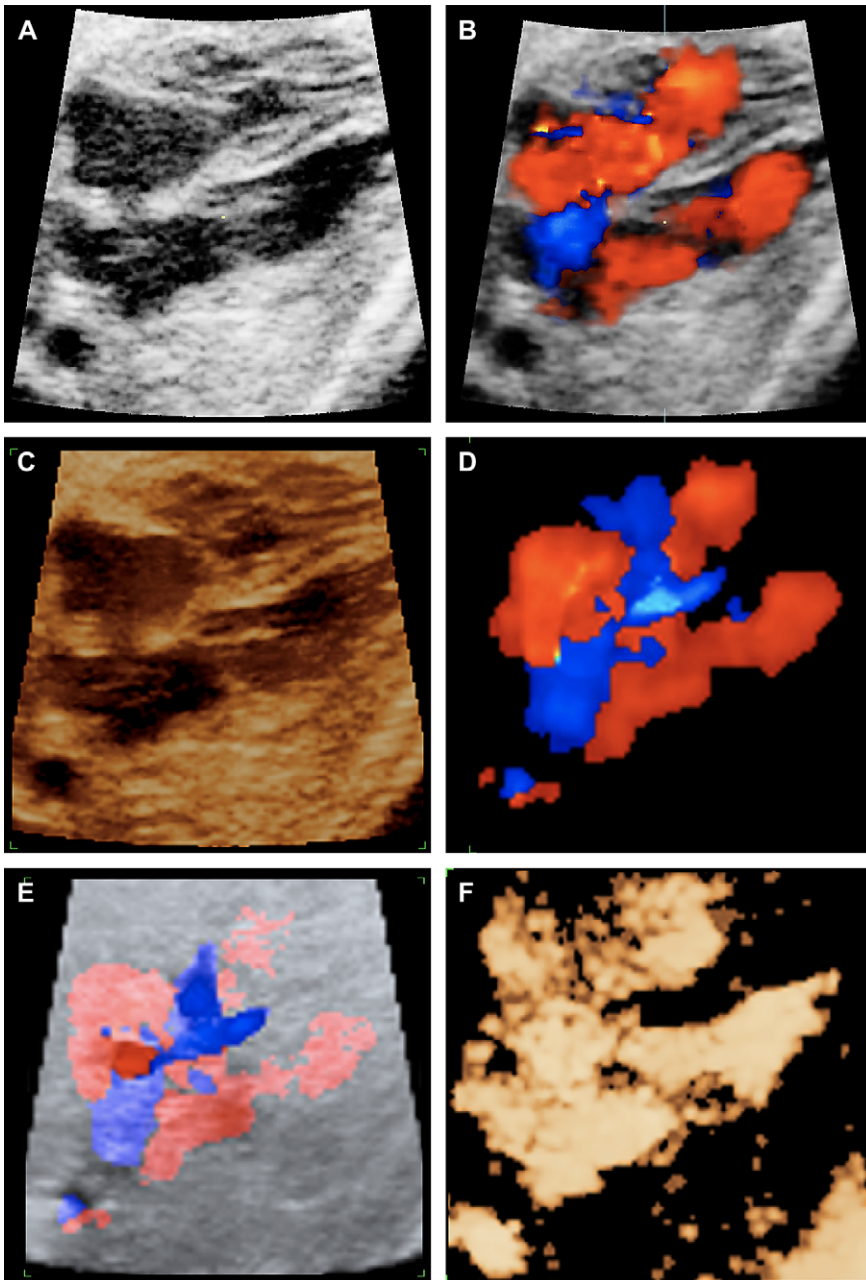


Fig. 5. Examples of cross-sectional and rendered views of a volume acquired from an initial four-chamber view (normal fetal heart at 29 weeks' gestation). All images were generated from the same diastolic frame seen from caudally. *Cross-sectional images:* (A) B-mode. (B) Color duplex with biventricular inflow (in red). *Rendered images:* (C) Surface-rendered view, cropped to display only the cranial half of the heart. (D) Color-only rendering of the whole volume with display of hepatic veins and inferior vena cava (blue) and ventricular inflow. (E) Glass-body region of interest as in (D), but with transparent tissue rendering over color Doppler. (F) inversion mode (thin volume slice cropped to display only the four-chamber plane).

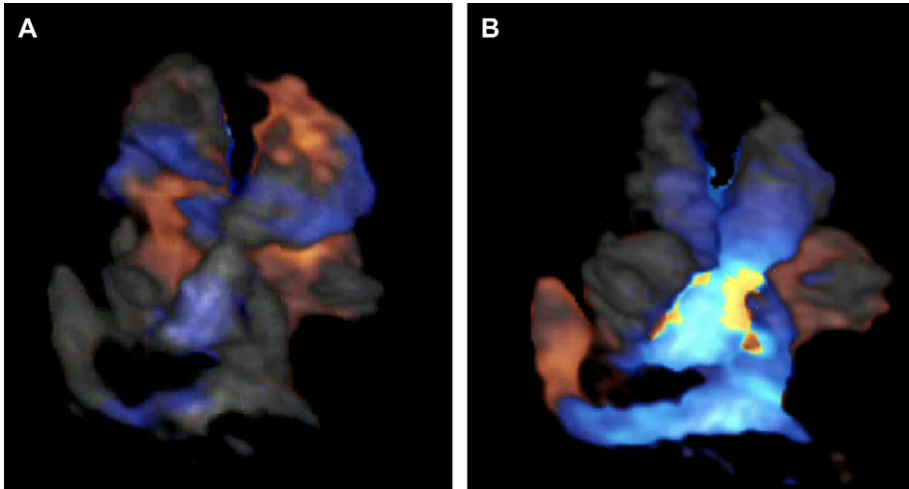


Fig. 6. Color invert mode of a normal fetal heart at 29 weeks' gestation. Full cardiac volume rendering (seen from cranially) in (A) diastole and (B) systole.

has been given different commercial names (“Multislice,” “Tomographic ultrasound imaging/TUI,” “iSlice”). Tomographic imaging of three-dimensional volumes of the fetal heart (Fig. 3) can be used to elegantly display different normal or structurally abnormal planes from one insonation angle (Fig. 4 and video “TI_nl_TGA.avi”).

Available at: “TI_nl_TGA.avi”

Taking into consideration the anatomy of organ growth, tomographic imaging has been both tailored to the growing heart and applied to CHD successfully [49]. Algorithms (both semi-automatic and automatic) have been described to successfully display the relevant cardiac structures in one or several tomographic and/or multiplanar panels comprising sections generated semiautomatically [50–52]. In the newest release of the Voluson ultrasound system (GE Kretz), such an automated approach (VCAD) is now available in a commercial system [53].

The different rendering (or rendered) modes are an alternative to the simple or complex cross-sectional display modes. Rendering describes the display of either external or internal surfaces of organs with data derived from multiple 2D sections. Using certain values for display thresholds (suppression of weaker signals mainly between the transducer and the object to be displayed), transparency (reduction of tissue signals, giving them a transparent appearance and revealing underlying objects) and shading produce photo-realistic 3D appearances on a two-

dimensional display like a computer monitor or in a printed image. Surface rendering originally was developed to display the outer surfaces of

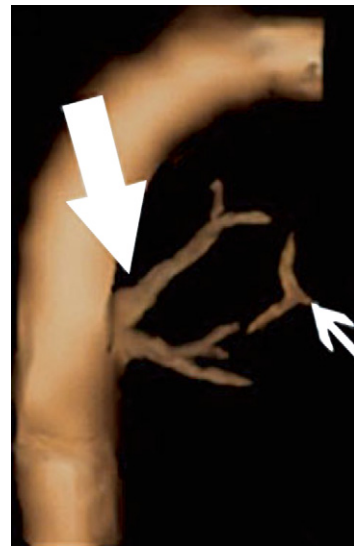


Fig. 7. B-flow 3D rendering from a spatial-temporal correlation volume of a major aortopulmonary collateral artery (*small arrow*) (large arrow: pulmonary arteries). (From Volpe P, Campobasso G, Stanziano A, et al. Novel application of 4D sonography with B-flow imaging and spatio-temporal image correlation (STIC) in the assessment of the anatomy of pulmonary arteries in fetuses with pulmonary atresia and ventricular septal defect. *Ultrasound Obstet Gynecol* 2006;28:40–6; with permission.)

solid objects like the fetal face in three dimensions [54]. In a surface rendering mode of the fetal heart, however, cropping into the heart will display its internal surfaces [55,56], for example cutting the heart in halves at the level of the four-chamber view or from an en face view of the valve plane, generating a more plastic impression than the thin slice usually displayed in a conventional B-mode image (Fig. 5). A modification of the surface-rendering mode, the so-called inversion mode (or invert mode), displays only fluid-filled spaces (see Fig. 5F), because it shows negative images of surface rendering. The inversion mode has been shown to produce digital casts of the fetal heart and vasculature both in normal and structurally abnormal cases [43,57–59].

STIC also can be used to include color and power Doppler information, generating detailed structural and functional cardiac information and even angiography-like images including directional information [26,41,60,61]. Power Doppler, with its high sensitivity even for low flow velocities, can display not only ventricular and great

artery anatomy, but also extracardiac structures like pulmonary vasculature, teratoma, and chorioangioma [62,63]. The most recent addition to the color Doppler rendering modes from STIC volumes is Color Invert mode (currently available on the HD11 ultrasound system, Philips Medical Systems), combining the anatomic detail of fluid-filled structures in invert mode with the dynamic information of color Doppler (Fig. 6).

Another technically different approach for flow detection, B-flow, extracts Doppler-independent flow information generated from a particular digitally processed B-mode that retains the conventional gray-scale information and spatial resolution (B-flow, GE Medical Systems). B-flow, combined with STIC and these rendering techniques, provides even more detailed visualization of small normal and aberrant vessels [42,64] (Fig. 7).

Another promising new application of volumetric fetal echocardiography (from STIC and from real-time 3D echocardiography) is the functional and quantitative analysis of the dynamics of cardiac ventricular volumes and of chambers

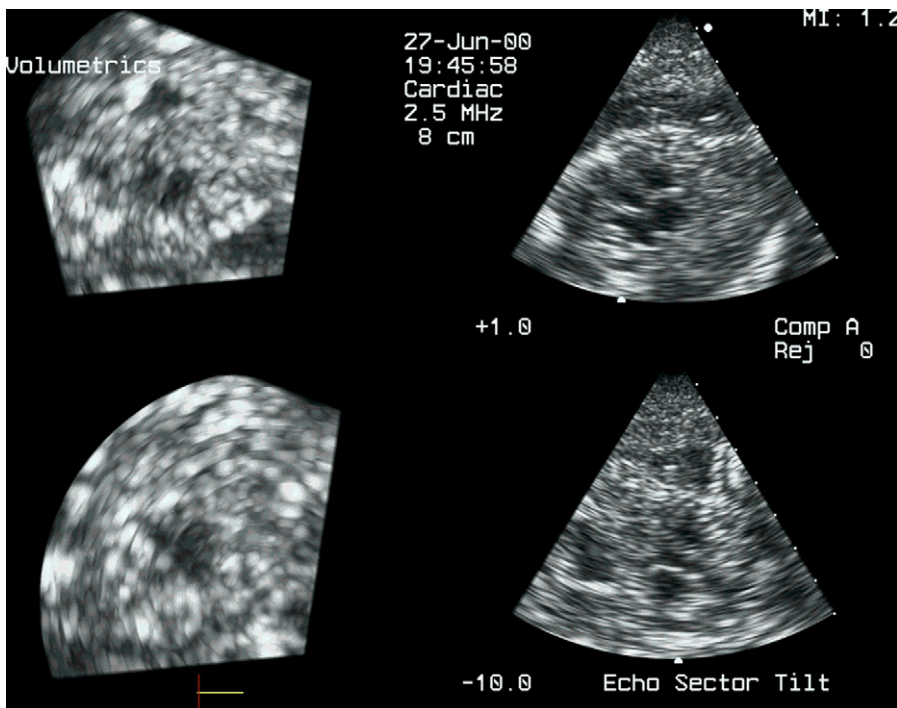


Fig. 8. Real-time fetal 3D echocardiography using the first-generation 2D matrix array (Volumetrics, 2.5 MHz matrix transducer). Fetal echocardiography at 25 weeks' gestation shows the acquisition orientation (four-chamber view on the top right, a section perpendicular to it (through the aortic outflow) in the lower right and two perpendicular images from the elevation plane (cross sections through the two ventricles in short axis) (see also "4CH_25_vlm.avi" and the article by Tutschek et al (2000) [71]).

masses. It can be done using different technical approaches from B-mode or inversion mode and has been shown to be feasible and sufficiently accurate [26,45–47,65].

Finally, volumetric ultrasound, because of its digital nature and off-line analysis feature, naturally lends itself to the application of telemedicine, enabling the separate the acquisition of data (cardiac and other volumes or volume sequences) from manipulation, extraction of relevant views, and interpretation [66–68].

Real-time fetal echocardiography using 2D matrix array transducers

Real-time 3D echocardiography acquires volume sequences of sonographic data

instantaneously by using transducers with a 2D array. These 2D arrays insonate volume blocks rather than tissue cross sections. Theoretically, real-time 3D ultrasound with 2D array transducers is the direct and easiest way of acquiring 3D data of the fetal heart, because it obviates the need for fetal gating, a potential source of artifacts [69].

Its wide-spread application, however, so far has been limited by the lower temporal and/or spatial resolution. For high-resolution fetal echocardiography, gated reconstruction to date provides superior spatial and temporal resolutions approaching 2D B-mode quality. Despite advances like STIC, however, the reconstruction required precludes the ease of real-time assessment and makes this method prone to motion

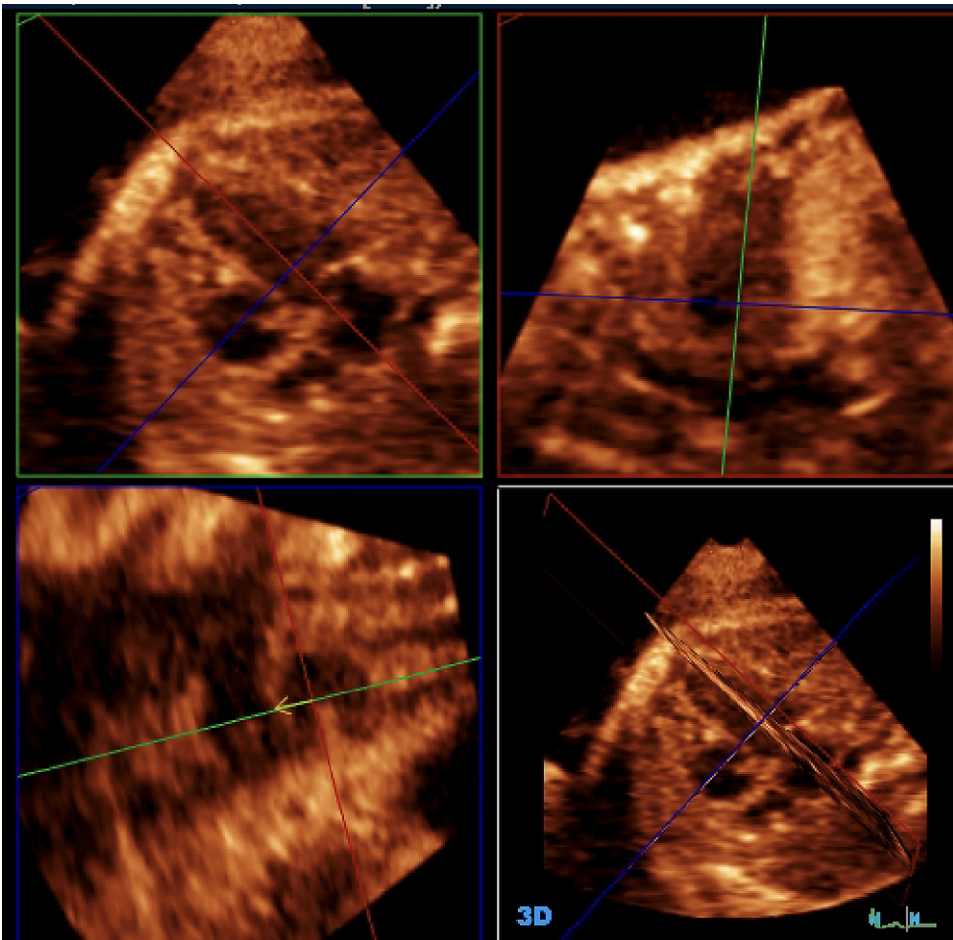


Fig. 9. Real-time fetal 3D echocardiography using a fully electronically steerable two-dimensional matrix array transducer (x3-1, iE33, Philips Medical Systems, Bothell Washington). (A–C) Cross-sectional images. (D) 3D niche-view of a normal 29-week-old human fetus.

artifacts. In contrast, real-time 3D echocardiography acquires a sequence of pyramidal volumes virtually instantaneously using a 2D matrix phased-array transducer. Although theoretically superior, with regard to fetal echocardiography the main limitation so far has been image resolution. The first prototypes of matrix array transducers had only 256 active elements and limited image quality. It still could be applied to fetal studies acquiring 20 volumes per second in an initial study [70]. Spatial resolution, however, is limited and inferior to comparable 2D systems [71] (Fig. 8 and video “4CH_25_vlm.avi”).

Available at: “4CH_25_vlm.avi”

The second generation of matrix array transducers is based on 2D arrays with about 3000 active ultrasound elements. This ultrasound system provides rendered images of the scanning sector in real time with a temporal resolution of 40 to 50 ms, equivalent to a volume rate of 20 to 25 images per second. Sklansky and colleagues [70] were the first to report a initial feasibility fetal echocardiography study. Maulik and colleagues [72] used the same 4 MHz 2D array transducer to study fetal hearts with CHD, suggesting that

this technology could be a significant tool for prenatal diagnosis and assessment of congenital heart disease in the human fetus. More recently using a sweep modification, especially for larger fetal hearts that cannot be acquired instantaneously using this transducer, an acceptable diagnostic rate could be shown [73]. Fig. 9 shows an example of a normal fetal heart visualized in real time three dimensionally using such a system. The utility of this transducer designed for adult studies for detailed fetal echocardiography remains limited, however, by its resolution, which is still inferior to the typical high-resolution 2D systems for fetal studies currently in use, and by its relative dependency on cardiac gating. Acar and colleagues [74] performed real-time imaging using such a system. They applied two modalities, the live 3D and the biplane scanning modes, in normal and CHD fetal hearts and could complete successfully the examinations in the majority of fetuses. Also in their study, the main limitations were comparatively low resolution and 3D artifacts.

There are technical advantages to real-time 3D echocardiography and the subsequent data processing, however, that already can be exploited



Fig. 10. Fetal echocardiography with a higher resolution program for fetal volumes running on the Philips IU22.

using such a system. Semiautomatic volume quantification of cardiac cavities has been reported [33,75]. Using a 3 MHz 2D matrix array transducer for real-time 3D fetal echocardiography (Figs. 10 and 11) followed by quantitative analysis of the volumetric loops showed that semi-automatic endocardial border detection can generate volume-time curves of fetal ventricular function and that ventricular volumes and ejection fractions can be calculated in human fetuses between 20 weeks and term (Fig. 12) [65]. These data compare favorably with volumetric measurements derived from STIC measurements [65] using a validated technique [45,46].

Real-time 3D echocardiography theoretically obviates the need for cardiac gating (no artifacts from fetal or maternal body movements). With improving transducer technology (mainly higher transducer frequencies), it can be speculated that real-time three-dimensional echocardiography using 2D matrix array transducers will become the dominant technology. As a first step in this direction, a 7 MHz 2D matrix array transducer

was introduced recently for a commercially available ultrasound system (iU22/iE33, Philips, Bothell, Washington). Initial studies show an encouraging resolution for fetal studies, but its usefulness for fetal echocardiography remains to be determined.

Summary

The present status of instrumentation for obtaining high-resolution three-dimensional images of the fetal heart is in transition. Expected advances should include large aperture matrix arrays more suitable for obstetric scanning—and with frequency ranges from 4-8 MHZ, flexible volume adjustment acquisition to target the fetal heart area with highest line density and frame rate available, and ultrasonic navigator sampling to clock motion of a region within the fetal heart as a trigger for obtaining full volume coverage when truly live scanning coverage is not capable of encompassing the entire cardiac volume. Continuing advances will change fetal imaging and

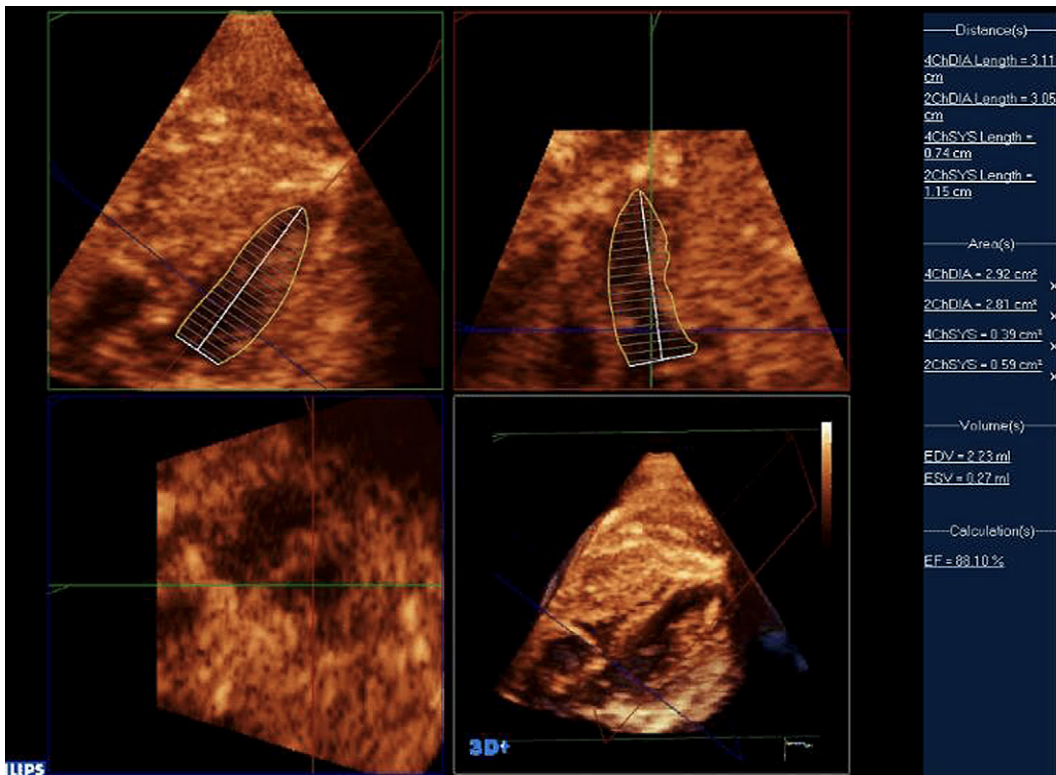


Fig. 11. Fetal left ventricular volume calculation: volumes measured with QLab version 5, no longer requires an apex-up orientation.

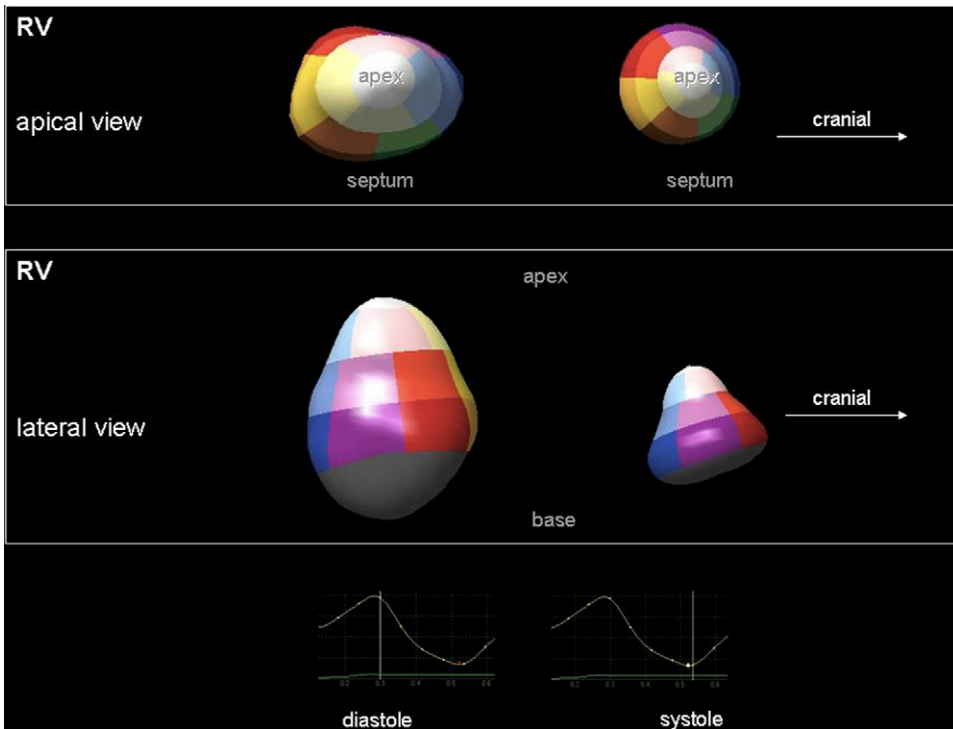


Fig. 12. Virtual endocardial casts of the normal human right cardiac ventricle in a 28-week fetus in diastole and systole and endocardial volume curves, generated using semiautomatic volume calculation software from a volume loop acquired using real-time 3D echocardiography (QLab 3DQAdvanced and x3-1/iE33; Philips Medical Systems).

provide new methods for diagnosing heart disease prenatally and understanding the in-utero natural history of congenital heart diseases by providing improved methods for visualization, and more importantly, for quantitatively evaluating fetal cardiac chamber volumes. New technologies will require new protocols for evaluation and new skills that will need to be learned by sonographers and by obstetricians/perinatologists and pediatric cardiologists.

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Three-Dimensional Echocardiography in Congenital Heart Disease

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Matrix array technology has brought 3D echocardiography into the clinical practice of cardiology [1–3]. Arguably, this advancement [4] is most notable in the field of pediatric cardiology [5,6]. Full-volume acquisitions now can be undertaken in the youngest of infants with excellent image quality. With increasing experience, on-line, live, or simultaneous 3D imaging can be performed, with scanning of the cardiac structures in a true four-dimensional perspective. Moreover, software programs allow for rapid analysis of both global and regional ventricular function. Dedicated software systems provide for summation of disc methodology, which can be applied to measure right and single ventricular size and function. Newer developments in semiautomated border detection have decreased the time for volume measurement determinations, and now allow for complex analysis of regional left and right ventricular function. As familiarity with 3D echocardiography has been gained, a compendium of experienced-based knowledge has been developed to allow recognition and hence rendering of complex congenital heart defects in a 3D imaging domain. Certainly, on-line rendering has aided this process, providing instantaneous image feedback and improved cropping of the desired 3D planes and perspectives of complex congenital heart defects.

A very significant important recent advancement in the application of 3D echocardiography to congenital heart disease has been the development

of small dedicated matrix array transducers (Fig. 1). This transducer has a much higher transmit frequency, resulting in increased resolution. Moreover, the frame rate has improved, as well as focusing and imaging in the near field. The much smaller transducer allows for probe placement in either the suprasternal notch or between the rib space for precordial imaging. This article illustrates the clinical application of 3D echocardiography in congenital heart disease.

Atrial septal defects

As has been published in the medical literature, 3D echocardiography can visualize secundum atrial septal defects as they exist in anatomic reality [7]. Rather than assuming the size and shape of the atrial septal defect by visualizing the edges of the defect in multiple 2D imaging cut planes, 3D echocardiography provides a visualization of the entire circumference of the defect (Fig. 2). In particular, secundum atrial septal defects can be rendered from a right or left atrial en face view. An important observation, based on three-dimensional echocardiographic imaging, was that secundum atrial septal defect changes size and shape during the cardiac cycle. Accurate delineation of atrial septal defect size is important in selecting appropriate sized devices for cardiac catheterization device closure. Thus, because of the irregular shape of such defects, and change in size during the cardiac cycle, 3D display of secundum defects would be essential for accurate size measurement. A myriad of 3D echocardiographic rendered planes can detail the anatomic relationship of the defect to other cardiac

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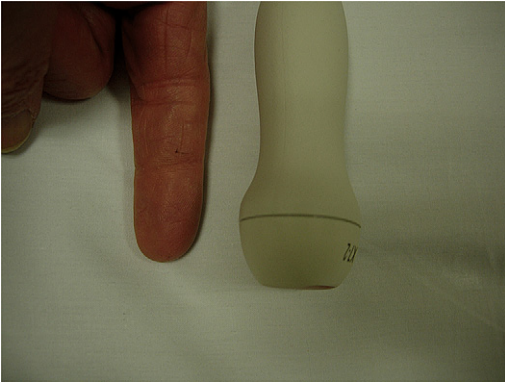


Fig. 1. Example of a small matrix array transducer with imaging frequency of 4 to 6 MHz.

structures, including the superior and inferior vena cava, pulmonary veins, atrioventricular valves, and ascending aorta. Perhaps the most important anatomic relationship to comprehend is the atrial septal defect device to the aortic wall. Although rare, reports have documented aortic wall rupture years after device placement. The amount of retro-aortic rim can be analyzed readily from a succession of serial cut planes from superior to inferior parallel planes. 2D images portray the image in a singular cut plane, which may provide a poor representation of the true extent of the atrial septal defect that is deficient in

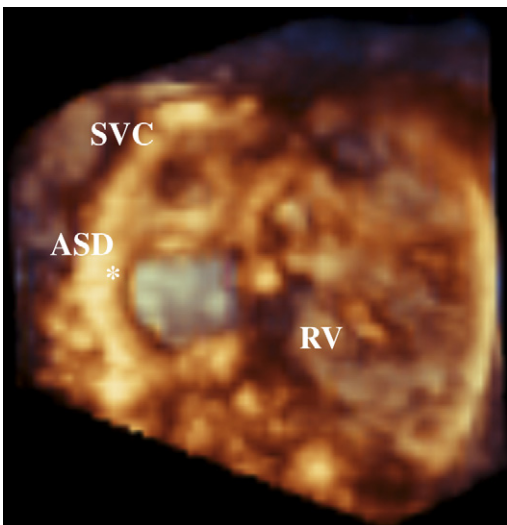


Fig. 2. E-face right atrial view of a secundum atrial septal defect (*). *Abbreviations:* ASD, atrial septal defect; SVC, superior vena cava; RV, right ventricle.

the retro-aortic region. Not only can 3D echocardiographic imaging be helpful in the preselection of patients for device closure, but it also can analyze the positioning of the device once it has been placed (Fig. 3). Multiple fenestrations in the septum primum of secundum atrial septal defects can be problematic for device closure. Determination of multiple fenestrations may be very difficult to determine either by 2D echocardiographic imaging or angiography. The recent improvements in three-dimensional echocardiographic imaging provide for higher resolution imaging, while reducing imaging artifacts. 3D imaging can provide for very good imaging of the multiple fenestrated secundum atrial septal defect (Fig. 4).

Ventricular septal defects

Irrefutably, for more than 25 years, 2D echocardiography has provided for excellent delineation and diagnostic information as to the relative size, position, and hemodynamics of ventricular septal defects. 3D echocardiography, however, can provide important additional imaging information concerning certain difficult-to-manage muscular ventricular defects [8–10] or a-v septal defects [11,12]. With recent development of catheterization device closure of membranous ventricular septal defects, the extent of rim tissue separating a membranous ventricular septal defect from the aorta can be depicted readily from left ventricular en face views (Fig. 5). Additionally,

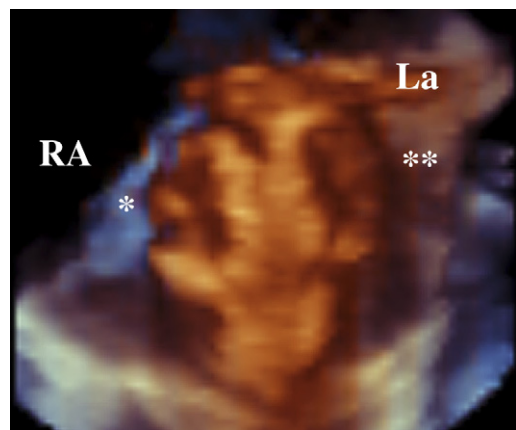


Fig. 3. A 3D echocardiographic image demonstrating the relationship of the right (*) and left (***) atrial discs of an Amplatzer device (AGA Medical, Plymouth, MN) used to close a secundum atrial septal defect. *Abbreviations:* RA, right atrium; LA, left atrium).

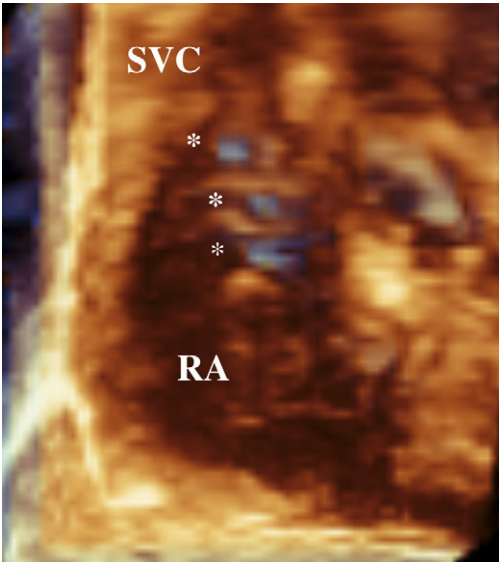


Fig. 4. With improved resolution, multiple fenestrations (*multiple asterisks*) in a secundum atrial septal defect can be seen from this 3D echocardiographic en face view. *Abbreviation:* SVC, superior vena cava.

3D imaging can see the volumetric relationship of the wind socket of tissue covering a membranous defect to the aortic valve. Again, this knowledge would be of paramount importance in considering a patient for device closure.

Certain muscular defects can be very difficult for the surgeon to visualize when operating by means of the right atrium. Such ventricular septal

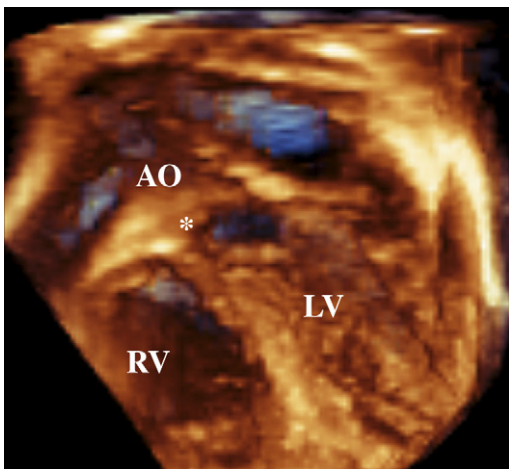


Fig. 5. Left ventricular en face view demonstrating the relationship of a membranous ventricular septal defect (*) to the aortic valve. *Abbreviation:* Ao, aorta.

defects include apical and anterior muscular defects. Moreover, important regions of the right ventricular septal surface can be very difficult to see because of large hypertrophied right ventricular muscle bundles, or tricuspid valvar attachments to the septal surface. Previously, the surgeon would perform a left ventriculotomy to gain inspection of the corresponding left ventricular septal surface. This would be advantageous, because there are no trabeculations on the left ventricle, and normally the mitral valve does not have attachments to the left ventricular septal surface. A surgical left ventriculotomy, however, can result in regional wall dysfunction, or create ultimate scar tissue that can become a nidus for future severe dysrhythmias. 3D echocardiography serves as an electronic knife, allowing left ventricular en face views to delineate the size and position of muscular defects. Once the defect (s) can be determined, multiple imaging planes and rotation of the ventricular septum can be undertaken. 3D color-flow imaging can improve the depiction of the number, size, and position of multiple septal defects in relation to the septum and to each other. Several imaging formats of the anatomic gray scale have been developed. One such format shows the heart structures in a transparent format, which heightens color-flow jets and shows the relation to the heart by overlaying the color-flow jets over the transparent shadow of the heart (Fig. 6).

Complex cono-truncal malformations

The anatomic relationship of the ventricular septal defect is of paramount importance to the surgical undertaking of complex congenital heart defects. The extent and relationship of the ventricular septal defect to the great arteries are of crucial importance for the surgical planning of double outlet right ventricle, or transposition of the great arteries. The prospective pathway from the left ventricular connection to the aorta must be constructed to ensure closure of the ventricular communication, avoidance of subsequent development of subaortic or subpulmonic outlet obstruction, or damage to the atrioventricular valves. Such a pathway may be difficult to conceptualize or even visualize in the flaccid heart at the time of cardio-pulmonary bypass. 3D echocardiographic imaging can provide a more exacting representation of the ventricular septal defect to these anatomic structures (Fig. 7).

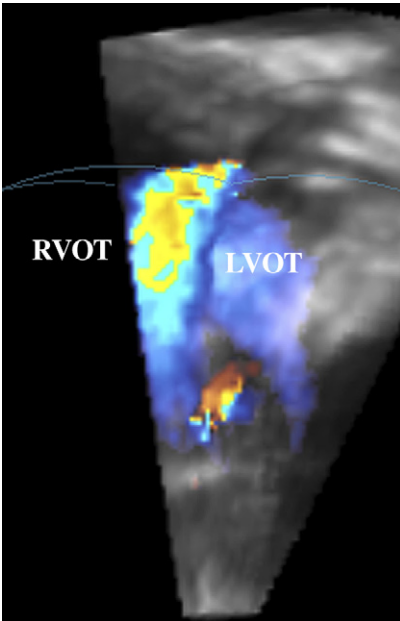


Fig. 6. The heart is displayed in a transparent gray scale format allowing improved imaging of the overlying color flow jets of an anterior muscular ventricular septal defect (*orange jet*) in relationship to the left and right ventricular outflow tracts. *Abbreviations:* LVOT, left ventricular outflow tract; RVOT, right ventricular outflow tract.

Presently, the surgeon and echocardiographers will analyze and render 3D images before surgery to outline the surgical undertaking. At the authors' center, the surgeons have become very knowledgeable of 3D echocardiography and can render the images independently.

Atrioventricular and semilunar valves

Another very important application of three-dimensional echocardiography has been to the understanding of both semilunar [13] and atrioventricular valve pathology [14,15]. 2D imaging can depict only the edges of the leaflets in a singular plane. 3D echocardiography demonstrates the surface area of the leaflets, and hence zones of coaptation (Fig. 8). Equally important for atrioventricular valves, 3D echocardiography details the dynamic and coordinated movements of the leaflets and tensor apparatus. Although on cardiopulmonary bypass, the surgeons can obtain a 3D perspective of the valve leaflets; they cannot obtain an image of the dynamic coaptation of the leaflet structures.

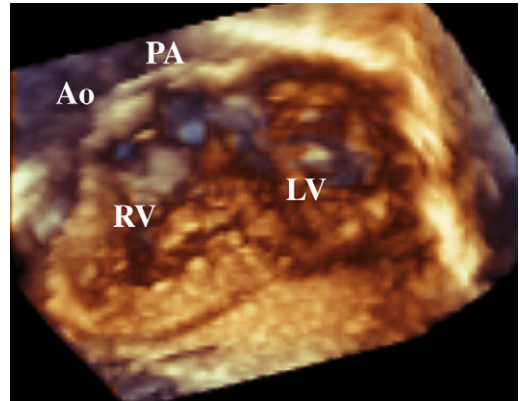


Fig. 7. Double outlet right ventricle demonstrating the relationship of the aorta and pulmonary artery arising from the right ventricle. *Abbreviation:* PA, pulmonary artery.

3D imaging provides direct en face views of the aortic valve from above the surgeon's view, but also from below the aortic valve. With 3D imaging, direct assessment of the most narrowed effective orifice area can be accomplished through multiple parallel cut planes [16]. This can be most important in that, to date, application of the continuity equation to determine the effective orifice area can be very difficult to obtain in young pediatric patients. With 3D echocardiographic imaging, the information is contained within a digital data set. As such, the exact plane from which the cross-sectional views are obtained can be referenced to the corresponding long axis plane. Additionally, because the entire valve surface region can be seen, the extent and locations of valvar deficiency can be seen best. Such examples include 3D echocardiographic visualization of leaflet holes or perforations, or retracted leaflets with

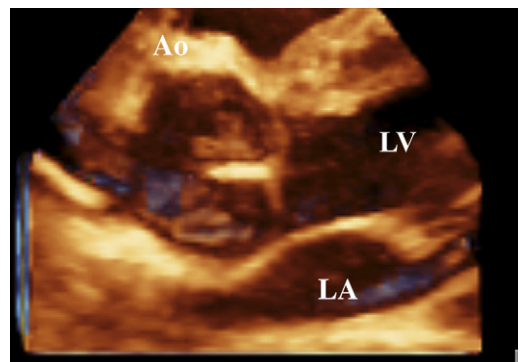


Fig. 8. Long axis view of the aortic valve. In a 3D perspective, the depth of the sinus of Valsalva can be appreciated fully.

diminished surface area, or torn leaflets (Fig. 9). Using superimposed 3D color-flow imaging, the very precise deficient regions can be confirmed. The application of 3D echocardiography is being applied on an everyday clinical practice at the authors' institution for surgical planning for aortic valve repair rather than replacement.

Another aspect of congenital heart disease that has been difficult to precisely diagnose and manage successfully has been left atrioventricular valve abnormalities in a-v septal defects. The incidence for reoperation for left atrioventricular valve stenosis or regurgitation ranges from 15% to 40%. This problem seems related in part to suboptimal imaging and hence diagnosis of the specific pathological problem. 3D imaging can display the a-v valve morphology in improved ways, not available with 2D imaging. The depth and areas of the valve components, and effective dynamic coaptation can be appreciated readily from atrial/and or ventricular en face views. The relative alignment of the common atrioventricular valve to the corresponding left and right ventricle can be discerned with improved clarity. Most importantly, 3D echocardiography can demarcate the full extent of the cleft in the anterior leaflet of the left atrioventricular valve either in patients who have atrioventricular septal defects (Fig. 10), or in the rare case of an isolated cleft. The entire extent or length of the cleft can be seen, and the effective coaptation of the three components of the left a-v valve (ie, the superior anterior, and inferior anterior components of the anterior leaflet) and the mural leaflet. Similar to analysis of aortic

valve pathology, 3D echocardiographic color-flow mapping can confirm the anatomic region of ineffective coaptation with the specific 3D color-flow map (Fig. 11).

The pathology of Ebstein's malformation of the tricuspid valve can be extremely difficult to comprehend by 2D imaging. Although the atrialized portion of the right ventricle with septal displacement of the tricuspid valve can be established by 2D imaging, the specific aspects concerning the mechanism of valvar regurgitation can be very difficult to determine. 3D imaging again can display the regions of ineffective leaflet coaptation from direct en face views (Fig. 12) [17]. Fibrous strands, restricting systolic motion and the corresponding regions of lack of coaptation, can be seen. Again, 3D echocardiographic imaging can be used to determine the leaflet surface areas. In particular, the apical view can be used to acquire the tricuspid valve in Ebstein's malformation in almost all patients. Specific serial cut planes can be analyzed in sequence from the apex to base of the right ventricle to best analyze the leaflet abnormalities. In the most severe Ebstein's malformation in newborns and infants, the valve may be displaced into the right ventricular outflow tract and oriented toward the pulmonary valve. A typical 2D apical view will not allow delineation of the valve leaflets. A sub-costal view, however, can delineate the entire atrialized portion of the right ventricle, and the tricuspid valve leaflets. Likewise, the regurgitant jet will not be visualized in a typical 2D echocardiographic apical view, because it will be oriented posterior and inferior toward the diaphragmatic surface. This tricuspid

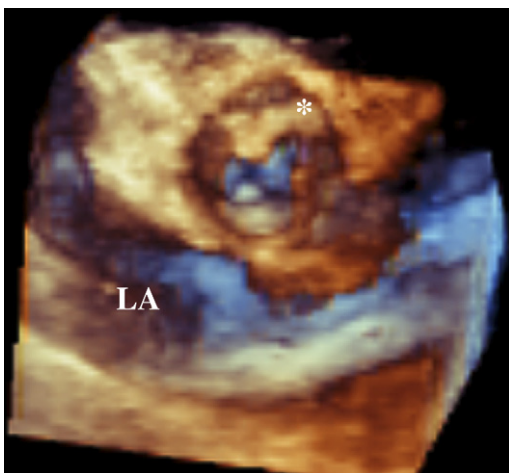


Fig. 9. Surgical en face view of a torn (*) aortic valve leaflet after a balloon dilation valvuloplasty.

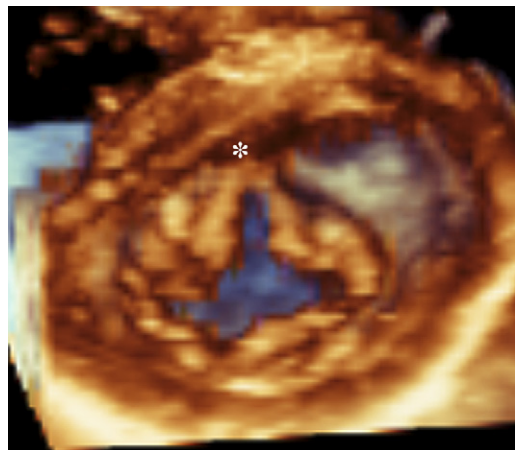


Fig. 10. 3D echocardiographic en face view of the mitral valve from the left ventricular apex to base to demonstrate a cleft (*) in the anterior leaflet.

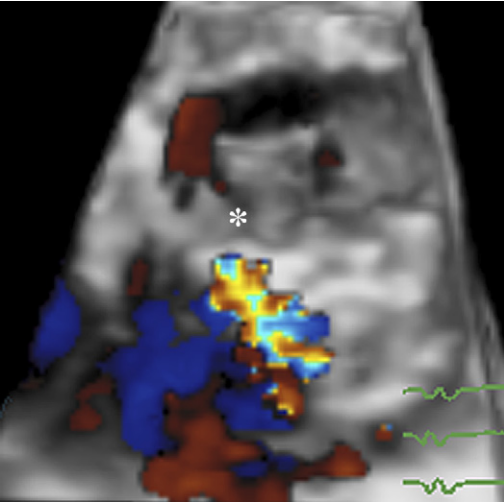


Fig. 11. 3D color flow mapping that confirms origination of the jet (*) through a cleft in the anterior mitral valve leaflet.

regurgitant jet can be appreciated best in a 3D format, especially when acquired from a subcostal plane.

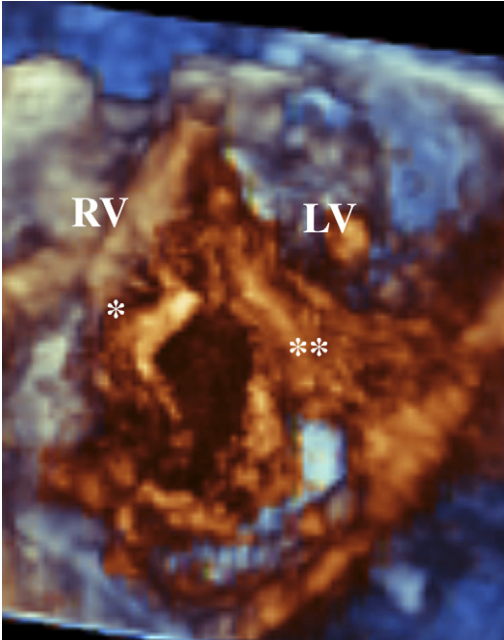


Fig. 12. En face view of the tricuspid valve in an adolescent with severe Ebstein's malformation of the tricuspid valve. Note the large region of noncoaptation of the large anterior (*) and tethered (***) septal leaflet of the tricuspid valve as best seen in this 3D display.

Subaortic stenosis

Subaortic stenosis continues to be a vexing problem, with a high incidence of reoperation. This, in part, is related to the myriad of complex anatomic subtypes. Additionally, complete delineation and understanding of the anatomy have been incomplete with standard 2D imaging. 3D echocardiography can provide an enhanced understanding of this difficult problem. Even for a more routine subaortic membrane, 3D echocardiography allows for visualization of the circumferential narrowing (Fig. 13), whereas 2D imaging depicts only the edges of obstruction. 3D imaging provides a more comprehensive understanding when the mitral valve and/or tensor apparatus is intricately involved in the subaortic obstruction. Often the surgeon will need to know the parts of the mitral valve that can be excised or removed from the subaortic region, without culminating in mitral regurgitation. In the authors' experience, 3D echocardiography has been invaluable to aid in surgical planning for complex left ventricular outflow obstruction.

Three-dimensional imaging of valvar regurgitation

To date, an important application of color flow 2D echocardiography has been the evaluation of the magnitude of valvar regurgitation. To date, the most reliable aspect has been the estimate of the size of the regurgitant vena contracta, which seems to apply best to regurgitant volume. 2D measurements of the vena contracta have relied on diameter measurements, assuming that the regurgitation orifice is circular. Experience with three-dimensional color-flow mapping has shown that the vena contracta can have a myriad of shapes that do not approach that of either a circle or ellipse. Hence, even measurement of the diameter in two orthogonal planes may be inadequate. From the color-flow volumetric digital data set, from the long axis view of the regurgitant jet, a corresponding cut plane can be placed orthogonal at the most narrowed region of the regurgitant. The cut planes then can be visualized in the sequential planes to best depict the true circumference of the vena contracta (Fig. 14).

Right and single ventricular function

Assessment of right ventricular size and function is essential for managing pediatric patients who have congenital heart disease. To date, this

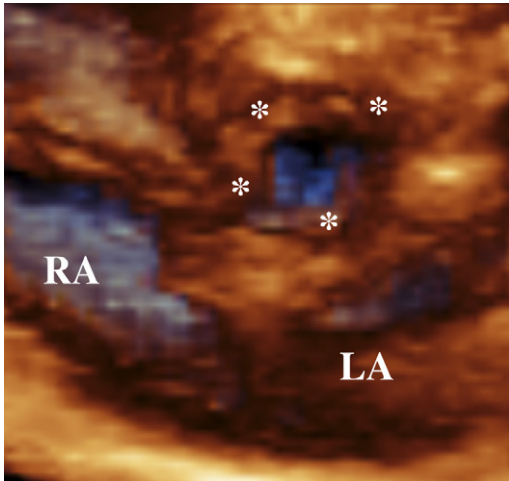


Fig. 13. 3D echocardiogram oriented from the apex of the left ventricle to the aortic outflow tract. The circumferential narrowing from a subaortic membrane (*multiple asterisks*) can be seen in a 3D echocardiographic display.

has been accomplished by MRI, especially in the adolescent or adult who has postoperative congenital heart surgery. MRI, however, is contraindicated in patients with pacemakers, often occurring in single ventricle patients. Moreover, certain adolescents or adults may suffer from claustrophobia. Young pediatric patients need to be anesthetized and ventilated for the best MRI. This can be very difficult for the significantly hemodynamically compromised patient. Moreover, endotracheal intubation and general anesthesia cannot be applied readily to the serial evaluation of such patients. An important example, to illustrate the importance of single ventricular evaluation, would be in the patients undergoing staged operations for single ventricle with complex systemic outflow tract obstruction. 3D echocardiography would be ideal in the serial evaluation of ventricular function in such patients [18–20].

In the authors' laboratory, the subcostal plane has been used for the three-dimensional echocardiographic analysis of either the single or right ventricular function in young pediatric patients. Analysis of left ventricular size and function has been obtained best from either the subcostal or apical planes. In the authors' experience, the subcostal plane has been the most reliable to acquire the full volume of either the right, left, or single ventricle, especially when dilated or distorted

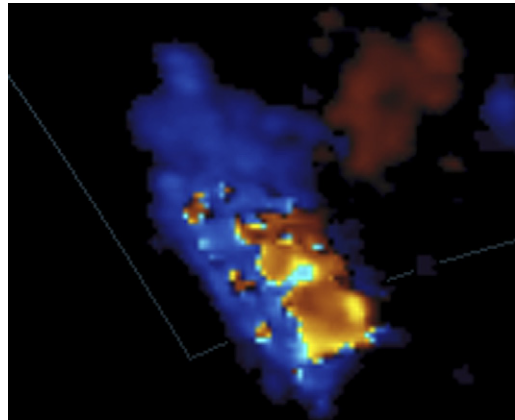


Fig. 14. 3D display of the vena contracta (*orange color*) of severe tricuspid regurgitation. Note that the shape is quite irregular.

(Fig. 15). Summation of disc methodology allows for analysis of volume, mass, and ejection fraction, again regardless of ventricular size and shape. This methodology, using a matrix array probe for the acquisition and summation of disc for volume determination, has compared well to measurements made by MRI in young pediatric patients in the authors' laboratory. To date, the authors' center has performed two separate studies comparing volumes by three-dimensional echocardiography with those obtained by MRI. The first study was done in infants with single ventricles with a mean age of 7 months. The second study was done to analyze right ventricular volumes in patients with a corresponding normal left ventricle. In the latter study, the mean age was 36 months. In both studies, the echocardiographic and MRI studies were done nearly simultaneously, under similar anesthetic and hemodynamic conditions. Because in both studies the patients were young, they were intubated and anesthetized for the MRI study. For the 3D echocardiographic acquisition, ventilation was suspended during the four-beat acquisition. In the studies comparing 3D echocardiographic right ventricular and single ventricular volumes with MRI, there was good correlation and agreement for end diastolic and end systolic volumes; however, 3D echocardiographic diastolic ventricular volumes were smaller by 7% and 10% respectively. Although these studies were not done under usual clinical conditions, they set the framework for the application of three-dimensional echocardiographic analysis of ventricular size and function in the pediatric age group. In even the youngest of

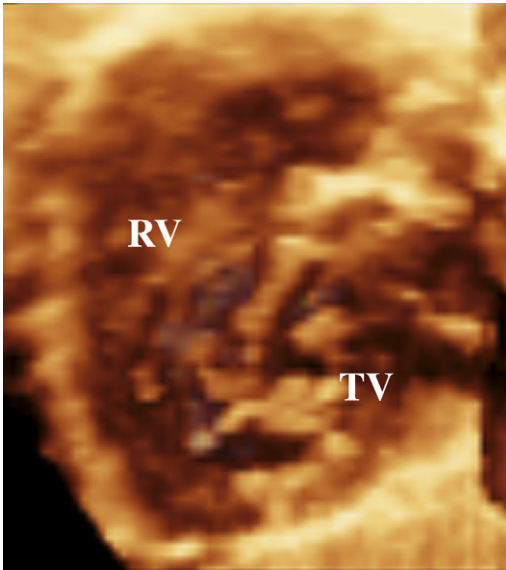


Fig. 15. 3D display of the entire right ventricle in a young pediatric patient with hypoplastic left ventricle. *Abbreviation:* TV, tricuspid valve.

infants, adequate full-volume acquisitions can be obtained with either no or light sedation. These acquisitions have minimal temporal or spatial artifact and can be used for volume determinations.

Matrix array 3D echocardiographic acquisitions and semiautomated border detection allow for rapid analysis of left ventricular volumes in pediatric and adult patients. This technology allows for evaluation of both global and regional ventricular function. Further, it can be used for left ventricular dyssynchrony analysis. Newer software programs also allow for semiautomated border detection of the right ventricle. The right ventricle can be subdivided into inflow, body and outflow sections, thus allowing for detection of regional function.

Summary

Quantum leaps in technological advances have resulted in quantum leaps in the application of 3D echocardiography in congenital heart disease. Although previously considered to be only in the realm of isolated research, three-dimensional echocardiography is now in the realm of everyday clinical application. With greater learning, continued technological advances, application, and universal acceptance, three-dimensional imaging will

become the mainstay of echocardiographic imaging for congenital heart disease.

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